

On parameter estimation of stochastic delay differential equations with guaranteed accuracy by noisy observations*

Uwe Küchler

Vjatcheslav A. Vasil'iev

Institute of Mathematics
Humboldt University Berlin
Unter den Linden 6, D-10099
Berlin, Germany

Department of Applied Mathematics
and Cybernetics
Tomsk State University
Lenina 36, 634050 Tomsk, Russia

Abstract

Let $(X(t), t \geq -1)$ and $(Y(t), t \geq 0)$ be stochastic processes satisfying

$$dX(t) = aX(t)dt + bX(t-1)dt + dW(t)$$

and

$$dY(t) = X(t)dt + dV(t),$$

respectively. Here $(W(t), t \geq 0)$ and $(V(t), t \geq 0)$ are independent standard Wiener processes and $\vartheta = (a, b)'$ is assumed to be an unknown parameter from some subset Θ of \mathcal{R}^2 .

The aim here is to estimate the parameter ϑ based on continuous observation of $(Y(t), t \geq 0)$.

Sequential estimation plans for ϑ with preassigned mean square accuracy ε are constructed using the so-called correlation method. The limit behaviour of the duration of the estimation procedure is studied if ε tends to zero.

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1 Introduction

Assume $(\Omega, \mathcal{F}, (\mathcal{F}(t), t \geq 0), P)$ is a given filtered probability space and the processes $W = (W(t), t \geq 0)$ and $V = (V(t), t \geq 0)$ are real-valued standard Wiener processes on $(\Omega, \mathcal{F}, (\mathcal{F}(t), t \geq 0), P)$, adopted to $(\mathcal{F}(t))$ and mutually independent. Furtherer assume that $X_0 = (X_0(t), t \in [-1, 0])$ and Y_0 are a real-valued cadlag process and a real-valued random variable, respectively, on $(\Omega, \mathcal{F}, (\mathcal{F}(t), t \geq 0), P)$ with

$$E \int_{-1}^0 X_0^2(s) ds < \infty \quad \text{and} \quad EY_0^2 < \infty.$$

Assume that Y_0 and $X_0(s)$ are \mathcal{F}_0 -measurable for every s from $[-1, 0]$ and that the quantities W , V , X_0 and Y_0 are mutually independent.

Consider a two-dimensional random process $(X, Y) = (X(t), Y(t))$ described by the system of stochastic differential equations

$$dX(t) = aX(t)dt + bX(t-1)dt + dW(t), \quad t \geq 0, \quad (1)$$

$$dY(t) = X(t)dt + dV(t), \quad t \geq 0 \quad (2)$$

with the initial conditions $X(t) = X_0(t)$, $t \in [-1, 0]$ and $Y(0) = Y_0$. The process X is supposed to be hidden, i.e. unobservable, and the process Y is observed. Such models are used in applied problems connected with control, filtering and prediction of stochastic processes (see, for example, [1], [7]).

The parameter $\vartheta = (a, b)'$ with $a, b \in \mathcal{R}^1$ is assumed to be unknown and shall be estimated by using the observation of Y .

Equations (1) and (2) together with the initial values $X_0(\cdot)$ and Y_0 respectively have uniquely solutions $X(\cdot)$ and $Y(\cdot)$, for details see [9].

Equation (1) is a very special case of stochastic differential equations with time delay, see [3] and [10] for examples.

To estimate the true parameter ϑ with a preassigned least square accuracy ε we shall construct sequential plans $(T_\varepsilon, \vartheta_\varepsilon^*)$. Moreover, we will derive asymptotic properties of the duration T_ε of these plans for ε tending to zero.

The method used below is to transform the equations (1) and (2) to a single equation (see (4) below) for the process $(Y(t), t \geq 0)$, which can be treated by modifying a method from [11]. The construction of $(T_\varepsilon, \vartheta_\varepsilon^*)$ may depend on the asymptotic behaviour of the correlation function of the solution of (1) and their estimators if the observation time is increasing unboundedly. These asymptotic properties vary if ϑ runs through \mathcal{R}^2 . Our construction does not seem to work for all ϑ in \mathcal{R}^2 . Therefore we restrict the discussion to two sets Θ_1 and Θ_2 of parameters, for which we are able to derive the desired properties.

The organization of this paper is as follows. In Section 2 we summarize some known properties of equation (1) needed in the sequel. The two mentioned cases for Θ , namely Θ_1 and Θ_2 , are presented and equations (1), (2) are transformed into a new one for the one-dimensional observed process $(Y(t), t \geq 0)$ (see (4)). In Section 3 the two sequential plans are constructed and the assertions are formulated. Section 4 contains the proofs.

2 Preliminaries

First we summarize some known facts about equation (1). For details the reader is refer to [2]. Together with the described initial condition equation (1) has a uniquely determined solution X which can be represented as follows for $t \geq 0$:

$$X(t) = x_0(t)X_0(t) + b \int_{-1}^0 x_0(t-s-1)X_0(s)ds + \int_0^t x_0(t-s)dW(s), \quad t \geq 0.$$

Here $x_0 = (x_0(t), t \geq -1)$ denotes the so-called fundamental solution of the deterministic equation

$$x_0(t) = 1 + \int_0^t (\vartheta_0 x_0(s) + \vartheta_1 x_0(s-1))ds, \quad t \geq 0,$$

corresponding to (1) with $x_0(t) = 0, \quad t \in [-1, 0), \quad x_0(0) = 1.$

The solution X has the property $E \int_0^T X^2(s)ds < \infty$ for every $T > 0.$

The limit behavior of $x_0(t)$ and therefore also of $X(t)$ for t tending to infinity is closely connected with the properties of the set $\Lambda = \{\lambda \in \mathcal{C} | \lambda = a + be^{-\lambda}\}$ (\mathcal{C} denotes the set of complex numbers). The set Λ is countable infinite (if $b \neq 0$), and for every real c the set $\Lambda_c = \Lambda \cap \{\lambda \in \mathcal{C} | \operatorname{Re}\lambda \geq c\}$ is finite. In particular, $v_0 := v_0(\vartheta) = \sup\{\operatorname{Re}\lambda | \lambda \in \Lambda\} < \infty, \quad \sup\{\emptyset\} = -\infty.$ Define $v_1(\vartheta) =: \sup\{\operatorname{Re}\lambda | \lambda \in \Lambda, \operatorname{Re}\lambda < v_0(\vartheta)\}.$

The values $v_0(\vartheta)$ and $v_1(\vartheta)$ determine the asymptotic behaviour of $x_0(t)$ as $t \rightarrow \infty.$ Indeed, it exist a real γ less than v_1 and a polynomial $\Psi_1(\cdot)$ of degree less than or equal one, being specified in the proof of Theorem 3.1 (Section 4 below), such that

$$x_0(t) = \frac{1}{v_0 - a + 1} e^{v_0 t} + \Psi_1(t) e^{v_1 t} + o(e^{\gamma t}) \quad \text{as } t \rightarrow \infty.$$

Now we define a subset Θ of \mathcal{R}^2 consisting of two disjoint sets Θ_1 and $\Theta_2.$ First fix a positive real $\bar{\vartheta}.$

Case I. The set Θ_1 : Assume L is an arbitrary line in the plane \mathcal{R}^2 :

$$L = L(\alpha, \beta, \omega) = \{\tilde{\vartheta} = (\tilde{a}, \tilde{b})' | \alpha \tilde{a} + \beta \tilde{b} = \omega\}.$$

Let $\tilde{\Theta}$ be the segment $L \cap \{\|\tilde{\vartheta}\| \leq \bar{\vartheta}\}$ (it is no restriction of generality to assume that $\tilde{\Theta}$ is non-void), $\|\cdot\|$ denotes the Euclidean norm.

Now we introduce the set S by

$$S = \{\vartheta = (a, b)' \in \tilde{\Theta} | v_0(\vartheta) \cdot v_1(\vartheta) = 0 \text{ or } (a > 1, b = -e^{(a-1)})\}$$

and put $\Theta_1 = \tilde{\Theta} \setminus S.$

Case II. The set Θ_2 : Define

$$\Theta_2 = \{\vartheta \in \mathcal{R}^2 | \|\vartheta\| \leq \bar{\vartheta}, v_0(\vartheta) < 0 \text{ or } (v_0(\vartheta) > 0 \text{ and } v_0(\vartheta) \notin \Lambda)\}.$$

The definition of the two sets Θ_1 and Θ_2 looks quite complicate. But they are distinguished by the property, that for all of their elements ϑ the correlation function of $X(\cdot)$ has an asymptotic property which is analogous to (16), (17), (41) and (42) below.

In particular, in Case I the partly observable two-dimensional process $(X(t), Y(t))$ will be reduced to a scalar observable linear process with a scalar function in the dynamic part. The asymptotic properties of this function are given in (16) and (17).

In Case II the information matrix $G_X(T)$ given by

$$G_X(T) = \begin{pmatrix} \int_0^T X^2(t)dt & \int_0^T X(t)X(t-1)dt \\ 0 & 0 \\ \int_0^T X(t)X(t-1)dt & \int_0^T X^2(t-1)dt \\ 0 & 0 \end{pmatrix}$$

has the asymptotic property (see [2] and [5, 6] for details)

$$\lim_{T \rightarrow \infty} |\varphi^{-1}(T)G_X(T) - I_\infty(T)| = 0 \quad P_\vartheta - \text{a.s.}, \quad (3)$$

where

$$\varphi(T) = \begin{cases} T, & \text{if } v_0 < 0, \\ e^{2v_0 T}, & \text{if } v_0 > 0, v_0 \notin \Lambda. \end{cases}$$

If $v_0 < 0$ then (1) admits a stationary solution and $I_\infty(T) \equiv I_\infty$ is a constant positive definite 2×2 -matrix (in the sequel we shall call this case the stationary case); if $v_0 > 0$ and $v_0(\vartheta) \notin \Lambda$, then $I_\infty(T)$ is nondeterministic periodic with the period $\Delta = \pi/Im\lambda_0$, where λ_0 is the unique element of Λ with $Re\lambda_0 = v_0(\vartheta)$ and $Im\lambda_0 > 0$ (below we refer to this case as the periodic case).

The problem of sequential estimation of ϑ by observation without noise under the condition (3) was considered in [5, 6].

To construct a sequential plan for estimating ϑ based on the observation of $Y(\cdot)$ we shall apply the idea of a method first used in [11]. To this end we shall reduce equations (1) and (2) to a single one for Y .

Using the integrated form of equations (1) and (2) we can get the following equation for the observed process Y

$$\begin{aligned} dY(t) &= [aY(t) + bY(t-1)]dt + [X(0) - aY(0) - bY(0) + b \int_{-1}^0 X_0(s)ds \\ &\quad - aV(t) - bV(t-1) + W(t)]dt + dV(t), \quad t \geq 1. \end{aligned}$$

Thus we have reduced the system (1), (2) to the form

$$dY(t) = \vartheta' A(t)dt + \xi(t)dt + dV(t), \quad (4)$$

with

$$A(t) = (Y(t), Y(t-1))',$$

$$\xi(t) = X(0) - aY(0) - bY(0) + b \int_{-1}^0 X_0(s)ds - aV(t) - bV(t-1) + W(t),$$

where the observable process $(A(t), t \geq 0)$ and the noise $\xi = (\xi(t), t \geq 0)$ are some $(\mathcal{F}(t))$ -adapted processes. The problem of estimation of ϑ with guaranteed accuracy in models of the type (4) was considered in [11].

