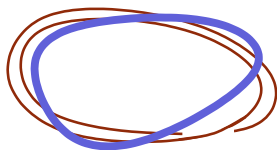


# Equivariant transversality, super-rigidity and all that

Chris Wendl

Humboldt-Universität zu Berlin

April 10, 2020



(slides available at [www.math.hu-berlin.de/~wendl/WesternHemisphere.pdf](http://www.math.hu-berlin.de/~wendl/WesternHemisphere.pdf))

# Motivation

$J$ -holomorphic curves are great!

**Example** (Gromov-McDuff, 1980's):

$u : (S^2, i) \rightarrow (M^4, J)$  with  $[u] \cdot [u] = 1$   
 $(M, \omega)$  minimal

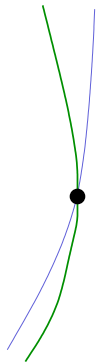


# Motivation

$J$ -holomorphic curves are great!

**Example** (Gromov-McDuff, 1980's):

$u : (S^2, i) \rightarrow (M^4, J)$  with  $[u] \cdot [u] = 1$   
 $(M, \omega)$  minimal

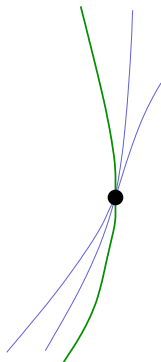


# Motivation

$J$ -holomorphic curves are great!

**Example** (Gromov-McDuff, 1980's):

$u : (S^2, i) \rightarrow (M^4, J)$  with  $[u] \cdot [u] = 1$   
 $(M, \omega)$  minimal

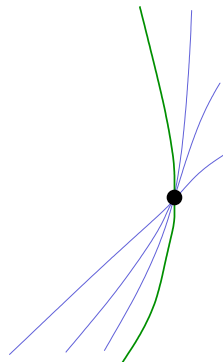


# Motivation

$J$ -holomorphic curves are great!

**Example** (Gromov-McDuff, 1980's):

$u : (S^2, i) \rightarrow (M^4, J)$  with  $[u] \cdot [u] = 1$   
 $(M, \omega)$  minimal

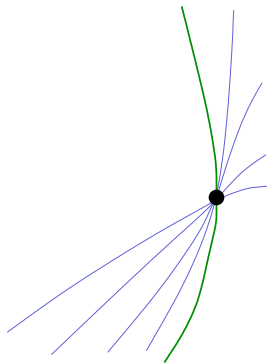


# Motivation

$J$ -holomorphic curves are great!

**Example** (Gromov-McDuff, 1980's):

$u : (S^2, i) \rightarrow (M^4, J)$  with  $[u] \cdot [u] = 1$   
 $(M, \omega)$  minimal

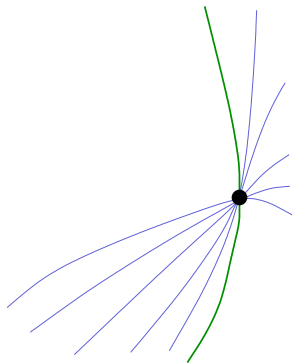


# Motivation

$J$ -holomorphic curves are great!

**Example** (Gromov-McDuff, 1980's):

$u : (S^2, i) \rightarrow (M^4, J)$  with  $[u] \cdot [u] = 1$   
 $(M, \omega)$  minimal

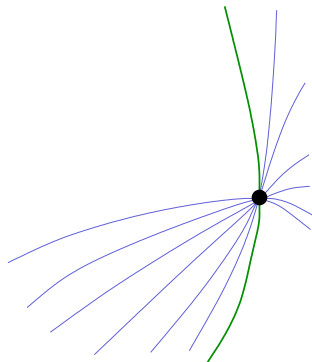


# Motivation

$J$ -holomorphic curves are great!

**Example** (Gromov-McDuff, 1980's):

$u : (S^2, i) \rightarrow (M^4, J)$  with  $[u] \cdot [u] = 1$   
 $(M, \omega)$  minimal



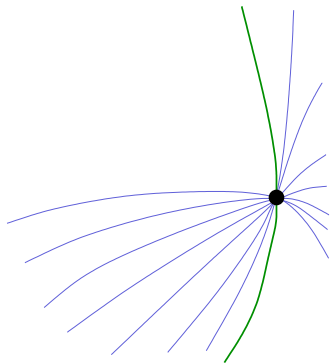


# Motivation

$J$ -holomorphic curves are great!

**Example** (Gromov-McDuff, 1980's):

$u : (S^2, i) \rightarrow (M^4, J)$  with  $[u] \cdot [u] = 1$   
 $(M, \omega)$  minimal

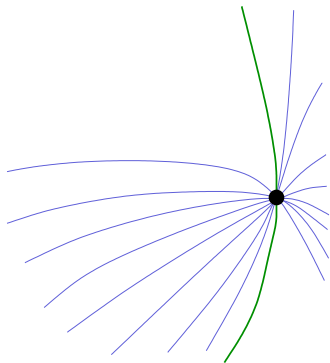


# Motivation

$J$ -holomorphic curves are great!

**Example** (Gromov-McDuff, 1980's):

$u : (S^2, i) \rightarrow (M^4, J)$  with  $[u] \cdot [u] = 1$   
 $(M, \omega)$  minimal

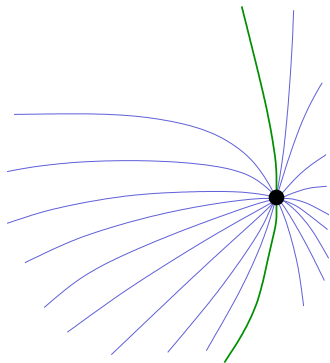


# Motivation

$J$ -holomorphic curves are great!

**Example** (Gromov-McDuff, 1980's):

$u : (S^2, i) \rightarrow (M^4, J)$  with  $[u] \cdot [u] = 1$   
 $(M, \omega)$  minimal

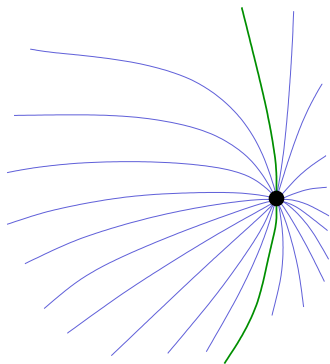


# Motivation

$J$ -holomorphic curves are great!

**Example** (Gromov-McDuff, 1980's):

$u : (S^2, i) \rightarrow (M^4, J)$  with  $[u] \cdot [u] = 1$   
 $(M, \omega)$  minimal

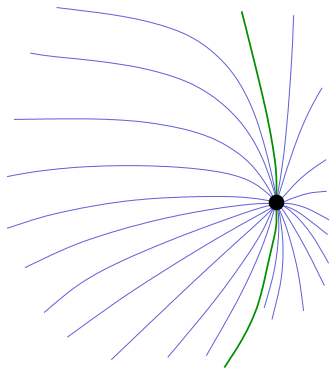


# Motivation

$J$ -holomorphic curves are great!

**Example** (Gromov-McDuff, 1980's):

$u : (S^2, i) \rightarrow (M^4, J)$  with  $[u] \cdot [u] = 1$   
 $(M, \omega)$  minimal



# Motivation

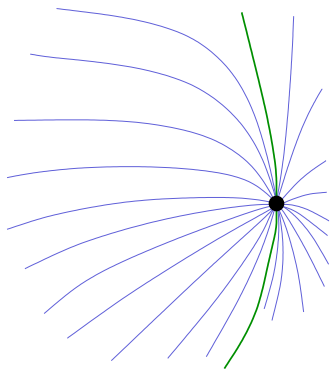
$J$ -holomorphic curves are great!

**Example** (Gromov-McDuff, 1980's):

$u : (S^2, i) \rightarrow (M^4, J)$  with  $[u] \cdot [u] = 1$   
 $(M, \omega)$  minimal

$\Rightarrow$  **Theorem** :  $(M, \omega) \cong (\mathbb{C}P^2, c\omega_{FS})$ .

□



# Motivation

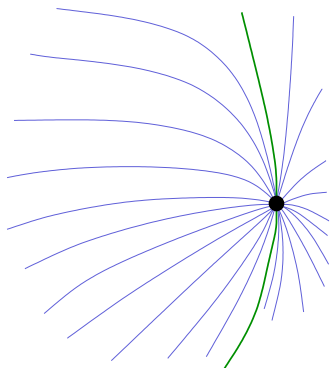
$J$ -holomorphic curves are great!

**Example** (Gromov-McDuff, 1980's):

$u : (S^2, i) \rightarrow (M^4, J)$  with  $[u] \cdot [u] = 1$   
 $(M, \omega)$  minimal

$\Rightarrow$  **Theorem** :  $(M, \omega) \cong (\mathbb{C}P^2, c\omega_{FS})$ .

□



$\mathcal{M}_g(A, J) := \{u : (\Sigma_g, j) \rightarrow (M^{2n}, J) \mid \bar{\partial}_J(u) = 0, [u] = A\} / \text{reparam.}$

is a **compact smooth manifold** of **dimension**  $(n - 3)(2 - 2g) + 2c_1(A)$ .

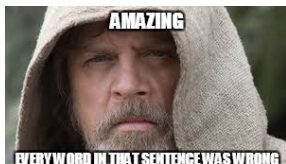
## (De)motivation



$\mathcal{M}_g(A, J) := \{u : (\Sigma_g, j) \rightarrow (M^{2n}, J) \mid \bar{\partial}_J(u) = 0, [u] = A\}$  /reparam.  
is a **compact smooth manifold** of **dimension**  $(n - 3)(2 - 2g) + 2c_1(A)$ .



# (De)motivation



$\mathcal{M}_g(A, J) := \{u : (\Sigma_g, j) \rightarrow (M^{2n}, J) \mid \bar{\partial}_J(u) = 0, [u] = A\} / \text{reparam.}$   
is a **compact smooth manifold** of **dimension**  $(n-3)(2-2g) + 2c_1(A)$ .

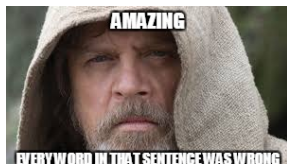
## Bad news

- 1 All  $J$ -holomorphic curves have multiple covers. They have symmetry. ...  $\bar{\partial}_J$  is **equivariant**.
- 2 Forgetting  $J$  generically perturbs by  $\mathbb{Z}/2$ .

$J$ -holomorphic curves are great **terrible!**

I hate them. Let's do combinatorics. (Just kidding.)

# (De)motivation



$\mathcal{M}_g(A, J) := \{u : (\Sigma_g, j) \rightarrow (M^{2n}, J) \mid \bar{\partial}_J(u) = 0, [u] = A\} / \text{reparam.}$   
is a compact **compactifiable smooth manifold** of **dimension**  
 $(n - 3)(2 - 2g) + 2c_1(A)$ .

## Bad news

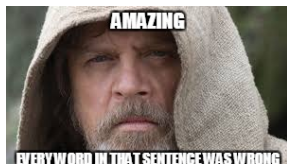
- 1 All  $J$ -holomorphic curves have multiple covers. They have symmetry...  $\bar{\partial}_J$  is **equivariant**.

- 2

$J$ -holomorphic curves are great **terrible!**

I hate them. Let's do combinatorics. (Just kidding.)

# (De)motivation



$\mathcal{M}_g(A, J) := \{u : (\Sigma_g, j) \rightarrow (M^{2n}, J) \mid \bar{\partial}_J(u) = 0, [u] = A\} / \text{reparam.}$   
is a compact **compactifiable smooth manifold** of **dimension**  
 $(n - 3)(2 - 2g) + 2c_1(A)$ .

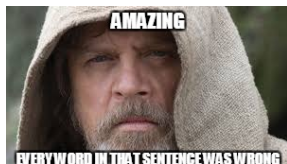
## Bad news

- 1 All  $J$ -holomorphic curves have multiple covers. They have symmetry...  $\bar{\partial}_J$  is **equivariant**.
- 2 Perturbing  $J$  generically perturbs  $\bar{\partial}_J$  **equivariantly**.  
*Equivariant transversality is NOT POSSIBLE.*

$J$ -holomorphic curves are great **terrible!**

I hate them. Let's do combinatorics. (Just kidding.)

# (De)motivation



$\mathcal{M}_g(A, J) := \{u : (\Sigma_g, j) \rightarrow (M^{2n}, J) \mid \bar{\partial}_J(u) = 0, [u] = A\} / \text{reparam.}$   
is a compact **compactifiable smooth** manifold **orbifold** of **dimension**  
 $(n - 3)(2 - 2g) + 2c_1(A)$ .

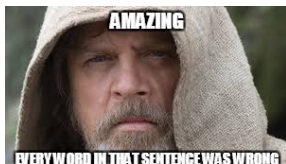
## Bad news

- 1 All  $J$ -holomorphic curves have multiple covers. They have symmetry...  $\bar{\partial}_J$  is **equivariant**.
- 2 Perturbing  $J$  generically perturbs  $\bar{\partial}_J$  **equivariantly**.  
*Equivariant transversality is NOT POSSIBLE.*

$J$ -holomorphic curves are great **terrible!**

I hate them. Let's do combinatorics. (Just kidding.)

# (De)motivation



$\mathcal{M}_g(A, J) := \{u : (\Sigma_g, j) \rightarrow (M^{2n}, J) \mid \bar{\partial}_J(u) = 0, [u] = A\} / \text{reparam.}$   
is a compact **compactifiable smooth** manifold **orbifold** of **dimension**  
 $(n-3)(2-2g) + 2c_1(A)$  **if**  $\bar{\partial}_J \pitchfork 0$ .

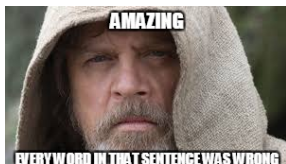
## Bad news

- 1 All  $J$ -holomorphic curves have multiple covers. They have symmetry...  $\bar{\partial}_J$  is **equivariant**.
- 2 Perturbing  $J$  generically perturbs  $\bar{\partial}_J$  **equivariantly**.  
*Equivariant transversality is NOT POSSIBLE.*

$J$ -holomorphic curves are great **terrible!**

I hate them. Let's do combinatorics. (Just kidding.)

# (De)motivation



$\mathcal{M}_g(A, J) := \{u : (\Sigma_g, j) \rightarrow (M^{2n}, J) \mid \bar{\partial}_J(u) = 0, [u] = A\} / \text{reparam.}$   
is a compact **compactifiable smooth** manifold **orbifold** of **dimension**  
 $(n-3)(2-2g) + 2c_1(A)$  **if**  $\bar{\partial}_J \pitchfork 0$ .

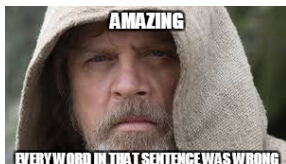
## Bad news

- 1 All  $J$ -holomorphic curves have multiple covers. They have symmetry...  $\bar{\partial}_J$  is **equivariant**.
- 2 Perturbing  $J$  generically perturbs  $\bar{\partial}_J$  **equivariantly**.  
*Equivariant transversality is **NOT POSSIBLE**.*

$J$ -holomorphic curves are great **terrible!**

I hate them. Let's do combinatorics. (Just kidding.)

# (De)motivation



$\mathcal{M}_g(A, J) := \{u : (\Sigma_g, j) \rightarrow (M^{2n}, J) \mid \bar{\partial}_J(u) = 0, [u] = A\} / \text{reparam.}$   
is a compact **compactifiable smooth** manifold **orbifold** of **dimension**  
 $(n-3)(2-2g) + 2c_1(A)$  **if**  $\bar{\partial}_J \pitchfork 0$ .

## Bad news

- 1 All  $J$ -holomorphic curves have multiple covers. They have symmetry...  $\bar{\partial}_J$  is **equivariant**.
- 2 Perturbing  $J$  generically perturbs  $\bar{\partial}_J$  **equivariantly**.  
*Equivariant transversality is* **NOT POSSIBLE**.

$J$ -holomorphic curves are great **terrible!**

I hate them. Let's do combinatorics. (Just kidding.)

# Equivariant transversality is not possible. . . unless it is.

My aim in this talk is to address the following general questions:

- How do we recognize when equivariant transversality is possible?  
*Claim: In many settings, if it is possible, then it holds generically.*
- When it is not possible, why not, and what is true instead?  
(key words: clean intersections, obstruction bundles)
- If I want to apply these ideas to my favorite nonlinear elliptic PDE with symmetry, what do I need to prove?

We will consider three classes of problems as examples:

- 1 The zero-set of a section of a **finite-dimensional orbibundle**\*
- 2 The space of connections on an oriented line field
- 3 The space of maps to a manifold

*(no claim of originality)*



# Equivariant transversality is not possible. . . unless it is.

My aim in this talk is to address the following general questions:

- How do we recognize when equivariant transversality is possible?  
*Claim: In many settings, if it is possible, then it holds generically.*
- When it is not possible, why not, and what is true instead?  
(key words: clean intersections, obstruction bundles)
- If I want to apply these ideas to my favorite nonlinear elliptic PDE with symmetry, what do I need to prove?

We will consider three classes of problems as examples:

- 1 The zero-set of a section of a finite-dimensional orbibundle\*
- 2 The space of solutions of an oriented line field
- 3 The space of solutions of a nonlinear elliptic PDE

\*no obstruction

# Equivariant transversality is not possible. . . unless it is.

My aim in this talk is to address the following general questions:

- How do we recognize when equivariant transversality is possible?  
*Claim: In many settings, if it is possible, then it holds generically.*
- When it is not possible, why not, and what is true instead?  
(key words: clean intersections, obstruction bundles)
- If I want to apply these ideas to my favorite nonlinear elliptic PDE with symmetry, what do I need to prove?

We will consider three classes of problems as examples:

- 1 The zero-set of a section of a finite-dimensional orbibundle\*
- 2 The space of solutions of an elliptic PDE
- 3 The space of solutions of a nonlinear elliptic PDE

\*no compactness

# Equivariant transversality is not possible. . . unless it is.

My aim in this talk is to address the following general questions:

- How do we recognize when equivariant transversality is possible?  
*Claim: In many settings, if it is possible, then it holds generically.*
- When it is not possible, why not, and what is true instead?  
(key words: **clean intersections**, **obstruction bundles**)
- If I want to apply these ideas to my favorite nonlinear elliptic PDE with symmetry, what do I need to prove?

We will consider three classes of problems as examples:

- 1 The zero-set of a section of a **finite-dimensional orbibundle**\*
- 2 The space of closed curves of a given length
- 3 The space of closed curves of a given length

*\*no claim of originality*

# Equivariant transversality is not possible. . . unless it is.

My aim in this talk is to address the following general questions:

- How do we recognize when equivariant transversality is possible?  
*Claim: In many settings, if it is possible, then it holds generically.*
- When it is not possible, why not, and what is true instead?  
(key words: **clean intersections**, **obstruction bundles**)
- If I want to apply these ideas to my favorite nonlinear elliptic PDE with symmetry, what do I need to prove?

We will consider three classes of problems as examples:

- 1 The zero-set of a section of a **finite-dimensional orbibundle**\*
- 2 The space of closed orbits of an oriented line field\*
- 3

\*no claim of originality

# Equivariant transversality is not possible. . . unless it is.

My aim in this talk is to address the following general questions:

- How do we recognize when equivariant transversality is possible?  
*Claim: In many settings, if it is possible, then it holds generically.*
- When it is not possible, why not, and what is true instead?  
(key words: **clean intersections**, **obstruction bundles**)
- If I want to apply these ideas to my favorite nonlinear elliptic PDE with symmetry, what do I need to prove?

We will consider three classes of problems as examples:

- 1 The zero-set of a section of a **finite-dimensional orbibundle**\*
- 2 The space of **closed orbits** of an oriented line field\*
- 3 The moduli space of  **$J$ -holomorphic curves**

\* *no claim of originality*

## Acknowledgements:

Several ideas were inspired by C. Taubes ("Counting..." JDG 1996), and also some recent work by A. Doan and T. Walpuski.

# Equivariant transversality is not possible. . . unless it is.

My aim in this talk is to address the following general questions:

- How do we recognize when equivariant transversality is possible?  
*Claim: In many settings, if it is possible, then it holds generically.*
- When it is not possible, why not, and what is true instead?  
(key words: **clean intersections**, **obstruction bundles**)
- If I want to apply these ideas to my favorite nonlinear elliptic PDE with symmetry, what do I need to prove?

We will consider three classes of problems as examples:

- 1 The zero-set of a section of a **finite-dimensional orbibundle**\*
- 2 The space of **closed orbits** of an oriented line field\*
- 3 The moduli space of  **$J$ -holomorphic curves**

\* *no claim of originality*

## Acknowledgements:

Several ideas were inspired by C. Taubes ("Counting. . ." JDG 1996), and also some recent work by A. Doan and T. Walpuski.

# Equivariant transversality is not possible. . . unless it is.

My aim in this talk is to address the following general questions:

- How do we recognize when equivariant transversality is possible?  
*Claim: In many settings, if it is possible, then it holds generically.*
- When it is not possible, why not, and what is true instead?  
(key words: **clean intersections**, **obstruction bundles**)
- If I want to apply these ideas to my favorite nonlinear elliptic PDE with symmetry, what do I need to prove?

We will consider three classes of problems as examples:

- ① The zero-set of a section of a **finite-dimensional orbibundle**\*
- ② The space of **closed orbits** of an oriented line field\*
- ③ The moduli space of  **$J$ -holomorphic curves**

\* *no claim of originality*

## Acknowledgements:

Several ideas were inspired by C. Taubes ("Counting. . ." JDG 1996), and also some recent work by A. Doan and T. Walpuski.

# Equivariant transversality is not possible. . . unless it is.

My aim in this talk is to address the following general questions:

- How do we recognize when equivariant transversality is possible?  
*Claim: In many settings, if it is possible, then it holds generically.*
- When it is not possible, why not, and what is true instead?  
(key words: **clean intersections**, **obstruction bundles**)
- If I want to apply these ideas to my favorite nonlinear elliptic PDE with symmetry, what do I need to prove?