The functions $A(t)$ and $\xi(t)$ are $\mathcal{F}(t)$ -measurable for every $t \geq 1$ and a short calculating shows that all conditions of type (3) in [11], consisting of

$$E \int_1^T (||A(t)||_1 + |\xi(t)|)dt < \infty \quad \text{for all } T > 1,$$

$$E[\tilde{\Delta}\xi(t)|\mathcal{F}(t-2)] = 0, \quad E[(\tilde{\Delta}\xi(t))^2|\mathcal{F}(t-2)] \leq \bar{s}^2, \quad t \geq 2, \quad (5)$$

$$\bar{s}^2 = 1 + \bar{\vartheta}^2, \quad ||A||_1 = \sum_i |A_i|$$

hold in our case. Here $\tilde{\Delta}$ denotes the difference operator defined by $\tilde{\Delta}f(t) = f(t) - f(t-1)$.

Using this operator and the definition of ξ we obtain the following equation:

$$\begin{aligned} d\tilde{\Delta}Y(t) &= a\tilde{\Delta}Y(t)dt + b\tilde{\Delta}Y(t-1)dt + \tilde{\Delta}\xi(t)dt \\ &+ dV(t) - dV(t-1), \quad t \geq 2 \end{aligned} \quad (6)$$

with initial condition $\tilde{\Delta}Y(1) = Y(1) - Y_0$.

We have reduced the system (1)–(2) to a single differential equation (6) for the observed process $(\tilde{\Delta}Y(t), t \geq 2)$ depending on the unknown parameters a and b . The term $\tilde{\Delta}\xi(t)$ also contains a and b , but its variance is controllable in certain sense (see formula (5)).

Nevertheless, a and b can not be estimated from (6) by the maximum likelihood or sequential maximum likelihood method given in [2] or [5, 6] respectively, because of the appearance of the terms $\tilde{\Delta}\xi(t)dt$ and $dV(t-1)$. Below we shall propose another way following an idea taken from [11].

3 Results

3.1 Sequential estimation procedure I

Consider the estimation problem of a linear combination $\theta = l'\vartheta$, $\vartheta \in \Theta_1$, where $l = (l_1, l_2)'$ is some known constant vector such that $\sigma = l_1\beta - l_2\alpha \neq 0$. Here α and β are the constants from the definition of the line L , defined in Section 2.

We introduce processes Z_1 , Z_2 and Ψ by the formulae

$$dZ_1(t) = \sigma^{-1}(\beta d\tilde{\Delta}Y(t) - c\tilde{\Delta}Y(t-1)dt), \quad t \geq 2,$$

$$dZ_2(t) = -\sigma^{-1}(\alpha d\tilde{\Delta}Y(t) - c\tilde{\Delta}Y(t)dt), \quad t \geq 2,$$

$$\Psi(t) = \begin{cases} \sigma^{-1}(\beta\tilde{\Delta}Y(t) - \alpha\tilde{\Delta}Y(t-1)), & t \geq 2, \\ 0, & t < 2. \end{cases}$$

From (6) and from the definition of Θ_1 we get for $t \geq 2$ the system of equations

$$dZ_1(t) = a\Psi(t)dt + \beta\sigma^{-1}(\tilde{\Delta}\xi(t)dt + d\tilde{\Delta}V(t)),$$

$$dZ_2(t) = b\Psi(t)dt - \alpha\sigma^{-1}(\tilde{\Delta}\xi(t)dt + d\tilde{\Delta}V(t)), \quad t \geq 2.$$

Now we obtain an equation for the observable scalar process $Z(t) = l_1Z_1(t) + l_2Z_2(t)$:

$$dZ(t) = \theta\Psi(t)dt + \tilde{\Delta}\xi(t)dt + d\tilde{\Delta}V(t), \quad t \geq 2 \quad (7)$$

with unknown parameter θ . For $t < 2$ we set $Z(t) = 0$.

In a similar way as in [11] we can define a sequential plan for the estimation of θ from $\{l^\vartheta | \vartheta \in \Theta_1\}$ with mean square deviation less than a given positive ε . The sequential estimation plans for θ have been constructed in [11] based on so-called correlation estimators which are generalized least squares estimators. Here we use an analogous definition as follows:

$$\theta^*(T) = G^{-1}(T, u)\Phi(T, u), \quad (8)$$

$$G(T, u) = \int_0^T \Psi(t-u)\Psi(t)dt, \quad \Phi(T, u) = \int_0^T \Psi(t-u)dZ(t), \quad T > 2, \quad u \geq 2.$$

Under the condition $u \geq 2$ the function $\Psi(t-u)$ in equation (7) is uncorrelated with respect to the noise $\tilde{\Delta}\xi(t)$ as well as to $\tilde{\Delta}V(t)$.

From (7) and (8) we find the deviation of the estimator $\theta^*(T)$:

$$\theta^*(T) - \theta = G^{-1}(T, u)\zeta(T, u), \quad (9)$$

where

$$\zeta(T, u) = \zeta(T, u, 1) + \zeta(T, u, 2) + \zeta(T, u, 3)$$

with

$$\zeta(T, u, 1) = \int_0^T \Psi(t-u)\tilde{\Delta}\xi(t)dt, \quad \zeta(T, u, 2) = \int_0^T \Psi(t-u)dV(t)$$

and

$$\zeta(T, u, 3) = - \int_0^T \Psi(t-u)dV(t-1).$$

As we will see from the proof of Theorem 3.1 (Section 4 below), there exist increasing functions $\varphi(T)$ corresponding to the various regions for the parameter ϑ from Θ_1 and Θ_2 such that for every $u \geq 2$ the function $g(T, u) = \varphi^{-1}(T)G(T, u)$ has one of the following properties:

either

a) the limit $g(u) = \lim_{T \rightarrow \infty} g(T, u)$ exists P -a.s. and is deterministic with $meas\{u \in (2, 3] : g(u) = 0\} = 0$ ($meas\{B\}$ is the Lebesgue measure of the set B) and $g(0) > 0$;
or

b) the limit $g(u) = \lim_{T \rightarrow \infty} g(T, u)$ exists P -a.s. and is non-deterministic, it holds $P\{g(u) = 0\} = 0, u \geq 0$;

or

c) there exists a random periodic function $\tilde{g}(T, u), T > 0$, periodic with respect to T and with period $\Delta > 1$, such that

$$P\{\lim_{T \rightarrow \infty} |g(T, u) - \tilde{g}(T, u)| = 0\} = 1, u \geq 0$$

holds (see the formulae (16) and (17) below).

It will be clear from the proofs in Section 4 below that in the periodic case c) the function $\tilde{g}(T, u)$ has for every $u \geq 0$ two roots as a maximum on every interval of the unknown period length Δ . Then the function $\varphi(T)G^{-1}(T, u)$ and consequently the deviation $\theta^*(T) - \theta$ may be unbounded.

Remark 1 *Properties a) and c) do not exclude that the limit functions $g(u)$ and $\tilde{g}(T, u)$ may be equal to zero for some u and (T, u) respectively. A similar picture arises in Case II (see proof of Theorem 3.2 below). Due to this fact the estimation procedure, used in [11] can not be applied in the cases considered above.*

To exclude this effect we introduce a discretization of the time of observations. Note that in the case of observations without noise we also need a similar discretization (by using Δ) for the investigation of asymptotic properties of maximum likelihood estimators [2]. The procedure which we construct here is non-asymptotic and we can not use the unknown value Δ in the construction of estimators.

For some $h \in (0, 1/3]$ put

$$r_n = \arg \max_{k=1,3} |G(nh - kh, 2 + 3h)|.$$

Such a choice of the value of h implies that for every $n \geq 1$ and $T > 0$ there are one or more values $nh - kh, k = \bar{1}, \bar{3}$, with $\tilde{g}(nh - kh, T) \neq 0$. In such a way (see the proof of Theorem 3.1) the sequence $\{g(nh - r_n h, 2 + 3h), n \geq 1\}$ is non-degenerate in the case c) for any $h \in (0, 1/3]$ asymptotically as $n \rightarrow \infty$.

To construct the estimators with preassigned accuracy we first change first the value nh in the argument of G (see the definition of r_n just given) to stopping times. As we will see later (inequalities (11)) this substitution gives us the possibility to control the second moments of the noise ζ .

Let $(c_n, n \geq 1)$ be some unboundedly increasing sequence of positive numbers. We shall define the stopping times $(\tau_\varepsilon(n), n \geq 1)$ from the discrete sequence $\{kh, k \geq 1\}$ with an arbitrary but fixed step size h by formula

$$\tau_\varepsilon(n) = h \inf\{k \geq 1 : \int_0^{kh} \Psi^2(t - 2 - 3h) dt \geq \varepsilon^{-1} c_n\}, n \geq 1. \quad (10)$$

Using formulae (16) and (17) below it is easy to see that $P(\tau_\varepsilon(n) < \infty) = 1$ for any $\varepsilon > 0$ and every $n \geq 1$.

For $k = \overline{1, 3}$, $n \geq 1$ we put

$$G_\varepsilon(n, k) = G(\tau_\varepsilon(n) - kh, 2 + 3h), \quad \Phi_\varepsilon(n, k) = \Phi_\varepsilon(\tau_\varepsilon(n) - kh, 2 + 3h),$$

$$\zeta_\varepsilon(n, k) = \zeta(\tau_\varepsilon(n) - kh, 2 + 3h);$$

$$k_n = \arg \max_{k=\overline{1,3}} \{|G_\varepsilon(n, k)|\}, \quad n \geq 1.$$

Now we introduce the sequence of estimators

$$\theta_\varepsilon(n) = G_\varepsilon^{-1}(n)\Phi_\varepsilon(n)$$

with

$$G_\varepsilon(n) = G_\varepsilon(n, k_n), \quad \Phi_\varepsilon(n) = \Phi_\varepsilon(n, k_n), \quad n \geq 1.$$

They have the deviation

$$\theta_\varepsilon(n) - \theta = G_\varepsilon^{-1}(n)\zeta_\varepsilon(n), \quad \zeta_\varepsilon(n) = \zeta_\varepsilon(n, k_n), \quad n \geq 1.$$

Fix an h_0 from $(0, 1/3)$ and choose an arbitrary random variable h being $\mathcal{F}(0)$ -measurable and having a continuous distribution concentrated on the interval $[h_0, 1/3]$. We need such randomization of the discretization step h in the case a) for the almost surely non-degeneration of the limit $g(2 + 3h) = \lim_{n \rightarrow \infty} \varphi^{-1}(\tau_\varepsilon(n) - k_n h)G_\varepsilon(n, k_n)$.

We will show that the second moments of the noise ζ calculated at times $\tau_\varepsilon(n) - k_n h$, $n \geq 1$ have known upper bounds. Note that the processes $(\zeta(T, 2 + 3h, i), \mathcal{F}(T))$, $i = \overline{1, 3}$ are square integrable martingales and the times $\tau_\varepsilon(n) - kh$, $n \geq 1$, $k = \overline{1, 3}$, are Markovian with respect to the system $(\mathcal{F}(T - 2))$. From the theory of martingales (see e.g. [8]) and from the definition of $\tau_\varepsilon(n)$ we obtain for all $\vartheta \in \mathcal{R}^2$, $k = \overline{1, 3}$ and $n \geq 1$ the inequalities

$$E_\vartheta \zeta^2(\tau_\varepsilon(n) - kh, 2 + 3h, 1) \leq \bar{s}^2 E_\vartheta \int_0^{\tau_\varepsilon(n) - kh} \Psi^2(t - 2 - 3h) dt < \bar{s}^2 \varepsilon^{-1} c_n,$$

$$E_\vartheta \zeta^2(\tau_\varepsilon(n) - kh, 2 + 3h, i) \leq \varepsilon^{-1} c_n, \quad i = 2, 3.$$

Thus for all $\varepsilon > 0$ and $n \geq 1$ the sequence $(\zeta_\varepsilon(n), n \geq 1)$ satisfies the inequalities

$$\begin{aligned} E_\vartheta \zeta_\varepsilon^2(n) &\leq \sum_{k=1}^3 E_\vartheta \zeta^2(\tau_\varepsilon(n) - kh, 2 + 3h) \\ &\leq 3 \sum_{k=1}^3 \sum_{i=1}^3 E_\vartheta \zeta^2(\tau_\varepsilon(n) - kh, 2 + 3h, i) \leq 9(2 + \bar{s}^2) \varepsilon^{-1} c_n. \end{aligned} \quad (11)$$

The asymptotic properties of the sequence $(G_\varepsilon(n), n \geq 1)$ and the inequalities (11) imply that the estimation of the parameter θ should be performed at the times $\tau_\varepsilon(n) - k_n h$, $n \geq 1$. Note that the estimators $\theta_\varepsilon(n)$ are strongly consistent (see

Theorem 3.1).