We will consider three classes of problems as examples:

- 1 The zero-set of a section of a **finite-dimensional orbibundle**\*
- 2 The space of **closed orbits** of an oriented line field\*
- 3 The moduli space of  **$J$ -holomorphic curves**

\* *no claim of originality*

## Acknowledgements:

Several ideas were inspired by C. Taubes (“Counting. . .” JDG 1996), and also some recent work by A. Doan and T. Walpuski.



# Problem 1: Finite dimensions

$M$  a compact  $n$ -dimensional orbifold,  $E \rightarrow M$  an orbibundle of rank  $m$ .

## Question

For generic  $\sigma \in \Gamma(E)$ , is  $\sigma^{-1}(0) \subset M$  a **suborbifold** of dimension  $n - m$ ? Does  $\sigma \pitchfork 0$  hold generically? **Answer:** Typically not.

## Local example

Call  $\sigma : \mathbb{R}^2 \rightarrow \mathbb{R}^2$   **$\mathbb{Z}_2$ -equivariant** if  $\sigma(x, -y) = -\sigma(x, y)$ . Then  $\sigma^{-1}(0)$  is **never** 0-dimensional, e.g. it contains  $\mathbb{R} \times \{0\}$ .

**Next best thing** (“Morse-Bott” condition):

Say  $\sigma \in \Gamma(E)$  intersects zero **cleanly** if all components  $\mathcal{M}_i \subset \sigma^{-1}(0)$  are **suborbifolds** (of dimensions  $\geq n - m$ ) with  $T_x \mathcal{M}_i = \ker D\sigma(x)$ .

We can then compute the Euler number of  $E$  via **obstruction bundles**:

$$\langle e(E), [M] \rangle = \sum_i \langle e(\mathcal{O}b_i), \mathcal{M}_i \rangle, \quad \mathcal{O}b_x := \text{coker } D\sigma(x).$$

## Problem 1: Finite dimensions

$M$  a compact  $n$ -dimensional orbifold,  $E \rightarrow M$  an orbibundle of rank  $m$ .

### Question

For generic  $\sigma \in \Gamma(E)$ , is  $\sigma^{-1}(0) \subset M$  a **suborbifold** of dimension  $n - m$ ?  
Does  $\sigma \pitchfork 0$  hold generically? **Answer:** Typically not.

### Local example

Call  $\sigma : \mathbb{R}^2 \rightarrow \mathbb{R}^2$   **$\mathbb{Z}_2$ -equivariant** if  $\sigma(x, -y) = -\sigma(x, y)$ .  
Then  $\sigma^{-1}(0)$  is **never** 0-dimensional, e.g. it contains  $\mathbb{R} \times \{0\}$ .

**Next best thing** (“Morse-Bott” condition):

Say  $\sigma \in \Gamma(E)$  intersects zero **cleanly** if all components  $\mathcal{M}_i \subset \sigma^{-1}(0)$  are **suborbifolds** (of dimensions  $\geq n - m$ ) with  $T_x \mathcal{M}_i = \ker D\sigma(x)$ .

We can then compute the Euler number of  $E$  via **obstruction bundles**:

$$\langle e(E), [M] \rangle = \sum_i \langle e(\mathcal{O}b_i), \mathcal{M}_i \rangle, \quad \mathcal{O}b_x := \text{coker } D\sigma(x).$$

# Problem 1: Finite dimensions

$M$  a compact  $n$ -dimensional orbifold,  $E \rightarrow M$  an orbibundle of rank  $m$ .

## Question

For generic  $\sigma \in \Gamma(E)$ , is  $\sigma^{-1}(0) \subset M$  a **suborbifold** of dimension  $n - m$ ? Does  $\sigma \pitchfork 0$  hold generically? **Answer:** Typically not.

## Local example

Call  $\sigma : \mathbb{R}^2 \rightarrow \mathbb{R}^2$   **$\mathbb{Z}_2$ -equivariant** if  $\sigma(x, -y) = -\sigma(x, y)$ . Then  $\sigma^{-1}(0)$  is **never** 0-dimensional, e.g. it contains  $\mathbb{R} \times \{0\}$ .

**Next best thing** (“Morse-Bott” condition):

Say  $\sigma \in \Gamma(E)$  intersects zero **cleanly** if all components  $\mathcal{M}_i \subset \sigma^{-1}(0)$  are **suborbifolds** (of dimensions  $\geq n - m$ ) with  $T_x \mathcal{M}_i = \ker D\sigma(x)$ .

We can then compute the Euler number of  $E$  via **obstruction bundles**:

$$\langle e(E), [M] \rangle = \sum_i \langle e(\mathcal{O}b_i), \mathcal{M}_i \rangle, \quad \mathcal{O}b_x := \text{coker } D\sigma(x).$$

## Problem 1: Finite dimensions

$M$  a compact  $n$ -dimensional orbifold,  $E \rightarrow M$  an orbibundle of rank  $m$ .

### Question

For generic  $\sigma \in \Gamma(E)$ , is  $\sigma^{-1}(0) \subset M$  a **suborbifold** of dimension  $n - m$ ? Does  $\sigma \pitchfork 0$  hold generically? **Answer:** Typically not.

### Local example

Call  $\sigma : \mathbb{R}^2 \rightarrow \mathbb{R}^2$   **$\mathbb{Z}_2$ -equivariant** if  $\sigma(x, -y) = -\sigma(x, y)$ . Then  $\sigma^{-1}(0)$  is **never** 0-dimensional, e.g. it contains  $\mathbb{R} \times \{0\}$ .

Next best thing (“Morse-Bott” condition):

Say  $\sigma \in \Gamma(E)$  intersects zero **cleanly** if all components  $\mathcal{M}_i \subset \sigma^{-1}(0)$  are **suborbifolds** (of dimensions  $\geq n - m$ ) with  $T_x \mathcal{M}_i = \ker D\sigma(x)$ .

We can then compute the Euler number of  $E$  via **obstruction bundles**:

$$\langle e(E), [M] \rangle = \sum_i \langle e(\mathcal{O}b_i), \mathcal{M}_i \rangle, \quad \mathcal{O}b_x := \text{coker } D\sigma(x).$$

## Problem 1: Finite dimensions

$M$  a compact  $n$ -dimensional orbifold,  $E \rightarrow M$  an orbibundle of rank  $m$ .

### Question

For generic  $\sigma \in \Gamma(E)$ , is  $\sigma^{-1}(0) \subset M$  a **suborbifold** of dimension  $n - m$ ? Does  $\sigma \pitchfork 0$  hold generically? **Answer:** Typically not.

### Local example

Call  $\sigma : \mathbb{R}^2 \rightarrow \mathbb{R}^2$   **$\mathbb{Z}_2$ -equivariant** if  $\sigma(x, -y) = -\sigma(x, y)$ . Then  $\sigma^{-1}(0)$  is **never** 0-dimensional, e.g. it contains  $\mathbb{R} \times \{0\}$ .

**Next best thing** (“Morse-Bott” condition):

Say  $\sigma \in \Gamma(E)$  intersects zero **cleanly** if all components  $\mathcal{M}_i \subset \sigma^{-1}(0)$  are **suborbifolds** (of dimensions  $\geq n - m$ ) with  $T_x \mathcal{M}_i = \ker D\sigma(x)$ .

We can then compute the Euler number of  $E$  via **obstruction bundles**:

$$\langle e(E), [M] \rangle = \sum_i \langle e(\mathcal{O}b_i), \mathcal{M}_i \rangle, \quad \mathcal{O}b_x := \text{coker } D\sigma(x).$$

## Problem 1: Finite dimensions

$M$  a compact  $n$ -dimensional orbifold,  $E \rightarrow M$  an orbibundle of rank  $m$ .

### Question

For generic  $\sigma \in \Gamma(E)$ , is  $\sigma^{-1}(0) \subset M$  a **suborbifold** of dimension  $n - m$ ? Does  $\sigma \pitchfork 0$  hold generically? **Answer:** Typically not.

### Local example

Call  $\sigma : \mathbb{R}^2 \rightarrow \mathbb{R}^2$   **$\mathbb{Z}_2$ -equivariant** if  $\sigma(x, -y) = -\sigma(x, y)$ . Then  $\sigma^{-1}(0)$  is **never** 0-dimensional, e.g. it contains  $\mathbb{R} \times \{0\}$ .

**Next best thing** (“Morse-Bott” condition):

Say  $\sigma \in \Gamma(E)$  intersects zero **cleanly** if all components  $\mathcal{M}_i \subset \sigma^{-1}(0)$  are **suborbifolds** (of dimensions  $\geq n - m$ ) with  $T_x \mathcal{M}_i = \ker D\sigma(x)$ .

We can then compute the Euler number of  $E$  via **obstruction bundles**:

$$\langle e(E), [M] \rangle = \sum_i \langle e(\mathcal{O}b_i), \mathcal{M}_i \rangle, \quad \mathcal{O}b_x := \text{coker } D\sigma(x).$$

# Problem 1: Finite dimensions

## Sample theorem 1.A

If  $\dim M = \text{rank } E$  and isotropy groups satisfy  $|G_x| \leq 3$  for all  $x$ , then generic sections of  $E$  intersect zero **cleanly**.

**Key observation** behind the proof (to be discussed):

$\mathbb{Z}_2$  and  $\mathbb{Z}_3$  each have **only two real irreducible representations**.

## Sample theorem 1.B (cf. Wasserman '69, Hepworth '09)

Generic smooth functions on an orbifold are **Morse**.

**Key observation** behind the proof (to be discussed):

**Self-adjoint** Fredholm operators (e.g. Hessians) always have **index 0**.

# Problem 1: Finite dimensions

## Sample theorem 1.A

If  $\dim M = \text{rank } E$  and isotropy groups satisfy  $|G_x| \leq 3$  for all  $x$ , then generic sections of  $E$  intersect zero **cleanly**.

**Key observation** behind the proof (to be discussed):

$\mathbb{Z}_2$  and  $\mathbb{Z}_3$  each have **only two real irreducible representations**.

## Sample theorem 1.B (cf. Wasserman '69, Hepworth '09)

Generic smooth functions on an orbifold are **Morse**.

**Key observation** behind the proof (to be discussed):

**Self-adjoint** Fredholm operators (e.g. Hessians) always have **index 0**.



# Problem 1: Finite dimensions

## Sample theorem 1.A

If  $\dim M = \text{rank } E$  and isotropy groups satisfy  $|G_x| \leq 3$  for all  $x$ , then generic sections of  $E$  intersect zero **cleanly**.

**Key observation** behind the proof (to be discussed):

$\mathbb{Z}_2$  and  $\mathbb{Z}_3$  each have **only two real irreducible representations**.

## Sample theorem 1.B (cf. Wasserman '69, Hepworth '09)

Generic smooth functions on an orbifold are **Morse**.

**Key observation** behind the proof (to be discussed):

**Self-adjoint** Fredholm operators (e.g. Hessians) always have **index 0**.

# Problem 1: Finite dimensions

## Sample theorem 1.A

If  $\dim M = \text{rank } E$  and isotropy groups satisfy  $|G_x| \leq 3$  for all  $x$ , then generic sections of  $E$  intersect zero **cleanly**.

**Key observation** behind the proof (to be discussed):

$\mathbb{Z}_2$  and  $\mathbb{Z}_3$  each have **only two real irreducible representations**.

## Sample theorem 1.B (cf. Wasserman '69, Hepworth '09)

Generic smooth functions on an orbifold are **Morse**.

**Key observation** behind the proof (to be discussed):

**Self-adjoint** Fredholm operators (e.g. Hessians) always have **index 0**.

## Problem 2: Closed orbits

For an **oriented line field**  $\ell \subset TM$  generated by  $R \in \mathfrak{X}(M)$ , we consider the moduli space of **closed orbits**

$$\mathcal{M}(\ell) := \{\gamma : S^1 \looparrowright M \mid \dot{\gamma} \in \ell\} / \text{Diff}(S^1) \cong \sigma_R^{-1}(0) / S^1,$$

where

$$(0, \infty) \times H^1(S^1, M) \xrightarrow{\sigma_R} \mathcal{E} \\ (\tau, \gamma) \longmapsto \dot{\gamma} - \tau R(\gamma)$$

is an  $S^1$ -**equivariant** smooth section of a **Hilbert space bundle**  $\mathcal{E} \rightarrow (0, \infty) \times H^1(S^1, M)$  with fibers  $\mathcal{E}_{(\tau, \gamma)} = L^2(\gamma^*TM)$ .

Each  $d$ -**fold covered** orbit  $\gamma \in \mathcal{M}(\ell)$  has **isotropy group**  $\mathbb{Z}_d$ . We call  $\gamma$  **nondegenerate** if  $\sigma \pitchfork 0$  at  $\gamma$ .

### Sample theorem 2.A

For generic line fields  $\ell$ , all orbits in  $\mathcal{M}(\ell)$  are **nondegenerate**, thus  $\mathcal{M}(\ell)$  is a **0-manifold**.

## Problem 2: Closed orbits

For an **oriented line field**  $\ell \subset TM$  generated by  $R \in \mathfrak{X}(M)$ , we consider the moduli space of **closed orbits**

$$\mathcal{M}(\ell) := \{ \gamma : S^1 \looparrowright M \mid \dot{\gamma} \in \ell \} / \text{Diff}(S^1) \cong \sigma_R^{-1}(0) / S^1,$$

where

$$\begin{aligned} (0, \infty) \times H^1(S^1, M) &\xrightarrow{\sigma_R} \mathcal{E} \\ (\tau, \gamma) &\longmapsto \dot{\gamma} - \tau R(\gamma) \end{aligned}$$

is an  $S^1$ -**equivariant** smooth section of a **Hilbert space bundle**  $\mathcal{E} \rightarrow (0, \infty) \times H^1(S^1, M)$  with fibers  $\mathcal{E}_{(\tau, \gamma)} = L^2(\gamma^*TM)$ .

Each  $d$ -**fold covered** orbit  $\gamma \in \mathcal{M}(\ell)$  has **isotropy group**  $\mathbb{Z}_d$ .  
We call  $\gamma$  **nondegenerate** if  $\sigma \pitchfork 0$  at  $\gamma$ .

### Sample theorem 2.A

For generic line fields  $\ell$ , all orbits in  $\mathcal{M}(\ell)$  are **nondegenerate**, thus  $\mathcal{M}(\ell)$  is a **0-manifold**.

## Problem 2: Closed orbits

For an **oriented line field**  $\ell \subset TM$  generated by  $R \in \mathfrak{X}(M)$ , we consider the moduli space of **closed orbits**

$$\mathcal{M}(\ell) := \{ \gamma : S^1 \looparrowright M \mid \dot{\gamma} \in \ell \} / \text{Diff}(S^1) \cong \sigma_R^{-1}(0) / S^1,$$

where

$$(0, \infty) \times H^1(S^1, M) \xrightarrow{\sigma_R} \mathcal{E} \\ (\tau, \gamma) \longmapsto \dot{\gamma} - \tau R(\gamma)$$

is an  **$S^1$ -equivariant** smooth section of a **Hilbert space bundle**  $\mathcal{E} \rightarrow (0, \infty) \times H^1(S^1, M)$  with fibers  $\mathcal{E}_{(\tau, \gamma)} = L^2(\gamma^*TM)$ .

Each  **$d$ -fold covered** orbit  $\gamma \in \mathcal{M}(\ell)$  has **isotropy group**  $\mathbb{Z}_d$ .

We call  $\gamma$  **nondegenerate** if  $\sigma \pitchfork 0$  at  $\gamma$ .

### Sample theorem 2.A

For generic line fields  $\ell$ , all orbits in  $\mathcal{M}(\ell)$  are **nondegenerate**, thus  $\mathcal{M}(\ell)$  is a **0-manifold**.

## Problem 2: Closed orbits

For an **oriented line field**  $\ell \subset TM$  generated by  $R \in \mathfrak{X}(M)$ , we consider the moduli space of **closed orbits**

$$\mathcal{M}(\ell) := \{ \gamma : S^1 \looparrowright M \mid \dot{\gamma} \in \ell \} / \text{Diff}(S^1) \cong \sigma_R^{-1}(0) / S^1,$$

where

$$\begin{aligned} (0, \infty) \times H^1(S^1, M) &\xrightarrow{\sigma_R} \mathcal{E} \\ (\tau, \gamma) &\longmapsto \dot{\gamma} - \tau R(\gamma) \end{aligned}$$

is an  **$S^1$ -equivariant** smooth section of a **Hilbert space bundle**  $\mathcal{E} \rightarrow (0, \infty) \times H^1(S^1, M)$  with fibers  $\mathcal{E}_{(\tau, \gamma)} = L^2(\gamma^*TM)$ .

Each  **$d$ -fold covered** orbit  $\gamma \in \mathcal{M}(\ell)$  has **isotropy group**  $\mathbb{Z}_d$ . We call  $\gamma$  **nondegenerate** if  $\sigma \pitchfork 0$  at  $\gamma$ .

### Sample theorem 2.A

For generic line fields  $\ell$ , all orbits in  $\mathcal{M}(\ell)$  are **nondegenerate**, thus  $\mathcal{M}(\ell)$  is a **0-manifold**.

## Problem 2: Closed orbits

For an **oriented line field**  $\ell \subset TM$  generated by  $R \in \mathfrak{X}(M)$ , we consider the moduli space of **closed orbits**

$$\mathcal{M}(\ell) := \{ \gamma : S^1 \looparrowright M \mid \dot{\gamma} \in \ell \} / \text{Diff}(S^1) \cong \sigma_R^{-1}(0) / S^1,$$

where

$$\begin{aligned} (0, \infty) \times H^1(S^1, M) &\xrightarrow{\sigma_R} \mathcal{E} \\ (\tau, \gamma) &\longmapsto \dot{\gamma} - \tau R(\gamma) \end{aligned}$$

is an  $S^1$ -**equivariant** smooth section of a **Hilbert space bundle**  $\mathcal{E} \rightarrow (0, \infty) \times H^1(S^1, M)$  with fibers  $\mathcal{E}_{(\tau, \gamma)} = L^2(\gamma^*TM)$ .

Each  $d$ -**fold covered** orbit  $\gamma \in \mathcal{M}(\ell)$  has **isotropy group**  $\mathbb{Z}_d$ . We call  $\gamma$  **nondegenerate** if  $\sigma \pitchfork 0$  at  $\gamma$ .

### Sample theorem 2.A

For generic line fields  $\ell$ , all orbits in  $\mathcal{M}(\ell)$  are **nondegenerate**, thus  $\mathcal{M}(\ell)$  is a **0-manifold**.

## Problem 2: Closed orbits

**Question:** What can happen to orbits under deformations  $\{\ell_s\}_{s \in [0,1]}$ ?



## Problem 2: Closed orbits

**Question:** What can happen to orbits under deformations  $\{\ell_s\}_{s \in [0,1]}$ ?

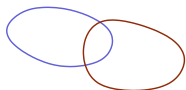
(1) **Birth-death** bifurcations:



## Problem 2: Closed orbits

**Question:** What can happen to orbits under deformations  $\{\ell_s\}_{s \in [0,1]}$ ?

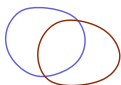
(1) **Birth-death** bifurcations:



## Problem 2: Closed orbits

**Question:** What can happen to orbits under deformations  $\{\ell_s\}_{s \in [0,1]}$ ?

(1) **Birth-death** bifurcations:



## Problem 2: Closed orbits

**Question:** What can happen to orbits under deformations  $\{\ell_s\}_{s \in [0,1]}$ ?

(1) **Birth-death** bifurcations:



## Problem 2: Closed orbits

**Question:** What can happen to orbits under deformations  $\{\ell_s\}_{s \in [0,1]}$ ?

(1) **Birth-death** bifurcations:



## Problem 2: Closed orbits

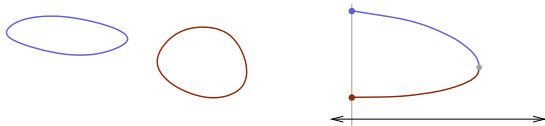
**Question:** What can happen to orbits under deformations  $\{\ell_s\}_{s \in [0,1]}$ ?

(1) **Birth-death** bifurcations:

## Problem 2: Closed orbits

**Question:** What can happen to orbits under deformations  $\{\ell_s\}_{s \in [0,1]}$ ?

(1) **Birth-death** bifurcations:

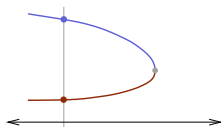
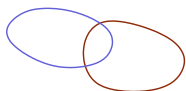


$$\mathcal{M}(\{\ell_s\}) := \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

## Problem 2: Closed orbits

**Question:** What can happen to orbits under deformations  $\{\ell_s\}_{s \in [0,1]}$ ?

(1) **Birth-death** bifurcations:



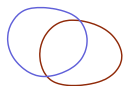
$$\mathcal{M}(\{\ell_s\}) := \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$



## Problem 2: Closed orbits

**Question:** What can happen to orbits under deformations  $\{\ell_s\}_{s \in [0,1]}$ ?

(1) **Birth-death** bifurcations:

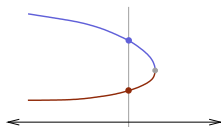


$$\mathcal{M}(\{\ell_s\}) := \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

## Problem 2: Closed orbits

**Question:** What can happen to orbits under deformations  $\{\ell_s\}_{s \in [0,1]}$ ?

(1) **Birth-death** bifurcations:

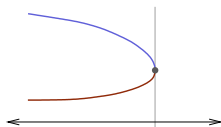


$$\mathcal{M}(\{\ell_s\}) := \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

## Problem 2: Closed orbits

**Question:** What can happen to orbits under deformations  $\{\ell_s\}_{s \in [0,1]}$ ?

(1) **Birth-death** bifurcations:

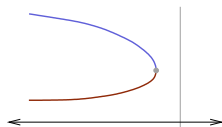


$$\mathcal{M}(\{\ell_s\}) := \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

## Problem 2: Closed orbits

**Question:** What can happen to orbits under deformations  $\{\ell_s\}_{s \in [0,1]}$ ?

(1) **Birth-death** bifurcations:



$$\mathcal{M}(\{\ell_s\}) := \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

## Problem 2: Closed orbits

**Question:** What can happen to orbits under deformations  $\{\ell_s\}_{s \in [0,1]}$ ?

(1) **Birth-death** bifurcations:

$$\mathcal{M}(\{\ell_s\}) := \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