We want obtain estimators with fixed mean square deviation. Therefore, taking into account the representation for the deviation of estimators $\theta_\varepsilon(n)$, one has to control the behaviour of the sequence of random variables $G_\varepsilon(n)$, $n \geq 1$. This can be achieved by observations up to the time $\tau_\varepsilon(n) - k_n h$ with a specially chosen number n .

Let $(\kappa_n, n \geq 1)$ be some unboundedly increasing sequence of positive numbers. Introduce the stopping time

$$\nu_\varepsilon = \inf\{n \geq 1 : |G_\varepsilon(n)| \geq \rho^{1/2} \varepsilon^{-1} \kappa_n\},$$

where

$$\rho = 9(2 + \bar{s}^2) \sum_{n \geq 1} c_n / \kappa_n^2.$$

We define the sequential plan $(T(\varepsilon), \theta_\varepsilon^*)$ for the estimation of θ as

$$T(\varepsilon) = \tau_\varepsilon(\nu_\varepsilon), \quad \theta_\varepsilon^* = \theta_\varepsilon(\nu_\varepsilon) = G_\varepsilon^{-1}(\nu_\varepsilon) \Phi_\varepsilon(\nu_\varepsilon). \quad (12)$$

It should be pointed out that the estimator (12) coincides with the sequential estimator which is obtained from general least squares criteria [11].

The following theorem presents the conditions under which $T(\varepsilon)$ and θ_ε^* are well-defined and have the desired property of preassigned mean square accuracy.

First we divide the parameter set Θ_1 into nine subsets, according to the definitions of Section I.

Define the functions $u(a)$, $a < 1$, and $w(a)$, $a \in \mathcal{R}^1$, as in [2]: consider a parametric curve $(a(\xi), b(\xi))$, $\xi > 0$, $\xi \neq \pi, 2\pi, \dots$, in \mathcal{R}^2 by

$$a(\xi) = \xi \cot \xi, \quad b(\xi) = -\xi / \sin \xi,$$

then functions $b = u(a)$ and $b = w(a)$ are defined to be the branches of this curve corresponding to $\xi \in (0, \pi)$ and $\xi \in (\pi, 2\pi)$ respectively. Put also $v(a) = -e^{a-1}$, $a \in \mathcal{R}^1$, and introduce the indices

$$i = \begin{cases} 0, & \text{if } \alpha \neq \beta e^{v_0}, \\ 1, & \text{if } \alpha = \beta e^{v_0}, \end{cases}$$

$$j = \begin{cases} 1, & \text{if } a < 1, u(a) < b < -a, \\ 2, & \text{if } -a < b < w(a), \\ 3, & \text{if } a > 1, v(a) < b < -a, \\ 4, & \text{if } a > 1, b = v(a), \\ 5, & \text{if } b > w(a), \\ 6, & \text{if } a < 1, b < u(a) \text{ or } a \geq 1, b < v(a), \\ 7, & \text{if } a < 1, b = -a, a \neq 0, \\ 8, & \text{if } a > 1, b = -a, \\ 9, & \text{if } b = w(a). \end{cases}$$

Note that the sets corresponding to different values of j are disjoint and the union of all the cases corresponding to $j = \overline{1, 9}$ is the whole plane \mathcal{R}^2 except for some one-dimensional smooth curve. We know that $v_0 < 0$ if $j = 1$; $v_0 = 0$ if $j = 7$ and $v_0 > 0$ in all other cases. Moreover we have $v_1 < 0$ if $j = 1, 2, 7$; $v_1 = 0$ if $j = 8, 9$ and $v_1 > 0$ if $j = 3, 5$ [2].

Introduce the sets

$$I_1 = \{(0, 1), (1, 1), (1, 2), (1, 7)\},$$

$$I_2 = \{(0, 2), (0, 3), (0, 5), (0, 8), (0, 9), (1, 4)\},$$

$$I_3 = \{(1, 3)\}, \quad I_4 = \{(0, 4)\}, \quad I_5 = \{(0, 6), (1, 5), (1, 6)\},$$

$$I_6 = I_2 \cup I_5 \setminus \{(1, 5)\}, \quad I_7 = I_3 \cup \{(1, 5)\}.$$

Theorem 3.1 *Assume that the sequences (c_n) and (κ_n) defined above satisfy the conditions*

$$\sum_{n \geq 1} \frac{c_n}{\kappa_n^2} < \infty \quad (13)$$

and

$$\lim_{n \rightarrow \infty} \kappa_n / c_n = 0 \quad (14)$$

Then we obtain the following result:

I. For any $\varepsilon > 0$ and every $\theta \in \Theta_1$ the sequential plan $(T(\varepsilon), \theta_\varepsilon^*)$ defined by (12) is closed (i.e. $T(\varepsilon) < \infty$ P -a.s.) and has the following properties:

$$1^\circ. \quad \sup_{\Theta_1} E_{\theta_\varepsilon^*} (\theta_\varepsilon^* - \theta)^2 \leq \varepsilon \quad \text{for every } \varepsilon > 0,$$

2 $^\circ$. for every $\theta \in \Theta_1$ the following relations hold:

- if $(i, j) \in I_1$ then

$$0 < \underline{\lim}_{\varepsilon \rightarrow 0} \varepsilon \cdot T(\varepsilon) \leq \overline{\lim}_{\varepsilon \rightarrow 0} \varepsilon \cdot T(\varepsilon) < \infty \quad P - a.s.,$$

- if $(i, j) \in I_2 \cup I_3 \cup I_5$ then

$$0 < \underline{\lim}_{\varepsilon \rightarrow 0} [T(\varepsilon) - \frac{1}{2v_i} \ln \varepsilon^{-1}] \leq \overline{\lim}_{\varepsilon \rightarrow 0} [T(\varepsilon) - \frac{1}{2v_i} \ln \varepsilon^{-1}] < \infty \quad P - a.s.,$$

- if $(i, j) \in I_4$ then

$$0 < \underline{\lim}_{\varepsilon \rightarrow 0} \varepsilon T^2(\varepsilon) e^{2v_0 T(\varepsilon)} \leq \overline{\lim}_{\varepsilon \rightarrow 0} \varepsilon T^2(\varepsilon) e^{2v_0 T(\varepsilon)} < \infty \quad P - a.s.$$

II. For any $\varepsilon > 0$ and every $\theta \in \Theta_1$ the estimator $\theta_\varepsilon(n)$ is strongly consistent:

$$\lim_{n \rightarrow \infty} \theta_\varepsilon(n) = \theta \quad P - a.s.$$

The proofs of this and the next theorem are given in Section 4.

Remark 2 *Consider the special case of the system (1), (2), when the parameter b equals zero, which means that $X(\cdot)$ is an Ornstein-Uhlenbeck process. Then the assertions of Theorem 3.1 are true if in equation (1) we have $a \neq 0$. Note, that in [11] only the case ($a < 0$) has been considered.*

3.2 Sequential estimation procedure II

Consider the problem of estimating $\vartheta \in \Theta_2$. Based on equation (6) we define the estimation procedure analogously to the one given in Section 3.1. Assume \tilde{h}_0 is a real number in $(0, 1/5)$ and \tilde{h} is a random variable with values in $[\tilde{h}_0, 1/5]$ only, $\mathcal{F}(0)$ -measurable and having a known continuous distribution function.

We introduce several quantities:

– the functions

$$\tilde{\Psi}_s(t) = \begin{cases} (\tilde{\Delta}Y(t), \tilde{\Delta}Y(t-s))' & \text{for } t \geq 1+s, \\ (0, 0)' & \text{for } t < 1+s; \end{cases}$$

– the sequence of stopping times

$$\tilde{\tau}_\varepsilon(n) = \tilde{h} \inf\{k \geq 1 : \int_0^{k\tilde{h}} \|\tilde{\Psi}_{\tilde{h}}(t-2-5\tilde{h})\|^2 dt \geq \varepsilon^{-1}c_n\} \quad \text{for } n \geq 1;$$

– the matrices

$$G^*(T, s) = \int_0^T \tilde{\Psi}_s(t-2-5s)\tilde{\Psi}'_1(t)dt,$$

$$\Phi^*(T, s) = \int_0^T \tilde{\Psi}_s(t-2-5s)d\tilde{\Delta}Y(t),$$

$$\tilde{G}_\varepsilon(n, k) = G^*(\tilde{\tau}_\varepsilon(n) - k\tilde{h}, \tilde{h}), \quad \tilde{\Phi}_\varepsilon(n, k) = \Phi^*(\tilde{\tau}_\varepsilon(n) - k\tilde{h}, \tilde{h});$$

– the times

$$\tilde{k}_n = \arg \min_{k=1,5} \|\tilde{G}_\varepsilon^{-1}(n, k)\|, \quad n \geq 1;$$

– the estimators

$$\tilde{\vartheta}_\varepsilon(n) = \tilde{G}_\varepsilon^{-1}(n)\tilde{\Phi}_\varepsilon(n), \quad n \geq 1, \quad \text{where}$$

$$\tilde{G}_\varepsilon(n) = \tilde{G}_\varepsilon(n, \tilde{k}_n), \quad \tilde{\Phi}_\varepsilon(n) = \tilde{\Phi}_\varepsilon(n, \tilde{k}_n);$$

– the stopping time

$$\tilde{\nu}_\varepsilon = \inf\{n \geq 1 : \|\tilde{G}_\varepsilon^{-1}(n)\| \leq \varepsilon(\tilde{\rho}^{1/2}\kappa_n)^{-1}\}, \quad \text{where}$$

$$\tilde{\rho} = 15(2 + \bar{s}^2) \sum_{n \geq 1} c_n / \kappa_n^2.$$

Define the sequential estimation plan of ϑ by

$$\tilde{T}(\varepsilon) = \tilde{\tau}_\varepsilon(\tilde{\nu}_\varepsilon), \quad \tilde{\vartheta}(\varepsilon) = \tilde{\vartheta}_\varepsilon(\tilde{\nu}_\varepsilon) = \tilde{G}_\varepsilon^{-1}(\tilde{\nu}_\varepsilon)\tilde{\Phi}_\varepsilon(\tilde{\nu}_\varepsilon). \quad (15)$$

We can see that the construction of the sequential estimator $\tilde{\vartheta}(\varepsilon)$ bases on the family of estimators $\vartheta^*(T, s) = (G^*(T, s))^{-1}\Phi^*(T, s)$, $s \geq 0$. We have taken the discretization step \tilde{h} as above, because from (49) below it follows that the functions

$$\tilde{f}(T, s) = \frac{1}{e^{2v_0T}} G^*(T, s)$$

for every $s \geq 0$ have some periodic matrix functions as a limit almost surely. These limiting matrix functions are finite and may be degenerate only for four values of their argument T on every interval of periodicity of length $\Delta > 1$ (see proof of Theorem 3.2 below).

We state the results concerning the estimation of the parameter $\vartheta \in \Theta_2$ in the following theorem.