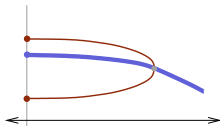
## Problem 2: Closed orbits

**Question:** What can happen to orbits under deformations  $\{\ell_s\}_{s \in [0,1]}$ ?

(1) **Birth-death** bifurcations:

$$\mathcal{M}(\{\ell_s\}) := \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

(2) **Period-doubling** bifurcations:



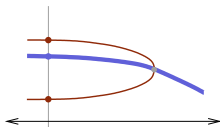
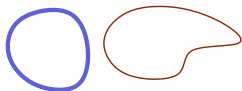
## Problem 2: Closed orbits

**Question:** What can happen to orbits under deformations  $\{\ell_s\}_{s \in [0,1]}$ ?

(1) **Birth-death** bifurcations:

$$\mathcal{M}(\{\ell_s\}) := \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

(2) **Period-doubling** bifurcations:



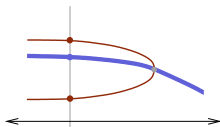
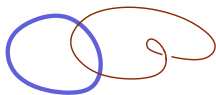
## Problem 2: Closed orbits

**Question:** What can happen to orbits under deformations  $\{\ell_s\}_{s \in [0,1]}$ ?

(1) **Birth-death** bifurcations:

$$\mathcal{M}(\{\ell_s\}) := \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

(2) **Period-doubling** bifurcations:





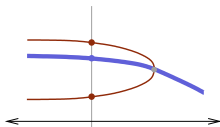
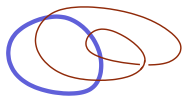
## Problem 2: Closed orbits

**Question:** What can happen to orbits under deformations  $\{\ell_s\}_{s \in [0,1]}$ ?

(1) **Birth-death** bifurcations:

$$\mathcal{M}(\{\ell_s\}) := \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

(2) **Period-doubling** bifurcations:



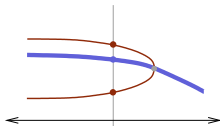
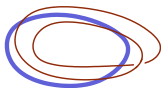
## Problem 2: Closed orbits

**Question:** What can happen to orbits under deformations  $\{\ell_s\}_{s \in [0,1]}$ ?

(1) **Birth-death** bifurcations:

$$\mathcal{M}(\{\ell_s\}) := \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

(2) **Period-doubling** bifurcations:



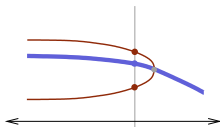
## Problem 2: Closed orbits

**Question:** What can happen to orbits under deformations  $\{\ell_s\}_{s \in [0,1]}$ ?

(1) **Birth-death** bifurcations:

$$\mathcal{M}(\{\ell_s\}) := \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

(2) **Period-doubling** bifurcations:



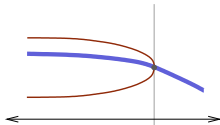
## Problem 2: Closed orbits

**Question:** What can happen to orbits under deformations  $\{\ell_s\}_{s \in [0,1]}$ ?

(1) **Birth-death** bifurcations:

$$\mathcal{M}(\{\ell_s\}) := \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

(2) **Period-doubling** bifurcations:



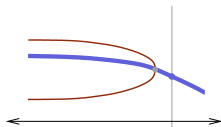
## Problem 2: Closed orbits

**Question:** What can happen to orbits under deformations  $\{\ell_s\}_{s \in [0,1]}$ ?

(1) **Birth-death** bifurcations:

$$\mathcal{M}(\{\ell_s\}) := \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

(2) **Period-doubling** bifurcations:



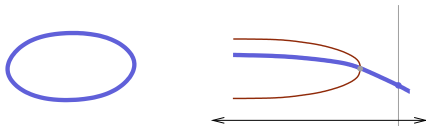
## Problem 2: Closed orbits

**Question:** What can happen to orbits under deformations  $\{\ell_s\}_{s \in [0,1]}$ ?

(1) **Birth-death** bifurcations:

$$\mathcal{M}(\{\ell_s\}) := \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

(2) **Period-doubling** bifurcations:



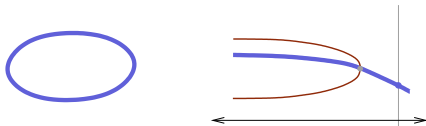
## Problem 2: Closed orbits

**Question:** What can happen to orbits under deformations  $\{\ell_s\}_{s \in [0,1]}$ ?

(1) **Birth-death** bifurcations:

$$\mathcal{M}(\{\ell_s\}) := \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

(2) **Period-doubling** bifurcations:



### Sample theorem 2.B

For generic deformations, **birth-death** and **period-doubling** are the **only** bifurcations.

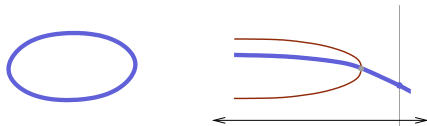
## Problem 2: Closed orbits

**Question:** What can happen to orbits under deformations  $\{\ell_s\}_{s \in [0,1]}$ ?

(1) **Birth-death** bifurcations:

$$\mathcal{M}(\{\ell_s\}) := \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

(2) **Period-doubling** bifurcations:



### Sample theorem 2.B

For generic deformations, **birth-death** and **period-doubling** are the **only** bifurcations. (i.e. “walls” of codimension 1 come in two types)



## Problem 2: Closed orbits

### Sample theorem 2.B

There is only **birth-death** and **period-doubling** for generic  $\{\ell_s\}_{s \in [0,1]}$ .

**Remark 1:** If the  $\ell_s$  are also **geodesible**, then components of  $\mathcal{M}(\{\ell_s\})$  are **compact up to period-doubling**, i.e. **no blue sky catastrophes**.

In the **Hamiltonian case** ( $\ell_s = \ker \omega_s$  for  $\omega_s \in \Omega^2(M)$  of maximal rank), geodesible  $\Leftrightarrow$  **stabilizable**.

**Remark 2:** But  $\{\ell_s = \ker \omega_s\}$  also has **higher-degree bifurcations**.  
(see e.g. Abraham-Marsden, Chapter 8)

## Problem 2: Closed orbits

### Sample theorem 2.B

There is only **birth-death** and **period-doubling** for generic  $\{\ell_s\}_{s \in [0,1]}$ .

**Remark 1:** If the  $\ell_s$  are also **geodesible**, then components of  $\mathcal{M}(\{\ell_s\})$  are **compact up to period-doubling**, i.e. **no blue sky catastrophes**.

In the **Hamiltonian case** ( $\ell_s = \ker \omega_s$  for  $\omega_s \in \Omega^2(M)$  of maximal rank), geodesible  $\Leftrightarrow$  **stabilizable**.

**Remark 2:** But  $\{\ell_s = \ker \omega_s\}$  also has **higher-degree bifurcations**.  
(see e.g. Abraham-Marsden, Chapter 8)

## Problem 2: Closed orbits

### Sample theorem 2.B

There is only **birth-death** and **period-doubling** for generic  $\{\ell_s\}_{s \in [0,1]}$ .

**Remark 1:** If the  $\ell_s$  are also **geodesible**, then components of  $\mathcal{M}(\{\ell_s\})$  are **compact up to period-doubling**, i.e. **no blue sky catastrophes**.

In the **Hamiltonian case** ( $\ell_s = \ker \omega_s$  for  $\omega_s \in \Omega^2(M)$  of maximal rank), geodesible  $\Leftrightarrow$  **stabilizable**.

**Remark 2:** But  $\{\ell_s = \ker \omega_s\}$  also has **higher-degree bifurcations**.  
(see e.g. Abraham-Marsden, Chapter 8)

## Problem 3: Holomorphic curves

Fix a  $2n$ -dimensional symplectic manifold  $(M, \omega)$  and consider compatible almost complex structures  $J$ .

### Theorem 3.A (W. '16–'19)

If  $(M, \omega)$  is a **symplectic Calabi-Yau 3-fold** ( $\dim M = 6$ ,  $c_1(M, \omega) = 0$ ) and  $J$  is generic, then  $\bar{\partial}_J$  intersects the zero-section **cleanly**, i.e. all simple curves are **super-rigid**.

**Corollary:** Gromov-Witten invariants of  $(M, \omega)$  are finite sums of Euler numbers of well-defined obstruction bundles. □

### Theorem 3.B (W. '16–'19)

If  $\dim M \geq 4$  and  $J$  is generic, all **unbranched covers** of simple  $J$ -holomorphic curves are **cut out transversely**.

**Precedent** (Taubes '96):

Doubly covered tori in the definition of the Gromov invariant.

## Problem 3: Holomorphic curves

Fix a  $2n$ -dimensional symplectic manifold  $(M, \omega)$  and consider compatible almost complex structures  $J$ .

### Theorem 3.A (W. '16-'19)

If  $(M, \omega)$  is a **symplectic Calabi-Yau 3-fold** ( $\dim M = 6$ ,  $c_1(M, \omega) = 0$ ) and  $J$  is generic, then  $\bar{\partial}_J$  intersects the zero-section **cleanly**, i.e. all simple curves are **super-rigid**.

**Corollary:** Gromov-Witten invariants of  $(M, \omega)$  are finite sums of Euler numbers of well-defined obstruction bundles. □

### Theorem 3.B (W. '16-'19)

If  $\dim M \geq 4$  and  $J$  is generic, all **unbranched covers** of simple  $J$ -holomorphic curves are **cut out transversely**.

**Precedent** (Taubes '96):

Doubly covered tori in the definition of the Gromov invariant.

## Problem 3: Holomorphic curves

Fix a  $2n$ -dimensional symplectic manifold  $(M, \omega)$  and consider compatible almost complex structures  $J$ .

### Theorem 3.A (W. '16-'19)

If  $(M, \omega)$  is a **symplectic Calabi-Yau 3-fold** ( $\dim M = 6$ ,  $c_1(M, \omega) = 0$ ) and  $J$  is generic, then  $\bar{\partial}_J$  intersects the zero-section **cleanly**, i.e. all simple curves are **super-rigid**.

**Corollary:** Gromov-Witten invariants of  $(M, \omega)$  are finite sums of Euler numbers of well-defined obstruction bundles. □

### Theorem 3.B (W. '16-'19)

If  $\dim M \geq 4$  and  $J$  is generic, all **unbranched covers** of simple  $J$ -holomorphic curves are **cut out transversely**.

**Precedent** (Taubes '96):

Doubly covered tori in the definition of the Gromov invariant.

## Problem 3: Holomorphic curves

Fix a  $2n$ -dimensional symplectic manifold  $(M, \omega)$  and consider compatible almost complex structures  $J$ .

### Theorem 3.A (W. '16-'19)

If  $(M, \omega)$  is a **symplectic Calabi-Yau 3-fold** ( $\dim M = 6$ ,  $c_1(M, \omega) = 0$ ) and  $J$  is generic, then  $\bar{\partial}_J$  intersects the zero-section **cleanly**, i.e. all simple curves are **super-rigid**.

**Corollary:** Gromov-Witten invariants of  $(M, \omega)$  are finite sums of Euler numbers of well-defined obstruction bundles. □

### Theorem 3.B (W. '16-'19)

If  $\dim M \geq 4$  and  $J$  is generic, all **unbranched covers** of simple  $J$ -holomorphic curves are **cut out transversely**.

**Precedent** (Taubes '96):

Doubly covered tori in the definition of the Gromov invariant.

## Problem 3: Holomorphic curves

Fix a  $2n$ -dimensional symplectic manifold  $(M, \omega)$  and consider compatible almost complex structures  $J$ .

### Theorem 3.A (W. '16-'19)

If  $(M, \omega)$  is a **symplectic Calabi-Yau 3-fold** ( $\dim M = 6$ ,  $c_1(M, \omega) = 0$ ) and  $J$  is generic, then  $\bar{\partial}_J$  intersects the zero-section **cleanly**, i.e. all simple curves are **super-rigid**.

**Corollary:** Gromov-Witten invariants of  $(M, \omega)$  are finite sums of Euler numbers of well-defined obstruction bundles. □

### Theorem 3.B (W. '16-'19)

If  $\dim M \geq 4$  and  $J$  is generic, all **unbranched covers** of simple  $J$ -holomorphic curves are **cut out transversely**.

**Precedent** (Taubes '96):

Doubly covered tori in the definition of the Gromov invariant.



# Paradigm

Each of our problems involves a **moduli space**  $\mathcal{M}(\sigma)$  defined via geometric data  $\sigma$ , such that to every  $x \in \mathcal{M}(\sigma)$  corresponds:

- A **finite symmetry group**  $G_x$ , which is **trivial** on a subset  $\mathcal{M}^*(\sigma) \subset \mathcal{M}(\sigma)$  for which transversality holds generically.
- A **Fredholm operator**  $D_x$ , which is **surjective** if and only if **transversality** holds at  $x$ .

Here is the general strategy

- **Isosymmetric strata** (easy):  
Decompose  $\mathcal{M}(\sigma)$  into subsets  $\mathcal{M}^G(\sigma) \subset \mathcal{M}(\sigma)$  on which  $G_x$  is constant. For generic  $\sigma$ , these are **submanifolds**.
- **Walls** (the technical part):  
**Stratify** each  $\mathcal{M}^G(\sigma)$  further into submanifolds on which  $\ker D_x$  and  $\operatorname{coker} D_x$  vary smoothly (i.e. **constant dimensions**).
- **Splitting** (mainly representation theory):  
 $D_x \cong \bigoplus_{\theta} D_x^{\theta}$  for the real irreducible representations  $\theta$  of  $G_x$ .  
**Compute indices**. . . the rest is **dimension counting!**

# Paradigm

Each of our problems involves a **moduli space**  $\mathcal{M}(\sigma)$  defined via geometric data  $\sigma$ , such that to every  $x \in \mathcal{M}(\sigma)$  corresponds:

- A **finite symmetry group**  $G_x$ , which is **trivial** on a subset  $\mathcal{M}^*(\sigma) \subset \mathcal{M}(\sigma)$  for which transversality holds generically.
- A **Fredholm operator**  $D_x$ , which is **surjective** if and only if **transversality** holds at  $x$ .

Here is the general strategy

- **Isosymmetric strata** (easy):  
Decompose  $\mathcal{M}(\sigma)$  into subsets  $\mathcal{M}^G(\sigma) \subset \mathcal{M}(\sigma)$  on which  $G_x$  is constant. For generic  $\sigma$ , these are **submanifolds**.
- **Walls** (the technical part):  
**Stratify** each  $\mathcal{M}^G(\sigma)$  further into submanifolds on which  $\ker D_x$  and  $\operatorname{coker} D_x$  vary smoothly (i.e. **constant dimensions**).
- **Splitting** (mainly representation theory):  
 $D_x \cong \bigoplus_{\theta} D_x^{\theta}$  for the real irreducible representations  $\theta$  of  $G_x$ .  
**Compute indices**. . . the rest is **dimension counting!**

# Paradigm

Each of our problems involves a **moduli space**  $\mathcal{M}(\sigma)$  defined via geometric data  $\sigma$ , such that to every  $x \in \mathcal{M}(\sigma)$  corresponds:

- A **finite symmetry group**  $G_x$ , which is **trivial** on a subset  $\mathcal{M}^*(\sigma) \subset \mathcal{M}(\sigma)$  for which transversality holds generically.
- A **Fredholm operator**  $\mathbf{D}_x$ , which is **surjective** if and only if **transversality** holds at  $x$ .

Here is the general strategy

- 1 **Isosymmetric strata** (easy):  
Decompose  $\mathcal{M}(\sigma)$  into subsets  $\mathcal{M}^G(\sigma) \subset \mathcal{M}(\sigma)$  on which  $G_x$  is constant. For generic  $\sigma$ , these are **submanifolds**.
- 2 **Walls** (the technical part):  
**Stratify** each  $\mathcal{M}^G(\sigma)$  further into submanifolds on which  $\ker \mathbf{D}_x$  and  $\operatorname{coker} \mathbf{D}_x$  vary smoothly (i.e. **constant dimensions**).
- 3 **Splitting** (mainly representation theory):  
 $\mathbf{D}_x \cong \bigoplus_{\theta} \mathbf{D}_x^{\theta}$  for the real irreducible representations  $\theta$  of  $G_x$ .  
**Compute indices**. . . the rest is **dimension counting!**

# Paradigm

Each of our problems involves a **moduli space**  $\mathcal{M}(\sigma)$  defined via geometric data  $\sigma$ , such that to every  $x \in \mathcal{M}(\sigma)$  corresponds:

- A **finite symmetry group**  $G_x$ , which is **trivial** on a subset  $\mathcal{M}^*(\sigma) \subset \mathcal{M}(\sigma)$  for which transversality holds generically.
- A **Fredholm operator**  $D_x$ , which is **surjective** if and only if **transversality** holds at  $x$ .

Here is the general strategy

① **Isosymmetric strata** (easy):

Decompose  $\mathcal{M}(\sigma)$  into subsets  $\mathcal{M}^G(\sigma) \subset \mathcal{M}(\sigma)$  on which  $G_x$  is constant. For generic  $\sigma$ , these are **submanifolds**.

② **Walls** (the technical part):

**Stratify** each  $\mathcal{M}^G(\sigma)$  further into submanifolds on which  $\ker D_x$  and  $\operatorname{coker} D_x$  vary smoothly (i.e. **constant dimensions**).

③ **Splitting** (mainly representation theory):

$D_x \cong \bigoplus_{\theta} D_x^{\theta}$  for the real irreducible representations  $\theta$  of  $G_x$ .

**Compute indices**. . . the rest is **dimension counting!**

# Paradigm

Each of our problems involves a **moduli space**  $\mathcal{M}(\sigma)$  defined via geometric data  $\sigma$ , such that to every  $x \in \mathcal{M}(\sigma)$  corresponds:

- A **finite symmetry group**  $G_x$ , which is **trivial** on a subset  $\mathcal{M}^*(\sigma) \subset \mathcal{M}(\sigma)$  for which transversality holds generically.
- A **Fredholm operator**  $\mathbf{D}_x$ , which is **surjective** if and only if **transversality** holds at  $x$ .

Here is the general strategy

① **Isosymmetric strata** (easy):

Decompose  $\mathcal{M}(\sigma)$  into subsets  $\mathcal{M}^G(\sigma) \subset \mathcal{M}(\sigma)$  on which  $G_x$  is constant. For generic  $\sigma$ , these are **submanifolds**.

② **Walls** (the technical part):

**Stratify** each  $\mathcal{M}^G(\sigma)$  further into submanifolds on which  $\ker \mathbf{D}_x$  and  $\operatorname{coker} \mathbf{D}_x$  vary smoothly (i.e. **constant dimensions**).

③ **Splitting** (mainly representation theory):

$\mathbf{D}_x \cong \bigoplus_{\theta} \mathbf{D}_x^{\theta}$  for the real irreducible representations  $\theta$  of  $G_x$ .

**Compute indices**. . . the rest is **dimension counting!**

# Paradigm

Each of our problems involves a **moduli space**  $\mathcal{M}(\sigma)$  defined via geometric data  $\sigma$ , such that to every  $x \in \mathcal{M}(\sigma)$  corresponds:

- A **finite symmetry group**  $G_x$ , which is **trivial** on a subset  $\mathcal{M}^*(\sigma) \subset \mathcal{M}(\sigma)$  for which transversality holds generically.
- A **Fredholm operator**  $\mathbf{D}_x$ , which is **surjective** if and only if **transversality** holds at  $x$ .

Here is the general strategy

① **Isosymmetric strata** (easy):

Decompose  $\mathcal{M}(\sigma)$  into subsets  $\mathcal{M}^G(\sigma) \subset \mathcal{M}(\sigma)$  on which  $G_x$  is constant. For generic  $\sigma$ , these are **submanifolds**.

② **Walls** (the technical part):

**Stratify** each  $\mathcal{M}^G(\sigma)$  further into submanifolds on which  $\ker \mathbf{D}_x$  and  $\operatorname{coker} \mathbf{D}_x$  vary smoothly (i.e. **constant dimensions**).

③ **Splitting** (mainly representation theory):

$\mathbf{D}_x \cong \bigoplus_{\theta} \mathbf{D}_x^{\theta}$  for the real irreducible representations  $\theta$  of  $G_x$ .

**Compute indices**. . . the rest is **dimension counting!**

## Problem 1 (finite dimensions): Isosymmetric strata

Given  $\sigma \in \Gamma(E)$ , write  $\mathcal{M}(\sigma) := \sigma^{-1}(0) \subset M$ .

For each finite group  $G$ , define

$$M^G := \{x \in M \mid G_x \cong G\},$$

and

$$\mathcal{M}^G(\sigma) := \mathcal{M}(\sigma) \cap M^G.$$

Key observations:

- 1  $M^G \subset M$  is a smooth submanifold.
- 2  $\sigma^G := \sigma|_{M^G} : M^G \rightarrow E$  takes values in a distinguished subbundle

$$E^G := \{v \in E_x \mid x \in M^G \text{ and } g \cdot v = v \text{ for all } g \in G_x\}.$$

Exercise (via the Sard-Smale theorem)

For every  $G$  and generic  $\sigma \in \Gamma(E)$ ,  $\sigma^G$  is **transverse** to the zero-section of  $E^G$ . In particular,  $\mathcal{M}^G(\sigma)$  is a **smooth manifold**. □

## Problem 1 (finite dimensions): Isosymmetric strata

Given  $\sigma \in \Gamma(E)$ , write  $\mathcal{M}(\sigma) := \sigma^{-1}(0) \subset M$ .

For each finite group  $G$ , define

$$M^G := \{x \in M \mid G_x \cong G\},$$

and

$$\mathcal{M}^G(\sigma) := \mathcal{M}(\sigma) \cap M^G.$$

Key observations:

- 1  $M^G \subset M$  is a smooth submanifold.
- 2  $\sigma^G := \sigma|_{M^G} : M^G \rightarrow E$  takes values in a distinguished subbundle

$$E^G := \{v \in E_x \mid x \in M^G \text{ and } g \cdot v = v \text{ for all } g \in G_x\}.$$

Exercise (via the Sard-Smale theorem)

For every  $G$  and generic  $\sigma \in \Gamma(E)$ ,  $\sigma^G$  is **transverse** to the zero-section of  $E^G$ . In particular,  $\mathcal{M}^G(\sigma)$  is a **smooth manifold**. □



## Problem 1 (finite dimensions): Isosymmetric strata

Given  $\sigma \in \Gamma(E)$ , write  $\mathcal{M}(\sigma) := \sigma^{-1}(0) \subset M$ .