Theorem 3.2 *Assume that the conditions (13) and (14) on the sequences (c_n) and (κ_n) hold and let the parameter $\vartheta = (a, b)'$ in (1) is such that $\vartheta \in \Theta_2$. Then we obtain:*

I. For any $\varepsilon > 0$ and every $\vartheta \in \Theta_2$ the sequential plan $(\tilde{T}(\varepsilon), \tilde{\vartheta}(\varepsilon))$ defined by (15) is closed and possesses the following properties:

$$1^\circ. \quad \sup_{\Theta_2} E_{\vartheta} \|\tilde{\vartheta}(\varepsilon) - \vartheta\|^2 \leq \varepsilon \quad \text{for every } \varepsilon > 0,$$

2°. *for every $\theta \in \Theta_2$ one of the inequalities below is valid:*

- *in the stationary case ($v_0 < 0$)*

$$0 < \liminf_{\varepsilon \rightarrow 0} \varepsilon \cdot \tilde{T}(\varepsilon) \leq \overline{\lim}_{\varepsilon \rightarrow 0} \varepsilon \cdot \tilde{T}(\varepsilon) < \infty \quad P - a.s.,$$

- *in the periodic case ($v_0 > 0$, $v_0 \notin \Lambda$)*

$$0 < \liminf_{\varepsilon \rightarrow 0} [\tilde{T}(\varepsilon) - \frac{1}{2v_0} \ln \varepsilon^{-1}] \leq \overline{\lim}_{\varepsilon \rightarrow 0} [\tilde{T}(\varepsilon) - \frac{1}{2v_0} \ln \varepsilon^{-1}] < \infty \quad P - a.s.$$

II. For any $\varepsilon > 0$ and every $\vartheta \in \Theta_2$ the estimator $\vartheta_\varepsilon(n)$ is strongly consistent:

$$\lim_{n \rightarrow \infty} \tilde{\vartheta}_\varepsilon(n) = \vartheta \quad P - a.s.$$

Remark 3 *Property I in Theorems 3.1 and 3.2 yields the rates of convergence of the considered sequential plans. These depend on the region to which the parameter ϑ belongs to. They have the same rate of convergence as the maximum likelihood estimator of ϑ , see [2], constructed directly from the observations of the process $X(\cdot)$.*

4 Proofs

4.1 Proof of Theorem 3.1

At first we prove the finiteness of the stopping times $T(\varepsilon)$.

To this aim we put

$$\varphi_{ij}(T) = \begin{cases} T, & (i, j) \in I_1, \\ e^{2v_i T}, & (i, j) \in I_2 \cup I_3 \cup I_5, \\ T^2 e^{2v_0 T}, & (i, j) \in I_4. \end{cases}$$

and prove the following auxiliary results: Fix $u = 0$ or $u \in [2, \infty)$. Then
– for $(i, j) \in I_1 \cup I_2 \cup I_3 \cup I_4$ it holds

$$\lim_{T \rightarrow \infty} \frac{1}{\varphi_{ij}(T)} \int_0^T \Psi(t-u) \Psi(t) dt = f_{iju} \quad P - \text{a.s.}, \quad (16)$$

where f_{iju} are some constants or random variables;

– for $(i, j) \in I_5$ we have

$$\lim_{T \rightarrow \infty} \left| \frac{1}{\varphi_{ij}(T)} \int_0^T \Psi(t-u) \Psi(t) dt - f_{iju}(T) \right| = 0 \quad P - \text{a.s.}, \quad (17)$$

where $f_{iju}(T)$ are periodic random functions of T with the period $\Delta = 2\pi/\xi_0$, $\xi_0 \in (0, \pi)$ if $(i, j) = \{(0, 6), (1, 6)\}$ and $\Delta = 2\pi/\xi_1$, $\xi_1 \in (\pi, 2\pi)$ if $(i, j) = (1, 5)$.

Proof of (16) and (17). Now we establish the equalities (16) in the cases I_1 for $u = 0$, $u \geq 2$ and the other equalities in (16) and (17) for $u \geq 0$. According to [2] for $\vartheta \in \Theta_1$ the solution $X(t)$ of (1) has the representation

$$\begin{aligned} X(t) &= x_0(t)X_0(0) + b \int_{-1}^0 x_0(t-s-1)X_0(s)ds \\ &+ \int_0^t x_0(t-s)dW(s), \quad t \geq 0, \end{aligned} \quad (18)$$

where $x_0(\cdot)$ is the so called fundamental solution of (1). It has the properties $x_0(t) = 0$, $t \in [-1, 0)$, $x_0(0) = 1$ and satisfies for $t \rightarrow \infty$

$$x_0(t) = \begin{cases} o(e^{\gamma t}), & \gamma < 0, \quad j = 1, \\ \frac{1}{v_0 - a + 1} e^{v_0 t} + o(e^{\gamma t}), & \gamma < 0, \quad j = 2, \\ \frac{1}{v_0 - a + 1} e^{v_0 t} + \frac{1}{a - v_1 - 1} e^{v_1 t} + o(e^{\gamma_1 t}), & \gamma_1 < v_1, \quad j = 3, \\ (2t + \frac{2}{3})e^{v_0 t} + o(e^{\gamma_0 t}), & \gamma_0 < v_0, \quad j = 4, \\ \frac{1}{v_0 - a + 1} e^{v_0 t} + \phi_1(t)e^{v_1 t} + o(e^{\gamma_1 t}), & \gamma_1 < v_1, \quad j = 5, \\ \phi_0(t)e^{v_0 t} + o(e^{\gamma_0 t}), & \gamma_0 < v_0, \quad j = 6, \\ \frac{1}{1-a} + o(e^{\gamma t}), & \gamma < 0, \quad j = 7, \\ \frac{1}{v_0 - a + 1} e^{v_0 t} - \frac{1}{a-1} + o(e^{\gamma t}), & \gamma < 0, \quad j = 8, \\ \frac{1}{v_0 - a + 1} e^{v_0 t} + \phi_1(t) + o(e^{\gamma t}), & \gamma < 0, \quad j = 9, \end{cases}$$

for all $\gamma, \gamma_0, \gamma_1$ satisfying the mentioned inequalities respectively and may be different in different lines,

$$\phi_i(t) = A_i \cos \xi_i t + B_i \sin \xi_i t \quad \text{with}$$

$$A_i = \frac{2(v_i - a + 1)}{(v_i - a + 1)^2 + \xi_i^2}, \quad B_i = \frac{2\xi_i}{(v_i - a + 1)^2 + \xi_i^2}, \quad i = 0, 1.$$

By the definition of Ψ we have

$$\Psi(t) = \tilde{\Psi}(t) + \tilde{V}(t), \quad t \geq -1, \quad (19)$$

$$\tilde{\Psi}(t) = \begin{cases} \sigma^{-1}(\beta\tilde{X}(t) - \alpha\tilde{X}(t-1)), & t \geq 2, \\ 0, & t \in [-1, 2], \end{cases}$$

$$\tilde{X}(t) = \int_{t-1}^t X(s)ds,$$

$$\tilde{V}(t) = \begin{cases} \sigma^{-1}(\beta\tilde{\Delta}V(t) - \alpha\tilde{\Delta}V(t-1)), & t \geq 2, \\ 0, & t \in [-1, 2]. \end{cases}$$

It is easy to show that the process $(\tilde{X}(\cdot))$ has the following representation:

$$\tilde{X}(t) = \sigma^{-1}(\tilde{x}_0(t)X_0(0) + b \int_{-1}^0 \tilde{x}_0(t-s-1)X_0(s)ds + \int_0^t \tilde{x}_0(t-s)dW(s))$$

for $t \geq 1$, $\tilde{X}(t) = \int_{t-1}^0 X_0(s)ds + \int_0^t X(s)ds$ for $t \in [0, 1)$ and $\tilde{X}(t) = 0$ for $t \in [-1, 0)$. Based on (18) and the subsequent properties of $x_0(t)$ the function $\tilde{x}_0(t) = \int_{t-1}^t x_0(s)ds$ can easily be shown to fulfill $\tilde{x}_0(t) = 0$, $t \in [-1, 0]$ and as $t \rightarrow \infty$

$$\tilde{x}_0(t) = \begin{cases} o(e^{\gamma t}), & \gamma < 0, \quad j = 1, \\ \frac{1-e^{-v_0}}{v_0(v_0-a+1)}e^{v_0 t} + o(e^{\gamma t}), & \gamma < 0, \quad j = 2, \\ \frac{1-e^{-v_0}}{v_0(v_0-a+1)}e^{v_0 t} + \frac{1-e^{-v_1}}{v_1(a-v_1-1)}e^{v_1 t} + o(e^{\gamma_1 t}), & \gamma_1 < v_1, \quad j = 3, \\ \frac{2}{v_0}[(1-e^{-v_0})t + e^{-v_0} - \frac{1-e^{-v_0}}{v_0}]e^{v_0 t} + o(e^{\gamma_0 t}), & \gamma_0 < v_0, \quad j = 4, \\ \frac{1-e^{-v_0}}{v_0(v_0-a+1)}e^{v_0 t} + \tilde{\phi}_1(t)e^{v_1 t} + o(e^{\gamma_1 t}), & \gamma_1 < v_1, \quad j = 5, \\ \tilde{\phi}_0(t)e^{v_0 t} + o(e^{\gamma_0 t}), & \gamma_0 < v_0, \quad j = 6, \\ \frac{1}{1-a} + o(e^{\gamma t}), & \gamma < 0, \quad j = 7, \\ \frac{1-e^{-v_0}}{v_0(v_0-a+1)}e^{v_0 t} - \frac{1}{a-1} + o(e^{\gamma t}), & \gamma < 0, \quad j = 8, \\ \frac{1-e^{-v_0}}{v_0(v_0-a+1)}e^{v_0 t} + \tilde{\phi}_1(t) + o(e^{\gamma t}), & \gamma < 0, \quad j = 9, \end{cases}$$

where

$$\tilde{\phi}_i(t) = \tilde{A}_i \cos \xi_i t + \tilde{B}_i \sin \xi_i t,$$

$$\begin{aligned} \tilde{A}_i &= \frac{1}{v_i^2 + \xi_i^2} [\xi_i e^{-v_i} \sin \xi_i - v_i e^{-v_i} \cos \xi_i + v_i] A_i \\ &+ \frac{1}{v_i^2 - \xi_i^2} [v_i e^{-v_i} \sin \xi_i + v_i e^{-v_i} \cos \xi_i - \xi_i] B_i, \end{aligned}$$

$$\begin{aligned} \tilde{B}_i &= \frac{1}{v_i^2 + \xi_i^2} [\xi_i - v_i e^{-v_i} \sin \xi_i - \xi_i e^{-v_i} \cos \xi_i] A_i \\ &+ \frac{1}{v_i^2 - \xi_i^2} [\xi_i e^{-v_i} \sin \xi_i - v_i e^{-v_i} \cos \xi_i + v_i] B_i. \end{aligned}$$

Analogously we can get the following representation for the process $\tilde{\Psi}(t)$ with $x_{\Psi}(t) = \beta\tilde{x}_0(t) - \alpha\tilde{x}_0(t-1)$:

$$\begin{aligned}\tilde{\Psi}(t) &= \sigma^{-1}(x_{\Psi}(t)X_0(0) + b \int_{-1}^0 x_{\Psi}(t-s-1)X_0(s)ds \\ &+ \int_0^t x_{\Psi}(t-s)dW(s))\end{aligned}\quad (20)$$

for $t \geq 2$; and x_{φ} has the properties $x_{\Psi}(t) = 0$ for $t \in [-1, 0]$; and for $t \rightarrow \infty$ it holds

$$x_{\Psi}(t) = \begin{cases} o(e^{\gamma t}), & \gamma < 0, \quad j = 1, \\ \frac{(1-e^{-v_0})(\beta-\alpha e^{-v_0})}{v_0(v_0-a+1)}e^{v_0 t} + o(e^{\gamma t}), & \gamma < 0, \quad j = 2, \\ \frac{(1-e^{-v_0})(\beta-\alpha e^{-v_0})}{v_0(v_0-a+1)}e^{v_0 t} + \frac{(1-e^{-v_1})(\beta-\alpha e^{-v_1})}{v_1(a-v_1-1)}e^{v_1 t} \\ + o(e^{\gamma_1 t}), & \gamma_1 < v_1, \quad j = 3, \\ \frac{2}{v_0} \{[(1-e^{-v_0})t + e^{-v_0} - \frac{1-e^{-v_0}}{v_0}](\beta - \alpha e^{-v_0}) \\ + \alpha e^{-v_0}(1-e^{-v_0})\}e^{v_0 t} + o(e^{\gamma_0 t}), & \gamma_0 < v_0, \quad j = 4, \\ \frac{(1-e^{-v_0})(\beta-\alpha e^{-v_0})}{v_0(v_0-a+1)}e^{v_0 t} + \phi_1^*(t)e^{v_1 t} + o(e^{\gamma_1 t}), & \gamma_1 < v_1, \quad j = 5, \\ \phi_0^*(t)e^{v_0 t} + o(e^{\gamma_0 t}), & \gamma_0 < v_0, \quad j = 6. \\ \frac{\beta-\alpha}{1-a} + o(e^{\gamma t}), & \gamma < 0, \quad j = 7, \\ \frac{(1-e^{-v_0})(\beta-\alpha e^{-v_0})}{v_0(v_0-a+1)}e^{v_0 t} - \frac{\beta-\alpha}{a-1} + o(e^{\gamma t}), & \gamma < 0, \quad j = 8, \\ \frac{(1-e^{-v_0})(\beta-\alpha e^{-v_0})}{v_0(v_0-a+1)}e^{v_0 t} + \phi_1^*(t) + o(e^{\gamma t}), & \gamma < 0, \quad j = 9. \end{cases}$$

Here

$$\phi_i^*(t) = A_i^* \cos \xi_i t + B_i^* \sin \xi_i t,$$

$$A_i^* = \beta\tilde{A}_i - \alpha\tilde{A}_i e^{-v_i} \cos \xi_i - \alpha\tilde{B}_i e^{-v_i} \sin \xi_i,$$

$$B_i^* = \beta\tilde{B}_i - \alpha\tilde{A}_i e^{-v_i} \sin \xi_i - \alpha\tilde{B}_i e^{-v_i} \cos \xi_i, \quad i = 0, 1.$$

The processes $\tilde{\Psi}(t)$ and $\tilde{V}(t)$ are mutually independent (by assumption, W, V and X_0 are independent), and the process $\tilde{\Psi}(t)$ has a representation similar to (18). This is a consequence of the definition of $\tilde{\Psi}$ and the preceding calculations. Then, after a series of calculations similar to those in [2] and [5, 6] we get the following limits:

– for $(i, j) \in I_1$

$$f_{iju} = \begin{cases} \sigma^{-2}(\int_0^{\infty} x_{\Psi}^2(t)dt + 1), & u = 0, \\ \sigma^{-2} \int_0^{\infty} x_{\Psi}(t+u)x_{\Psi}(t)dt, & u \geq 2; \end{cases}$$

– for $(i, j) \in I_2 \cup I_3$

$$\lim_{t \rightarrow \infty} e^{-v_i t} \tilde{\Psi}(t) = \tilde{c}_{ij} U_i \quad P - \text{a.s.},$$

$$U_i = X_0(0) + b \int_{-1}^0 e^{-v_i(s+1)} X_0(s)ds + \int_0^{\infty} e^{-v_i s} dW(s),$$

$$\tilde{c}_{0j} = \frac{(1 - e^{-v_0})(\beta - \alpha e^{-v_0})}{v_0(v_0 - a + 1)}\sigma^{-1}, \quad \tilde{c}_{13} = \frac{(1 - e^{-v_1})(1 - e^{v_0 - v_1})}{v_1(a - v_1 - 1)}\beta\sigma^{-1},$$

$$\tilde{c}_{14} = \frac{2(1 - e^{-v_0})}{v_0}\beta\sigma^{-1}$$

and as follows

$$f_{iju} = \frac{\tilde{c}_{ij}^2 U_i^2}{2v_i} e^{-v_i u}, \quad u \geq 0;$$

– for $(i, j) \in I_4$

$$\lim_{t \rightarrow \infty} t^{-1} e^{-v_0 t} \tilde{\Psi}(t) = \tilde{c}_0 U_0 \quad P - \text{a.s.},$$

$$\tilde{c}_0 = \frac{2(1 - e^{-v_0})}{v_0}(\beta - \alpha e^{-v_0})\sigma^{-1}$$

and

$$f_{iju} = \frac{\tilde{c}_0^2 U_0^2}{4v_0} e^{-v_i u}, \quad u \geq 0;$$

– for $(i, j) \in I_5$

$$\lim_{t \rightarrow \infty} |e^{-v_i t} \tilde{\Psi}(t) - U_{ij}(t)| = 0 \quad P - \text{a.s.},$$

where for $(i, j) \in I_5 \setminus \{(1, 6)\}$

$$\begin{aligned} U_{ij}(t) &= \sigma^{-1}(X_0(0)\phi_i^*(t) + b \int_{-1}^0 \phi_i^*(t-s-1)e^{-v_i(s+1)}X_0(s)ds \\ &\quad + \int_0^\infty \phi_i^*(t-s)e^{-v_i s}dW(s)), \end{aligned}$$

$$\begin{aligned} U_{16}(t) &= \sigma^{-1}(X_0(0)\phi_0^*(t) + b \int_{-1}^0 \phi_0^*(t-s-1)e^{-v_i(s+1)}X_0(s)ds \\ &\quad + \int_0^\infty \phi_0^*(t-s)e^{-v_i s}dW(s)) \end{aligned}$$

and

$$f_{iju}(T) = \sigma^{-2} e^{v_i u} \int_0^\infty e^{-2v_i t} U_i(T-t) \hat{U}_i(T-t) dt, \quad u \geq 0,$$

$$\begin{aligned} \hat{U}_i(t) &= X_0(0)\hat{\phi}_i(t) + b \int_{-1}^0 \hat{\phi}_i(t-s-1)e^{-v_i(s+1)}X_0(s)ds \\ &\quad + \int_0^\infty \hat{\phi}_i(t-s)e^{-v_i s}dW(s), \end{aligned}$$

$$\hat{\phi}_i(t) = \hat{A}_i \cos \xi_i t + \hat{B}_i \sin \xi_i t,$$

$$\hat{A}_i = A_i^* \cos \xi_i u - B_i^* \sin \xi_i u, \quad \hat{B}_i = -A_i^* \sin \xi_i u + B_i^* \cos \xi_i u, \quad i = 0, 1.$$

Here $U_i(t) \equiv \hat{U}_i(t)$ by $u = 0$.

The relations (16) and (17) are proved. We continue to show the finiteness of $T(\varepsilon)$.

Because the function $x_\Psi(t)$ is defined similar to the function $x_0(t)$ (its structure and properties have been investigated, for example, in [2]), we can see that $meas\{u \in (2, 3] : f_{iju} = 0\} = 0$ in the cases $(i, j) \in I_1$ and it is obviously that $f_{iju} \neq 0$ P -a.s. for $(i, j) \in I_2 \cup I_3 \cup I_4$.

Define for $(i, j) \in I_5$

$$\bar{f}_{iju} = \sup_{t \in (0, \infty)} |f_{iju}(t)|, \quad \underline{f}_{ij0} = \inf_{t \in (0, \infty)} |f_{ij0}(t)|.$$

It is clear that for $u = 0$ and $u \geq 2$ respectively these values are positive and finite. From here and (16), (17) it follows, in particular, the finiteness of the stopping times $\tau_\varepsilon(n)$, $n \geq 1$ defined by (10), because for all $(i, j) \in I_1 \cup I_2 \cup I_3 \cup I_4$ the limits f_{ij0} are positive P -a.s.

By using (16) and the definition of $\tau_\varepsilon(n)$ we have the next limiting equalities:

– for $(i, j) \in I_1$

$$\lim_{n \rightarrow \infty} \frac{\tau_\varepsilon(n)}{\varepsilon^{-1} c_n} = \lim_{\varepsilon \rightarrow 0} \frac{\tau_\varepsilon(n)}{\varepsilon^{-1} c_n} = f_{ij0}^{-1} P \text{ - a.s.} \quad (21)$$

Taking into account the inequalities

$$\int_0^{\tau_\varepsilon(n)-2-4h} \Psi^2(t) dt < \varepsilon^{-1} c_n \leq \int_0^{\tau_\varepsilon(n)-2-3h} \Psi^2(t) dt,$$

we obtain:

– for $(i, j) \in I_2 \cup I_3$

$$e^{2v_i(2+3h)} f_{ij0}^{-1} \leq \lim_{n \rightarrow \infty} \frac{e^{2v_i \tau_\varepsilon(n)}}{\varepsilon^{-1} c_n} \leq \overline{\lim}_{n \rightarrow \infty} \frac{e^{2v_i \tau_\varepsilon(n)}}{\varepsilon^{-1} c_n} \leq e^{4v_i(1+2h)} f_{ij0}^{-1} P \text{ - a.s.}, \quad (22)$$

$$e^{2v_i(2+3h)} f_{ij0}^{-1} \leq \lim_{\varepsilon \rightarrow 0} \frac{e^{2v_i \tau_\varepsilon(n)}}{\varepsilon^{-1} c_n} \leq \overline{\lim}_{\varepsilon \rightarrow 0} \frac{e^{2v_i \tau_\varepsilon(n)}}{\varepsilon^{-1} c_n} \leq e^{4v_i(1+2h)} f_{ij0}^{-1} P \text{ - a.s.} \quad (23)$$

and as follows

$$2 + 3h - \frac{1}{2v_i} \ln f_{ij0} + \frac{1}{2v_i} \ln \varepsilon^{-1} \leq \lim_{n \rightarrow \infty} [\tau_\varepsilon(n) - \frac{1}{2v_i} \ln c_n] \leq \overline{\lim}_{n \rightarrow \infty} [\tau_\varepsilon(n) - \frac{1}{2v_i} \ln c_n] \leq 2(1 + 2h) - \frac{1}{2v_i} \ln f_{ij0} + \frac{1}{2v_i} \ln \varepsilon^{-1} P \text{ - a.s.}, \quad (24)$$

$$\begin{aligned}
2 + 3h - \frac{1}{2v_i} \ln f_{ij0} + \frac{1}{2v_i} \ln c_n &\leq \lim_{\varepsilon \rightarrow 0} [\tau_\varepsilon(n) - \frac{1}{2v_i} \ln \varepsilon^{-1}] \leq \overline{\lim}_{\varepsilon \rightarrow 0} [\tau_\varepsilon(n) \\
&- \frac{1}{2v_i} \ln \varepsilon^{-1}] \leq 2(1 + 2h) - \frac{1}{2v_i} \ln f_{ij0} + \frac{1}{2v_i} \ln c_n \quad P - \text{a.s.};
\end{aligned} \tag{25}$$