For each finite group  $G$ , define

$$M^G := \{x \in M \mid G_x \cong G\},$$

and

$$\mathcal{M}^G(\sigma) := \mathcal{M}(\sigma) \cap M^G.$$

Key observations:

- 1  $M^G \subset M$  is a smooth submanifold.
- 2  $\sigma^G := \sigma|_{M^G} : M^G \rightarrow E$  takes values in a distinguished subbundle

$$E^G := \{v \in E_x \mid x \in M^G \text{ and } g \cdot v = v \text{ for all } g \in G_x\}.$$

Exercise (via the Sard-Smale theorem)

For every  $G$  and generic  $\sigma \in \Gamma(E)$ ,  $\sigma^G$  is **transverse** to the zero-section of  $E^G$ . In particular,  $\mathcal{M}^G(\sigma)$  is a **smooth manifold**. □

## Problem 1 (finite dimensions): Isosymmetric strata

Given  $\sigma \in \Gamma(E)$ , write  $\mathcal{M}(\sigma) := \sigma^{-1}(0) \subset M$ .

For each finite group  $G$ , define

$$M^G := \{x \in M \mid G_x \cong G\},$$

and

$$\mathcal{M}^G(\sigma) := \mathcal{M}(\sigma) \cap M^G.$$

Key observations:

- 1  $M^G \subset M$  is a smooth submanifold.
- 2  $\sigma^G := \sigma|_{M^G} : M^G \rightarrow E$  takes values in a distinguished subbundle

$$E^G := \{v \in E_x \mid x \in M^G \text{ and } g \cdot v = v \text{ for all } g \in G_x\}.$$

### Exercise (via the Sard-Smale theorem)

For every  $G$  and generic  $\sigma \in \Gamma(E)$ ,  $\sigma^G$  is **transverse** to the zero-section of  $E^G$ . In particular,  $\mathcal{M}^G(\sigma)$  is a **smooth manifold**. □

# Problem 1 (finite dimensions): Walls

At each  $x \in \mathcal{M}^G(\sigma)$ , there is a **linearization**

$$\mathbf{D}_x := D\sigma(x) \in \text{Hom}_G(T_x M, E_x).$$

For integers  $k, c \geq 0$ , define

$$\mathcal{M}^G(\sigma; k, c) := \{x \in \mathcal{M}^G(\sigma) \mid \dim \ker \mathbf{D}_x = k \text{ and } \dim \text{coker } \mathbf{D}_x = c\}.$$

Key observations:

- 1 Every Fredholm operator  $\mathbf{T}_0 : X \rightarrow Y$  admits a neighborhood  $\mathcal{O} \subset \mathcal{L}(X, Y)$  and smooth map  $\Phi : \mathcal{O} \rightarrow \text{Hom}(\ker \mathbf{T}_0, \text{coker } \mathbf{T}_0)$  s.t.  $\Phi(\mathbf{T}) = 0 \Leftrightarrow \dim \ker \mathbf{T} = \dim \ker \mathbf{T}_0, \dim \text{coker } \mathbf{T} = \dim \text{coker } \mathbf{T}_0$ .
- 2 In the present setting, all operators are  $G$ -equivariant.

Stratification theorem (via IFT and Sard-Smale)

For all  $G, k, c$  and generic  $\sigma \in \Gamma(E)$ ,  $\mathcal{M}^G(\sigma; k, c) \subset \mathcal{M}^G(\sigma)$  is a **smooth submanifold** whose codimension near  $x \in \mathcal{M}^G(\sigma; k, c)$  is  $\dim \text{Hom}_G(\ker \mathbf{D}_x, \text{coker } \mathbf{D}_x)$ . □

# Problem 1 (finite dimensions): Walls

At each  $x \in \mathcal{M}^G(\sigma)$ , there is a **linearization**

$$\mathbf{D}_x := D\sigma(x) \in \text{Hom}_G(T_x M, E_x).$$

For integers  $k, c \geq 0$ , define

$$\mathcal{M}^G(\sigma; k, c) := \{x \in \mathcal{M}^G(\sigma) \mid \dim \ker \mathbf{D}_x = k \text{ and } \dim \text{coker } \mathbf{D}_x = c\}.$$

Key observations:

- 1 Every Fredholm operator  $\mathbf{T}_0 : X \rightarrow Y$  admits a neighborhood  $\mathcal{O} \subset \mathcal{L}(X, Y)$  and smooth map  $\Phi : \mathcal{O} \rightarrow \text{Hom}(\ker \mathbf{T}_0, \text{coker } \mathbf{T}_0)$  s.t.  $\Phi(\mathbf{T}) = 0 \Leftrightarrow \dim \ker \mathbf{T} = \dim \ker \mathbf{T}_0, \dim \text{coker } \mathbf{T} = \dim \text{coker } \mathbf{T}_0$ .
- 2 In the present setting, all operators are  $G$ -equivariant.

Stratification theorem (via IFT and Sard-Smale)

For all  $G, k, c$  and generic  $\sigma \in \Gamma(E)$ ,  $\mathcal{M}^G(\sigma; k, c) \subset \mathcal{M}^G(\sigma)$  is a **smooth submanifold** whose codimension near  $x \in \mathcal{M}^G(\sigma; k, c)$  is  $\dim \text{Hom}_G(\ker \mathbf{D}_x, \text{coker } \mathbf{D}_x)$ . □

# Problem 1 (finite dimensions): Walls

At each  $x \in \mathcal{M}^G(\sigma)$ , there is a **linearization**

$$\mathbf{D}_x := D\sigma(x) \in \text{Hom}_G(T_x M, E_x).$$

For integers  $k, c \geq 0$ , define

$$\mathcal{M}^G(\sigma; k, c) := \{x \in \mathcal{M}^G(\sigma) \mid \dim \ker \mathbf{D}_x = k \text{ and } \dim \text{coker } \mathbf{D}_x = c\}.$$

Key observations:

- 1 Every Fredholm operator  $\mathbf{T}_0 : X \rightarrow Y$  admits a neighborhood  $\mathcal{O} \subset \mathcal{L}(X, Y)$  and smooth map  $\Phi : \mathcal{O} \rightarrow \text{Hom}(\ker \mathbf{T}_0, \text{coker } \mathbf{T}_0)$  s.t.  $\Phi(\mathbf{T}) = 0 \Leftrightarrow \dim \ker \mathbf{T} = \dim \ker \mathbf{T}_0, \dim \text{coker } \mathbf{T} = \dim \text{coker } \mathbf{T}_0$ .
- 2 In the present setting, all operators are  $G$ -equivariant.

Stratification theorem (via IFT and Sard-Smale)

For all  $G, k, c$  and generic  $\sigma \in \Gamma(E)$ ,  $\mathcal{M}^G(\sigma; k, c) \subset \mathcal{M}^G(\sigma)$  is a **smooth submanifold** whose codimension near  $x \in \mathcal{M}^G(\sigma; k, c)$  is  $\dim \text{Hom}_G(\ker \mathbf{D}_x, \text{coker } \mathbf{D}_x)$ . □

# Problem 1 (finite dimensions): Walls

At each  $x \in \mathcal{M}^G(\sigma)$ , there is a **linearization**

$$\mathbf{D}_x := D\sigma(x) \in \text{Hom}_G(T_x M, E_x).$$

For integers  $k, c \geq 0$ , define

$$\mathcal{M}^G(\sigma; k, c) := \{x \in \mathcal{M}^G(\sigma) \mid \dim \ker \mathbf{D}_x = k \text{ and } \dim \text{coker } \mathbf{D}_x = c\}.$$

Key observations:

- 1 Every Fredholm operator  $\mathbf{T}_0 : X \rightarrow Y$  admits a neighborhood  $\mathcal{O} \subset \mathcal{L}(X, Y)$  and smooth map  $\Phi : \mathcal{O} \rightarrow \text{Hom}(\ker \mathbf{T}_0, \text{coker } \mathbf{T}_0)$  s.t.  $\Phi(\mathbf{T}) = 0 \Leftrightarrow \dim \ker \mathbf{T} = \dim \ker \mathbf{T}_0, \dim \text{coker } \mathbf{T} = \dim \text{coker } \mathbf{T}_0$ .
- 2 In the present setting, all operators are  $G$ -equivariant.

Stratification theorem (via IFT and Sard-Smale)

For all  $G, k, c$  and generic  $\sigma \in \Gamma(E)$ ,  $\mathcal{M}^G(\sigma; k, c) \subset \mathcal{M}^G(\sigma)$  is a **smooth submanifold** whose codimension near  $x \in \mathcal{M}^G(\sigma; k, c)$  is  $\dim \text{Hom}_G(\ker \mathbf{D}_x, \text{coker } \mathbf{D}_x)$ . □

## Problem 1 (finite dimensions): Walls

At each  $x \in \mathcal{M}^G(\sigma)$ , there is a **linearization**

$$\mathbf{D}_x := D\sigma(x) \in \text{Hom}_G(T_x M, E_x).$$

For integers  $k, c \geq 0$ , define

$$\mathcal{M}^G(\sigma; k, c) := \{x \in \mathcal{M}^G(\sigma) \mid \dim \ker \mathbf{D}_x = k \text{ and } \dim \text{coker } \mathbf{D}_x = c\}.$$

Key observations:

- 1 Every Fredholm operator  $\mathbf{T}_0 : X \rightarrow Y$  admits a neighborhood  $\mathcal{O} \subset \mathcal{L}(X, Y)$  and smooth map  $\Phi : \mathcal{O} \rightarrow \text{Hom}(\ker \mathbf{T}_0, \text{coker } \mathbf{T}_0)$  s.t.  $\Phi(\mathbf{T}) = 0 \Leftrightarrow \dim \ker \mathbf{T} = \dim \ker \mathbf{T}_0, \dim \text{coker } \mathbf{T} = \dim \text{coker } \mathbf{T}_0$ .
- 2 In the present setting, all operators are  $G$ -equivariant.

### Stratification theorem (via IFT and Sard-Smale)

For all  $G, k, c$  and generic  $\sigma \in \Gamma(E)$ ,  $\mathcal{M}^G(\sigma; k, c) \subset \mathcal{M}^G(\sigma)$  is a **smooth submanifold** whose codimension near  $x \in \mathcal{M}^G(\sigma; k, c)$  is  $\dim \text{Hom}_G(\ker \mathbf{D}_x, \text{coker } \mathbf{D}_x)$ . □

## Problem 1 (finite dimensions): Splitting

Let  $\{\theta_i : G \rightarrow \text{Aut}_{\mathbb{R}}(W_i)\}_{i=1}^N$  denote the **real irreducible representations** of  $G$ , with  $\theta_1$  as the trivial representation.