– for $(i, j) \in I_4$

$$\begin{aligned}
e^{2v_i(2+3h)} f_{ij0}^{-1} &\leq \lim_{n \rightarrow \infty} \frac{\tau_\varepsilon^2(n) e^{2v_i \tau_\varepsilon(n)}}{\varepsilon^{-1} c_n} \leq \overline{\lim}_{n \rightarrow \infty} \frac{\tau_\varepsilon^2(n) e^{2v_i \tau_\varepsilon(n)}}{\varepsilon^{-1} c_n} \\
&\leq e^{4v_i(1+2h)} f_{ij0}^{-1} \quad P - \text{a.s.},
\end{aligned} \tag{26}$$

$$\begin{aligned}
e^{2v_i(2+3h)} f_{ij0}^{-1} &\leq \lim_{\varepsilon \rightarrow 0} \frac{\tau_\varepsilon^2(n) e^{2v_i \tau_\varepsilon(n)}}{\varepsilon^{-1} c_n} \leq \overline{\lim}_{\varepsilon \rightarrow 0} \frac{\tau_\varepsilon^2(n) e^{2v_i \tau_\varepsilon(n)}}{\varepsilon^{-1} c_n} \\
&\leq e^{4v_i(1+2h)} f_{ij0}^{-1} \quad P - \text{a.s.}
\end{aligned} \tag{27}$$

From (17) and by the definition (10) of $\tau_\varepsilon(n)$ for all $(i, j) \in I_5$ we have

$$e^{2v_i(2+3h)} \bar{f}_{ij0}^{-1} \leq \lim_{n \rightarrow \infty} \frac{e^{2v_i \tau_\varepsilon(n)}}{\varepsilon^{-1} c_n} \leq \overline{\lim}_{n \rightarrow \infty} \frac{e^{2v_i \tau_\varepsilon(n)}}{\varepsilon^{-1} c_n} \leq e^{4v_i(1+2h)} \bar{f}_{ij0}^{-1} \quad P - \text{a.s.} \tag{28}$$

and

$$e^{2v_i(2+3h)} \bar{f}_{ij0}^{-1} \leq \lim_{\varepsilon \rightarrow 0} \frac{e^{2v_i \tau_\varepsilon(n)}}{\varepsilon^{-1} c_n} \leq \overline{\lim}_{\varepsilon \rightarrow 0} \frac{e^{2v_i \tau_\varepsilon(n)}}{\varepsilon^{-1} c_n} \leq e^{4v_i(1+2h)} \bar{f}_{ij0}^{-1} \quad P - \text{a.s.} \tag{29}$$

From (28) we obtain for every $\varepsilon > 0$

$$\begin{aligned}
2 + 3h - \frac{1}{2v_i} \ln \bar{f}_{ij0} + \frac{1}{2v_i} \ln \varepsilon^{-1} &\leq \lim_{n \rightarrow \infty} [\tau_\varepsilon(n) - \frac{1}{2v_i} \ln c_n] \leq \overline{\lim}_{n \rightarrow \infty} [\tau_\varepsilon(n) \\
&- \frac{1}{2v_i} \ln c_n] \leq 2(1 + 2h) - \frac{1}{2v_i} \ln \bar{f}_{ij0} + \frac{1}{2v_i} \ln \varepsilon^{-1} \quad P - \text{a.s.}
\end{aligned} \tag{30}$$

and from (29) for $n \geq 1$ it follows

$$\begin{aligned}
2 + 3h - \frac{1}{2v_i} \ln \bar{f}_{ij0} + \frac{1}{2v_i} \ln c_n &\leq \lim_{\varepsilon \rightarrow 0} [\tau_\varepsilon(n) - \frac{1}{2v_i} \ln \varepsilon^{-1}] \leq \overline{\lim}_{\varepsilon \rightarrow 0} [\tau_\varepsilon(n) \\
&- \frac{1}{2v_i} \ln \varepsilon^{-1}] \leq 2(1 + 2h) - \frac{1}{2v_i} \ln \bar{f}_{ij0} + \frac{1}{2v_i} \ln c_n \quad P - \text{a.s.}
\end{aligned} \tag{31}$$

Note that in the cases $I_2 \cup I_3 \cup I_5$ we have

$$\lim_{n \rightarrow \infty} \frac{\tau_\varepsilon(n)}{\ln c_n} = \lim_{\varepsilon \rightarrow 0} \frac{\tau_\varepsilon(n)}{\ln \varepsilon^{-1}} = \frac{1}{2v_i} \quad P - \text{a.s.} \tag{32}$$

Put $\delta_\varepsilon(n) = \tau_\varepsilon(n)k_n h$.

Now we are able to show the finiteness of the stopping time ν_ε . From (16), (21), (22) and (26) with P -probability one we have the relations:

– for $(i, j) \in I_1$

$$\lim_{n \rightarrow \infty} \frac{1}{c_n} \int_2^{\delta_\varepsilon(n)} \Psi(t - 2 - 3h) \Psi(t) dt = (\varepsilon f_{ij0})^{-1} f_{ij(2+3h)}; \quad (33)$$

– for $(i, j) \in I_2 \cup I_3 \cup I_4$

$$\begin{aligned} e^{4v_i} (\varepsilon f_{ij0})^{-1} |f_{ij(2+3h)}| &\leq \lim_{n \rightarrow \infty} \left| \frac{1}{c_n} \int_2^{\delta_\varepsilon(n)} \Psi(t - 2 - 3h) \Psi(t) dt \right| \\ &\leq \overline{\lim}_{n \rightarrow \infty} \left| \frac{1}{c_n} \int_2^{\delta_\varepsilon(n)} \Psi(t - 2 - 3h) \Psi(t) dt \right| \leq e^{2v_i(2+3h)} (\varepsilon f_{ij0})^{-1} |f_{ij(2+3h)}|. \end{aligned} \quad (34)$$

Consider the cases $(i, j) \in I_5$. For all $u \geq 2$ and $(i, j) \in I_5$ the functions $f_{iju}(T)$ of T are periodic with corresponding periods $\Delta > 1$ and each of them has at most two roots on every interval of the lengths Δ . Denote these roots for $u = 2 + 3h$ as $t_m(i, j)$, $m \leq 2$ on the set $(0, \Delta]$. Then define V_{ij} to be the union of open disjoint neighborhoods with the radius less than $1/6$ for all roots $t_m(i, j) + N\Delta$, $m = 1, 2$, $N \geq 0$ and put

$$\mathcal{R}_{ij}^+ = (0, \infty) \setminus V_{ij}.$$

Define

$$f_{iju}^* = \inf_{t \in \mathcal{R}_{ij}^+} |f_{iju}(t)|,$$

$$Q_n(i, j) = \{k = \overline{1, 3} : nh - kh \in \mathcal{R}_{ij}^+\},$$

$$r_{ij}(n) = \arg \max_{k \in Q_n(i, j)} |f_{ij(2+3h)}(nh - kh)|.$$

By the continuity of $f_{iju}(\cdot)$ we have $f_{iju}^* > 0$ for $u = 0$ and $u \geq 2$. Note that for any $h \in (0, 1/3]$ and $(i, j) \in I_5$ the sets $Q_n(i, j)$ are non-empty and for n large enough from (17) we have

$$r_{ij}(n) = \arg \max_{k \in Q_n(i, j)} \left| e^{-2v_i(nh - kh)} \int_0^{nh - kh} \Psi(t - 2 - 3h) \Psi(t) dt \right| \quad P - \text{a.s.},$$

besides by the definition of $Q_n(i, j)$ for n large enough with P -probability one

$$f_{ij(2+3h)}^* \leq |f_{ij(2+3h)}(nh - r_{ij}(n)h)| \leq \overline{f}_{ij(2+3h)}$$

and

$$f_{ij(2+3h)}^* \leq \left| e^{-2v_i(nh - r_{ij}(n)h)} \int_0^{nh - r_{ij}(n)h} \Psi(t - 2 - 3h) \Psi(t) dt \right| \leq \overline{f}_{ij(2+3h)}.$$

Then for $(i, j) \in I_5$ with P -probability one we obtain the following relations

$$\begin{aligned}
& \overline{\lim}_{n \rightarrow \infty} |e^{-2v_i n h} \int_0^{nh-r_n h} \Psi(t-2-3h)\Psi(t)dt| \\
&= \overline{\lim}_{n \rightarrow \infty} e^{-2v_i r_n h} |e^{-2v_i(nh-r_n h)} \int_0^{nh-r_n h} \Psi(t-2-3h)\Psi(t)dt| \leq e^{-2v_i h} \bar{f}_{ij(2+3h)}, \\
& \underline{\lim}_{n \rightarrow \infty} |e^{-2v_i n h} \int_0^{nh-r_n h} \Psi(t-2-3h)\Psi(t)dt| \geq \underline{\lim}_{n \rightarrow \infty} e^{-2v_i r_{ij}(n)h} \\
& \cdot |e^{-2v_i(nh-r_{ij}(n)h)} \int_0^{nh-r_{ij}(n)h} \Psi(t-2-3h)\Psi(t)dt| \geq e^{-6v_i h} f_{ij(2+3h)}^*
\end{aligned}$$

and as follows for all $\varepsilon > 0$

$$\begin{aligned}
& e^{-6v_i h} f_{ij(2+3h)}^* \leq \underline{\lim}_{n \rightarrow \infty} |e^{-2v_i \tau_\varepsilon(n)} \int_0^{\tau_\varepsilon(n)-k_n h} \Psi(t-2-3h)\Psi(t)dt| \\
& \leq \overline{\lim}_{n \rightarrow \infty} |e^{-2v_i \tau_\varepsilon(n)} \int_0^{\tau_\varepsilon(n)-k_n h} \Psi(t-2-3h)\Psi(t)dt| \leq e^{-2v_i h} \bar{f}_{ij(2+3h)}. \quad (35)
\end{aligned}$$

In such a way for the cases $(i, j) \in I_5$ from (28) and (35) with P -probability one we have

$$\begin{aligned}
& e^{4v_i} (\varepsilon \bar{f}_{ij0})^{-1} f_{ij(2+3h)}^* \leq \underline{\lim}_{n \rightarrow \infty} \frac{1}{c_n} \left| \int_2^{\delta_\varepsilon(n)} \tilde{\Psi}(t-2-3h)\tilde{\Psi}(t)dt \right| \\
& \leq \overline{\lim}_{n \rightarrow \infty} \frac{1}{c_n} \left| \int_2^{\delta_\varepsilon(n)} \tilde{\Psi}(t-2-3h)\tilde{\Psi}(t)dt \right| \leq e^{2v_i(2+3h)} (\varepsilon \underline{f}_{ij0})^{-1} \bar{f}_{ij(2+3h)}. \quad (36)
\end{aligned}$$

The finiteness of ν_ε follows from the definition ν_ε , (33), (34), (36) and the condition (14) on the sequences (c_n) and (κ_n) .

Thus the finiteness of the stopping times $T(\varepsilon)$ is established.

Let us estimate the mean square deviation of θ_ε^* . From (11) and by definitions of the stopping time ν_ε and ρ it follows that for all $\vartheta \in \mathcal{R}^2$

$$\begin{aligned}
& E_\vartheta(\theta_\varepsilon^* - \theta)^2 = E_\vartheta G_\varepsilon^{-2}(\nu_\varepsilon) \zeta_\varepsilon^2(\nu_\varepsilon) \leq \frac{\varepsilon^2}{\rho} E_\vartheta \frac{1}{\kappa_{\nu_\varepsilon}^2} \zeta_\varepsilon^2(\nu_\varepsilon) \\
& \leq \frac{\varepsilon^2}{\rho} \sum_{n \geq 1} \frac{1}{\kappa_n^2} E_\vartheta \zeta_\varepsilon^2(n) \leq \frac{9(2 + \bar{s}^2)\varepsilon}{\rho} \sum_{n \geq 1} \frac{c_n}{\kappa_n^2} = \varepsilon.
\end{aligned}$$

Thus the first property I.1^o of the sequential plans $(T(\varepsilon), \theta_\varepsilon^*)$ in Theorem 3.1 is proved.

In order to establish the second property note that similar to (33), (34), (36) for all $n \geq 1$ we can prove P-a.s.

– for $(i, j) \in I_1$

$$\lim_{\varepsilon \rightarrow 0} \varepsilon \int_0^{\delta_\varepsilon(n)} \Psi(t - 2 - 3h) \Psi(t) dt = f_{ij0}^{-1} f_{ij(2+3h)} c_n; \quad (37)$$

– for $(i, j) \in I_2 \cup I_3 \cup I_4$

$$\begin{aligned} e^{4v_i} f_{ij0}^{-1} |f_{ij(2+3h)}| c_n &\leq \lim_{\varepsilon \rightarrow 0} \varepsilon \left| \int_0^{\delta_\varepsilon(n)} \Psi(t - 2 - 3h) \Psi(t) dt \right| \\ &\leq \overline{\lim}_{\varepsilon \rightarrow 0} \varepsilon \left| \int_0^{\delta_\varepsilon(n)} \Psi(t - 2 - 3h) \Psi(t) dt \right| \leq e^{2v_i(2+3h)} f_{ij0}^{-1} |f_{ij(2+3h)}| c_n; \end{aligned} \quad (38)$$

– for $(i, j) \in I_5$

$$\begin{aligned} e^{4v_i} \bar{f}_{ij0}^{-1} f_{ij(2+3h)}^* c_n &\leq \lim_{\varepsilon \rightarrow 0} \varepsilon \left| \int_0^{\delta_\varepsilon(n)} \Psi(t - 2 - 3h) \Psi(t) dt \right| \\ &\leq \overline{\lim}_{\varepsilon \rightarrow 0} \varepsilon \left| \int_0^{\delta_\varepsilon(n)} \Psi(t - 2 - 3h) \Psi(t) dt \right| \leq e^{2v_i(2+3h)} \bar{f}_{ij0}^{-1} \bar{f}_{ij(2+3h)} c_n. \end{aligned} \quad (39)$$

Analogously to [11] from the definition of ν_ε and from (37)-(39) we can see that for ε small enough and $(i, j) \in I_1 \cup I_2 \cup I_3 \cup I_4 \cup I_5$

$$\nu'_{ij} \leq \nu_\varepsilon \leq \nu''_{ij} \quad P_\vartheta - \text{a.s.}, \quad (40)$$

where

$$\nu'_{ij} = \max\{\inf\{n \geq 1 : c_n/\kappa_n > g'_{ij}\} - 1, 1\},$$

$$\nu''_{ij} = \inf\{n \geq 1 : c_n/\kappa_n > g''_{ij}\},$$

$$g'_{ij} = \begin{cases} \rho^{1/2} f_{ij0} |f_{ij(2+3h)}^{-1}|, & (i, j) \in I_1, \\ \rho^{1/2} e^{-2v_i(2+3h)} f_{ij0} |f_{ij(2+3h)}^{-1}|, & (i, j) \in I_2 \cup I_3 \cup I_4, \\ \rho^{1/2} e^{-2v_i(2+3h)} \bar{f}_{ij0} \bar{f}_{ij(2+3h)}^{-1}, & (i, j) \in I_5, \end{cases}$$

$$g''_{ij} = \begin{cases} g'_{ij}, & (i, j) \in I_1, \\ \rho^{1/2} e^{-4v_i} f_{ij0} |f_{ij(2+3h)}^{-1}|, & (i, j) \in I_2 \cup I_3 \cup I_4, \\ \rho^{1/2} e^{-4v_i} \bar{f}_{ij0} (f_{ij(2+3h)}^*)^{-1}, & (i, j) \in I_5. \end{cases}$$

Now from (12), (21), (25), (27), (31) and (40) the second I.2^o assertion of Theorem 3.1 follows:

– for $(i, j) \in I_1$ by

$$f_{ij0}^{-1} c_{\nu'_{ij}} \leq \liminf_{\varepsilon \rightarrow 0} \varepsilon T(\varepsilon) \leq \overline{\lim}_{\varepsilon \rightarrow 0} \varepsilon T(\varepsilon) \leq f_{ij0}^{-1} c_{\nu''_{ij}} P - \text{a.s.};$$

– for $(i, j) \in I_2 \cup I_3$ by

$$\begin{aligned} 2 + 3h - \frac{1}{2v_i} \ln f_{ij0} + \frac{1}{2v_i} \ln c_{\nu'_{ij}} &\leq \liminf_{\varepsilon \rightarrow 0} [T(\varepsilon) - \frac{1}{2v_i} \ln \varepsilon^{-1}] \\ &\leq \overline{\lim}_{\varepsilon \rightarrow 0} [T(\varepsilon) - \frac{1}{2v_i} \ln \varepsilon^{-1}] \leq 2(1 + 2h) - \frac{1}{2v_i} \ln f_{ij0} + \frac{1}{2v_i} \ln c_{\nu''_{ij}} P - \text{a.s.}; \end{aligned}$$

– for $(i, j) \in I_4$ by

$$\begin{aligned} e^{2v_0(2+3h)} f_{ij0}^{-1} c_{\nu'_{ij}} &\leq \liminf_{\varepsilon \rightarrow 0} \varepsilon T^2(\varepsilon) e^{2v_0 T(\varepsilon)} \leq \overline{\lim}_{\varepsilon \rightarrow 0} \varepsilon T^2(\varepsilon) e^{2v_0 T(\varepsilon)} \\ &\leq e^{4v_0(1+2h)} f_{ij0}^{-1} c_{\nu''_{ij}} P - \text{a.s.}; \end{aligned}$$

– for $(i, j) \in I_5$ by

$$\begin{aligned} 2 + 3h - \frac{1}{2v_i} \ln \bar{f}_{ij0} + \frac{1}{2v_i} \ln c_{\nu'_{ij}} &\leq \liminf_{\varepsilon \rightarrow 0} [T(\varepsilon) - \frac{1}{2v_i} \ln \varepsilon^{-1}] \\ &\leq \overline{\lim}_{\varepsilon \rightarrow 0} [T(\varepsilon) - \frac{1}{2v_i} \ln \varepsilon^{-1}] \leq 2(1 + 2h) - \frac{1}{2v_i} \ln \bar{f}_{ij0} + \frac{1}{2v_i} \ln c_{\nu''_{ij}} P - \text{a.s.} \end{aligned}$$

Thus the proof of part I of Theorem 3.1 is finished.

In order to prove the second assertion II of Theorem 3.1 note that according to (33), (34) and (36)

$$\overline{\lim}_{n \rightarrow \infty} c_n |G_\varepsilon^{-1}(n)| < \infty P - \text{a.s.}$$

and from (13), (14) it follows that

$$\sum_{n \geq 1} \frac{1}{c_n} < \infty.$$

In view of the form for the deviation of the estimators $\theta_\varepsilon(n)$ from ϑ it suffices to establish the next limiting equality

$$\lim_{n \rightarrow \infty} \frac{1}{c_n} \zeta_\varepsilon(n) = 0 P - \text{a.s.},$$

which follows from (11), as well as Chebychev's inequality and by the Borel–Cantelli lemma.

Therefore strong consistency of the estimators $\theta_\varepsilon(n)$, $\varepsilon > 0$ is obtained. \square

4.2 Proof of Theorem 3.2

Firstly we show the finiteness of the stopping times $\tilde{T}(\varepsilon)$.

We start by calculating for $u = 0$ and $u \geq 1$ the limits

$$\lim_{T \rightarrow \infty} \frac{1}{T} \int_1^T \tilde{\Delta}Y(t) \tilde{\Delta}Y(t-u) dt = f(u) \quad P - \text{a.s.} \quad (41)$$

in the stationary case and

$$\lim_{T \rightarrow \infty} \left| \frac{1}{e^{2v_0 T}} \int_1^T \tilde{\Delta}Y(t) \tilde{\Delta}Y(t-u) dt - f_u(T) \right| = 0 \quad P - \text{a.s.} \quad (42)$$

in the periodic case, where $f(u)$ is random function of u and $f_u(T)$ are periodic functions of T for all $u \geq 0$.

From (2) we have

$$\tilde{\Delta}Y(t) = \tilde{X}(t) + \tilde{\Delta}V(t), \quad t \geq 1.$$

By assumption the processes $\tilde{X}(t)$ and $\tilde{\Delta}Y(t)$ are mutually independent. Similar to the proof of Theorem 3.1 we can get the following limiting relations using the definition of the process $\tilde{X}(t)$:

– in the stationary case

$$f(u) = \begin{cases} \int_0^\infty \tilde{x}_0^2 dt + 1, & u = 0, \\ \int_0^\infty \tilde{x}_0(t+u) \tilde{x}_0(t) dt, & u \geq 1; \end{cases}$$

– in the periodic case

$$f_u(T) = e^{-v_0 u} \int_0^\infty e^{-2v_0 t} U_0^*(T-t) U_u^*(T-t) dt, \quad u \geq 0,$$

$$\begin{aligned} U_u^*(t) &= X_0(0) \tilde{\phi}_u^*(t) + b \int_{-1}^0 \tilde{\phi}_u^*(t-s-1) e^{-v_0(s+1)} X_0(s) ds \\ &+ \int_0^\infty \tilde{\phi}_u^*(t-s) e^{-v_0 s} dW(s), \end{aligned}$$

$$\tilde{\phi}_u^*(t) = \tilde{A}_u^* \cos \xi_0 t + \tilde{B}_u^* \sin \xi_0 t,$$

$$\tilde{A}_u^* = \tilde{A}_0 \cos \xi_0 u - \tilde{B}_0 \sin \xi_0 u, \quad \tilde{B}_u^* = \tilde{B}_0 \cos \xi_0 u - \tilde{A}_0 \sin \xi_0 u.$$

By the definition of ξ_0 we can see that functions $f_u(T)$ are periodic with the period $\Delta > 1$. Note that $f(0) > 0$ and $0 < \underline{f}_0 = \inf_T f_0(T) < \sup_T f_0(T) = \bar{f}_0 < \infty$.

The relations (41), (42) and therefore the finiteness of the times $\tilde{\tau}_\varepsilon(n)$, $n \geq 1$, $\varepsilon > 0$ are established.

From (41), (42) and by the definition of the stopping times $\tilde{\tau}_\varepsilon(n)$ we have the next limiting relations:

– in the stationary case

$$\lim_{n \rightarrow \infty} \frac{\tilde{\tau}_\varepsilon(n)}{\varepsilon^{-1} c_n} = \lim_{\varepsilon \rightarrow 0} \frac{\tilde{\tau}_\varepsilon(n)}{\varepsilon^{-1} c_n} = (2f(0))^{-1} P - \text{a.s.}; \quad (43)$$

– in the periodic case for any $\varepsilon > 0$

$$\begin{aligned} e^{2v_0(2+5\tilde{h})} [\varepsilon(1 + e^{2v_0\tilde{h}}) \bar{f}_0]^{-1} &\leq \lim_{n \rightarrow \infty} c_n^{-1} e^{2v_0\tilde{\tau}_\varepsilon(n)} \\ &\leq \overline{\lim}_{n \rightarrow \infty} c_n^{-1} e^{2v_0\tilde{\tau}_\varepsilon(n)} \leq e^{4v_0(1+3\tilde{h})} [\varepsilon(1 + e^{2v_0\tilde{h}}) \underline{f}_0]^{-1} P - \text{a.s.} \end{aligned} \quad (44)$$

and for $n \geq 1$

$$\begin{aligned} e^{4v_0(1+3\tilde{h})} [(1 + e^{2v_0\tilde{h}}) \bar{f}_0]^{-1} c_n &\leq \lim_{\varepsilon \rightarrow 0} \varepsilon e^{2v_0\tilde{\tau}_\varepsilon(n)} \leq \overline{\lim}_{\varepsilon \rightarrow 0} \varepsilon e^{2v_0\tilde{\tau}_\varepsilon(n)} \\ &\leq e^{2v_0(2+7\tilde{h})} [(1 + e^{2v_0\tilde{h}}) \underline{f}_0]^{-1} c_n P - \text{a.s.} \end{aligned} \quad (45)$$

From (43), (44) in the periodic case for $\varepsilon > 0$

$$\begin{aligned} 2(1 + 3\tilde{h}) - \frac{1}{2v_0} \ln(1 + e^{2v_0\tilde{h}}) - \frac{1}{2v_0} \ln \bar{f}_0 + \frac{1}{2v_0} \ln \varepsilon^{-1} \\ \leq \lim_{n \rightarrow \infty} [\tilde{\tau}_\varepsilon(n) - \frac{1}{2v_0} \ln c_n] \leq \overline{\lim}_{n \rightarrow \infty} [\tilde{\tau}_\varepsilon(n) - \frac{1}{2v_0} \ln c_n] \leq 2 + 7\tilde{h} \\ - \frac{1}{2v_0} \ln(1 + e^{2v_0\tilde{h}}) - \frac{1}{2v_0} \ln \underline{f}_0 + \frac{1}{2v_0} \ln \varepsilon^{-1} P - \text{a.s.} \end{aligned} \quad (46)$$

and for $n \geq 1$

$$\begin{aligned} 2(1 + 3\tilde{h}) - \frac{1}{2v_0} \ln(1 + e^{2v_0\tilde{h}}) - \frac{1}{2v_0} \ln \bar{f}_0 + \frac{1}{2v_0} \ln c_n \\ \leq \lim_{\varepsilon \rightarrow 0} [\tilde{\tau}_\varepsilon(n) - \frac{1}{2v_0} \ln \varepsilon^{-1}] \leq \overline{\lim}_{\varepsilon \rightarrow 0} [\tilde{\tau}_\varepsilon(n) - \frac{1}{2v_0} \ln \varepsilon^{-1}] \\ \leq 2 + 7\tilde{h} - \frac{1}{2v_0} \ln(1 + e^{2v_0\tilde{h}}) - \frac{1}{2v_0} \ln \underline{f}_0 + \frac{1}{2v_0} \ln c_n P - \text{a.s.} \end{aligned} \quad (47)$$

From (41), (43) we can obtain in the stationary case

$$\begin{aligned} \lim_{n \rightarrow \infty} \frac{\varepsilon}{c_n} \int_1^{\tilde{\tau}_\varepsilon(n)} \tilde{\Delta} Y(t-u) \tilde{\Delta} Y(t) dt &= \lim_{\varepsilon \rightarrow 0} \frac{\varepsilon}{c_n} \int_1^{\tilde{\tau}_\varepsilon(n)} \tilde{\Delta} Y(t-u) \tilde{\Delta} Y(t) dt \\ &= (2f(0))^{-1} f(u), \quad u \geq 1 \quad P - \text{a.s.} \end{aligned}$$

and

$$\lim_{n \rightarrow \infty} \frac{\varepsilon}{c_n} \tilde{G}_\varepsilon(n) = \lim_{\varepsilon \rightarrow 0} \frac{\varepsilon}{c_n} \tilde{G}_\varepsilon(n) = \tilde{G}(\tilde{h}) \quad P - \text{a.s.}, \quad (48)$$

$$\tilde{G}(\tilde{h}) = (2f(0))^{-1} \begin{pmatrix} f(2+5\tilde{h}) & f(1+\tilde{h}) \\ f(2+6\tilde{h}) & f(1+6\tilde{h}) \end{pmatrix}.$$

Similar to the Case I we can see that $\text{meas}\{u \in [\tilde{h}_0, 1/5] : f(u) = 0\} = 0$ and $\text{meas}\{u \in [\tilde{h}_0, 1/5] : \det \tilde{G}(u) = 0\} = 0$. As follows $\det \tilde{G}(\tilde{h}) \neq 0 \quad P - \text{a.s.}$ From here, (14), (15) and (48) we have the finiteness of the times $\tilde{\nu}_\varepsilon$ in the stationary case.

Put

$$\tilde{G}(T, \tilde{h}) = \begin{pmatrix} f_{2+5\tilde{h}}(T) & e^{-2v_0} f_{1+5\tilde{h}}(T) \\ f_{2+6\tilde{h}}(T) & e^{-2v_0} f_{1+6\tilde{h}}(T) \end{pmatrix}.$$

From (42) in the periodic case it follows that the matrices $\tilde{G}(T, s)$ are the limits of the matrix functions $\tilde{f}(T, s) = \frac{1}{e^{2v_0 T}} G^*(T, s)$ in the almost surely sense:

$$\lim_{T \rightarrow \infty} |\tilde{f}(T, s) - \tilde{G}(T, s)| = 0, \quad s \geq 0 \quad P - \text{a.s.} \quad (49)$$

The matrix functions $\tilde{G}(T, s)$ are periodic with the period $\Delta > 1$ and according to the definition of functions $f_u(T)$, $u \geq 0$ the equation

$$\det \tilde{G}(T, s) = 0$$

has at most four roots \tilde{t}_m , $m = \overline{1, 4}$ on the set $(0, \Delta]$ for any s . Put $\tilde{\delta}_\varepsilon(n) = \tilde{\tau}_\varepsilon(n) - \tilde{k}_n \tilde{h}$. Note that in the periodic case by the definition of $\tilde{G}_\varepsilon(n)$ (15) and from (42) analogously to the proof of Theorem 3.1 we can get the following relations

$$\begin{aligned} & \lim_{n \rightarrow \infty} \left| \frac{1}{e^{2v_0 \tilde{\delta}_\varepsilon(n)}} \tilde{G}_\varepsilon(n) - \tilde{G}(\tilde{\delta}_\varepsilon(n), \tilde{h}) \right| \\ &= \lim_{\varepsilon \rightarrow 0} \left| \frac{1}{e^{2v_0 \tilde{\delta}_\varepsilon(n)}} \tilde{G}_\varepsilon(n) - \tilde{G}(\tilde{\delta}_\varepsilon(n), \tilde{h}) \right| = 0 \quad P - \text{a.s.} \end{aligned} \quad (50)$$

and for some constants \tilde{g}_1, \tilde{g}_2

$$0 < \tilde{g}_1 = \liminf_{n \rightarrow \infty} \|\tilde{G}^{-1}(\tilde{\delta}_\varepsilon(n), \tilde{h})\| \leq \overline{\lim}_{n \rightarrow \infty} \|\tilde{G}^{-1}(\tilde{\delta}_\varepsilon(n), \tilde{h})\| = \tilde{g}_2 < \infty, \quad (51)$$

$$0 < \tilde{g}_1 = \liminf_{\varepsilon \rightarrow 0} \|\tilde{G}^{-1}(\tilde{\delta}_\varepsilon(n), \tilde{h})\| \leq \overline{\lim}_{\varepsilon \rightarrow 0} \|\tilde{G}^{-1}(\tilde{\delta}_\varepsilon(n), \tilde{h})\| = \tilde{g}_2 < \infty. \quad (52)$$

From (14), (15), (44), (50) and (51) the finiteness of times $\tilde{\nu}_\varepsilon$ in the periodic case follows.

Thus the finiteness of the stopping times $\tilde{T}(\varepsilon)$ is established.

The property I.1^o of the sequential estimators $(\tilde{T}(\varepsilon), \tilde{\vartheta}(\varepsilon))$ and the strong consistency of the estimators $\hat{\vartheta}_\varepsilon(n)$ may be proved similar to the proof of Theorem 3.1.

Now we find the limiting low and upper bounds for the duration time $\tilde{T}(\varepsilon)$ of our sequential estimation. Put for $k = 1, 2$

$$\tilde{\nu}(k) = \inf\{n \geq 1 : c_n/\kappa_n > \tilde{g}(k)\} - 1,$$

$$\nu^*(k) = \inf\{n \geq 1 : c_n/\kappa_n > g^*(k)\},$$

$$\tilde{g}(1) = g^*(1) = 2f(0)\tilde{\rho}^{1/2}\|\tilde{G}^{-1}(\tilde{h})\|,$$

$$\tilde{g}(2) = \tilde{\rho}^{1/2}\tilde{g}_1e^{-4v_0(1+3\tilde{h})}(1 + e^{2v_0\tilde{h}})\underline{f}_0,$$

$$g^*(2) = \tilde{\rho}^{1/2}\tilde{g}_2e^{-2v_0(2+\tilde{h})}(1 + e^{2v_0\tilde{h}})\bar{f}_0.$$

By the definition of $\tilde{\nu}_\varepsilon$ and from (43), (45), (48), (50), (52) it follows that for ε small enough

– in the stationary case

$$\tilde{\nu}(1) \leq \tilde{\nu}_\varepsilon \leq \nu^*(1); \quad (53)$$

– in the periodic case

$$\tilde{\nu}(2) \leq \tilde{\nu}_\varepsilon \leq \nu^*(2). \quad (54)$$

From (15), (43), (47), (53) and (54) the assertion I.2^o of Theorem 3.2 follows:

– in the stationary case

$$(2f(0))^{-1}c_{\tilde{\nu}(1)} \leq \liminf_{\varepsilon \rightarrow 0} \varepsilon\tilde{T}(\varepsilon) \leq \overline{\lim}_{\varepsilon \rightarrow 0} \varepsilon\tilde{T}(\varepsilon) \leq (2f(0))^{-1}c_{\nu^*(1)} \quad P - \text{a.s.};$$

– in the periodic case

$$\begin{aligned} & 2(1 + 3\tilde{h}) - \frac{1}{2v_0} \ln(1 + e^{2v_0\tilde{h}}) - \frac{1}{2v_0} \ln \bar{f}_0 + \frac{1}{2v_0} \ln c_{\tilde{\nu}(2)} \\ & \leq \liminf_{\varepsilon \rightarrow 0} [\tilde{T}(\varepsilon) - \frac{1}{2v_0} \ln \varepsilon^{-1}] \leq \overline{\lim}_{\varepsilon \rightarrow 0} [\tilde{T}(\varepsilon) - \frac{1}{2v_0} \ln \varepsilon^{-1}] \leq 2 + 7\tilde{h} \\ & - \frac{1}{2v_0} \ln(1 + e^{2v_0\tilde{h}}) - \frac{1}{2v_0} \ln \underline{f}_0 + \frac{1}{2v_0} \ln c_{\nu^*(2)} \quad P - \text{a.s.} \quad \square \end{aligned}$$

Remark 4 It should be pointed out that one could obtain the following limiting equalities for $(i, j) \in I_1$ in Problem I

$$\lim_{\varepsilon \rightarrow 0} \varepsilon\tilde{T}(\varepsilon) = f_{ij0}^{-1}c_{\nu_{ij}^*} \quad P - \text{a.s.}$$

and in stationary case in Problem II

$$\lim_{\varepsilon \rightarrow 0} \varepsilon\tilde{T}(\varepsilon) = (2f(0))^{-1}c_{\nu^*(1)} \quad P - \text{a.s.}$$

if the magnitudes $\rho^{1/2}\varepsilon^{-1}c_n|G_\varepsilon^{-1}(n)|$ and $\tilde{\rho}^{1/2}\varepsilon^{-1}c_n|\tilde{G}_\varepsilon^{-1}(n)|$ in the definitions of ν_ε and $\tilde{\nu}_\varepsilon$ respectively were replaced by the nearest integer from above and the sequences (c_n) and (κ_n) were chosen in such a way that the relation c_n/κ_n were fractional for all $n \geq 1$.

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