Since  $\mathbf{D}_x : T_x M \rightarrow E_x$  is  $G_x$ -**equivariant**, Schur's lemma implies that it splits with respect to the **isotypic decompositions**  $T_x M = \bigoplus_{i=1}^N T_x M^i$  and  $E_x = \bigoplus_{i=1}^N E_x^i$ , giving

$$\mathbf{D}_x = \mathbf{D}_x^1 \oplus \dots \oplus \mathbf{D}_x^N, \quad \text{where} \quad \mathbf{D}_x^i : T_x M^i \rightarrow E_x^i.$$

Key observations:

- 1  $\mathbf{D}_x^1 = D\sigma^G(x)$ , so it is surjective and  $\ker \mathbf{D}_x^1 = T_x \mathcal{M}^G(\sigma)$ .
- 2  $\sigma \pitchfork 0$  at  $x \Leftrightarrow \mathbf{D}_x^i$  **surjective** for all  $i = 1, \dots, N$ .  
**Impossible** unless  $\text{ind } \mathbf{D}_x^i \geq 0 \forall i$ ; could fail even if  $\text{ind } \mathbf{D}_x \geq 0$ .
- 3 If  $\mathbf{D}_x^i$  **injective** for all  $i \geq 2$ , then  $\sigma$  intersects  $0$  **cleanly** at  $x$ .



## Problem 1 (finite dimensions): Splitting

Let  $\{\theta_i : G \rightarrow \text{Aut}_{\mathbb{R}}(W_i)\}_{i=1}^N$  denote the **real irreducible representations** of  $G$ , with  $\theta_1$  as the trivial representation.

Since  $\mathbf{D}_x : T_x M \rightarrow E_x$  is  $G_x$ -**equivariant**, Schur's lemma implies that it splits with respect to the **isotypic decompositions**  $T_x M = \bigoplus_{i=1}^N T_x M^i$  and  $E_x = \bigoplus_{i=1}^N E_x^i$ , giving

$$\mathbf{D}_x = \mathbf{D}_x^1 \oplus \dots \oplus \mathbf{D}_x^N, \quad \text{where} \quad \mathbf{D}_x^i : T_x M^i \rightarrow E_x^i.$$

Key observations:

- 1  $\mathbf{D}_x^1 = D\sigma^G(x)$ , so it is surjective and  $\ker \mathbf{D}_x^1 = T_x \mathcal{M}^G(\sigma)$ .
- 2  $\sigma \pitchfork 0$  at  $x \Leftrightarrow \mathbf{D}_x^i$  **surjective** for all  $i = 1, \dots, N$ .  
**Impossible** unless  $\text{ind } \mathbf{D}_x^i \geq 0 \forall i$ ; could fail even if  $\text{ind } \mathbf{D}_x \geq 0$ .
- 3 If  $\mathbf{D}_x^i$  **injective** for all  $i \geq 2$ , then  $\sigma$  intersects  $0$  **cleanly** at  $x$ .

## Problem 1 (finite dimensions): Splitting

Let  $\{\theta_i : G \rightarrow \text{Aut}_{\mathbb{R}}(W_i)\}_{i=1}^N$  denote the **real irreducible representations** of  $G$ , with  $\theta_1$  as the trivial representation.

Since  $\mathbf{D}_x : T_x M \rightarrow E_x$  is  $G_x$ -**equivariant**, Schur's lemma implies that it splits with respect to the **isotypic decompositions**  $T_x M = \bigoplus_{i=1}^N T_x M^i$  and  $E_x = \bigoplus_{i=1}^N E_x^i$ , giving

$$\mathbf{D}_x = \mathbf{D}_x^1 \oplus \dots \oplus \mathbf{D}_x^N, \quad \text{where} \quad \mathbf{D}_x^i : T_x M^i \rightarrow E_x^i.$$

Key observations:

- 1  $\mathbf{D}_x^1 = D\sigma^G(x)$ , so it is surjective and  $\ker \mathbf{D}_x^1 = T_x \mathcal{M}^G(\sigma)$ .
- 2  $\sigma \pitchfork 0$  at  $x \Leftrightarrow \mathbf{D}_x^i$  **surjective** for all  $i = 1, \dots, N$ .  
**Impossible** unless  $\text{ind } \mathbf{D}_x^i \geq 0 \forall i$ ; could fail even if  $\text{ind } \mathbf{D}_x \geq 0$ .
- 3 If  $\mathbf{D}_x^i$  **injective** for all  $i \geq 2$ , then  $\sigma$  intersects 0 **cleanly** at  $x$ .

## Problem 1 (finite dimensions): Splitting

Let  $\{\theta_i : G \rightarrow \text{Aut}_{\mathbb{R}}(W_i)\}_{i=1}^N$  denote the **real irreducible representations** of  $G$ , with  $\theta_1$  as the trivial representation.

Since  $\mathbf{D}_x : T_x M \rightarrow E_x$  is  $G_x$ -**equivariant**, Schur's lemma implies that it splits with respect to the **isotypic decompositions**  $T_x M = \bigoplus_{i=1}^N T_x M^i$  and  $E_x = \bigoplus_{i=1}^N E_x^i$ , giving

$$\mathbf{D}_x = \mathbf{D}_x^1 \oplus \dots \oplus \mathbf{D}_x^N, \quad \text{where} \quad \mathbf{D}_x^i : T_x M^i \rightarrow E_x^i.$$

Key observations:

- 1  $\mathbf{D}_x^1 = D\sigma^G(x)$ , so it is surjective and  $\ker \mathbf{D}_x^1 = T_x \mathcal{M}^G(\sigma)$ .
- 2  $\sigma \pitchfork 0$  at  $x \Leftrightarrow \mathbf{D}_x^i$  **surjective** for all  $i = 1, \dots, N$ .  
**Impossible** unless  $\text{ind } \mathbf{D}_x^i \geq 0 \ \forall i$ ; could fail even if  $\text{ind } \mathbf{D}_x \geq 0$ .
- 3 If  $\mathbf{D}_x^i$  **injective** for all  $i \geq 2$ , then  $\sigma$  intersects  $0$  **cleanly** at  $x$ .

## Problem 1 (finite dimensions): Splitting

Let  $\{\theta_i : G \rightarrow \text{Aut}_{\mathbb{R}}(W_i)\}_{i=1}^N$  denote the **real irreducible representations** of  $G$ , with  $\theta_1$  as the trivial representation.

Since  $\mathbf{D}_x : T_x M \rightarrow E_x$  is  $G_x$ -**equivariant**, Schur's lemma implies that it splits with respect to the **isotypic decompositions**  $T_x M = \bigoplus_{i=1}^N T_x M^i$  and  $E_x = \bigoplus_{i=1}^N E_x^i$ , giving

$$\mathbf{D}_x = \mathbf{D}_x^1 \oplus \dots \oplus \mathbf{D}_x^N, \quad \text{where} \quad \mathbf{D}_x^i : T_x M^i \rightarrow E_x^i.$$

Key observations:

- 1  $\mathbf{D}_x^1 = D\sigma^G(x)$ , so it is surjective and  $\ker \mathbf{D}_x^1 = T_x \mathcal{M}^G(\sigma)$ .
- 2  $\sigma \pitchfork 0$  at  $x \Leftrightarrow \mathbf{D}_x^i$  **surjective** for all  $i = 1, \dots, N$ .  
**Impossible** unless  $\text{ind } \mathbf{D}_x^i \geq 0 \forall i$ ; could fail even if  $\text{ind } \mathbf{D}_x \geq 0$ .
- 3 If  $\mathbf{D}_x^i$  **injective** for all  $i \geq 2$ , then  $\sigma$  intersects 0 **cleanly** at  $x$ .

# Problem 1 (finite dimensions): Proofs

## Corollary (of stratification)

For generic  $\sigma$ , if  $\mathcal{M}_i \subset \mathcal{M}^G(\sigma)$  is a component whose points  $x \in \mathcal{M}_i$  satisfy  $\text{ind } \mathbf{D}_x^i \geq 0$  for all  $i$ , then  $\sigma \pitchfork 0$  on an **open dense** subset of  $\mathcal{M}_i$ . Similarly for **clean intersections** if  $\text{ind } \mathbf{D}^i \leq 0$  for  $i \geq 2$ .  $\square$

## Proof of Theorem 1.B (Morse functions):

We consider  $E := T^*M$  and  $df \in \Gamma(E)$  and need to show  $df \pitchfork 0$  for generic  $f : M \rightarrow \mathbb{R}$ . **Two new features:**

- 1 For  $x \in df^{-1}(0)$ ,  $\mathbf{D}_x := D(df)(x)$  is always **symmetric**, so the previous codimension formula changes to

$$\text{codim } \mathcal{M}^G(df; k, c) = \dim \text{End}_G^{\text{sym}}(\ker \mathbf{D}_x)$$

which is generally **smaller**, but still **positive**.

- 2 Every  $\mathbf{D}_x^i$  is self-adjoint, thus  $\text{ind } \mathbf{D}_x^i = 0$ .

Then all strata  $\mathcal{M}^G(df)$  are **0-dimensional**. Non-Morse critical points live in walls  $\mathcal{M}^G(df; k, c)$ , which have **negative dimension**  $\Rightarrow$  empty.  $\square$

# Problem 1 (finite dimensions): Proofs

## Corollary (of stratification)

For generic  $\sigma$ , if  $\mathcal{M}_i \subset \mathcal{M}^G(\sigma)$  is a component whose points  $x \in \mathcal{M}_i$  satisfy  $\text{ind } \mathbf{D}_x^i \geq 0$  for all  $i$ , then  $\sigma \pitchfork 0$  on an **open dense** subset of  $\mathcal{M}_i$ . Similarly for **clean intersections** if  $\text{ind } \mathbf{D}^i \leq 0$  for  $i \geq 2$ .  $\square$

## Proof of Theorem 1.B (Morse functions):

We consider  $E := T^*M$  and  $df \in \Gamma(E)$  and need to show  $df \pitchfork 0$  for generic  $f : M \rightarrow \mathbb{R}$ . **Two new features:**

- 1 For  $x \in df^{-1}(0)$ ,  $\mathbf{D}_x := D(df)(x)$  is always **symmetric**, so the previous codimension formula changes to

$$\text{codim } \mathcal{M}^G(df; k, c) = \dim \text{End}_G^{\text{sym}}(\ker \mathbf{D}_x)$$

which is generally **smaller**, but still **positive**.

- 2 Every  $\mathbf{D}_x^i$  is self-adjoint, thus  $\text{ind } \mathbf{D}_x^i = 0$ .

Then all strata  $\mathcal{M}^G(df)$  are **0-dimensional**. Non-Morse critical points live in walls  $\mathcal{M}^G(df; k, c)$ , which have **negative dimension**  $\Rightarrow$  empty.  $\square$

# Problem 1 (finite dimensions): Proofs

## Corollary (of stratification)

For generic  $\sigma$ , if  $\mathcal{M}_i \subset \mathcal{M}^G(\sigma)$  is a component whose points  $x \in \mathcal{M}_i$  satisfy  $\text{ind } \mathbf{D}_x^i \geq 0$  for all  $i$ , then  $\sigma \pitchfork 0$  on an **open dense** subset of  $\mathcal{M}_i$ . Similarly for **clean intersections** if  $\text{ind } \mathbf{D}^i \leq 0$  for  $i \geq 2$ .  $\square$

## Proof of Theorem 1.B (Morse functions):

We consider  $E := T^*M$  and  $df \in \Gamma(E)$  and need to show  $df \pitchfork 0$  for generic  $f : M \rightarrow \mathbb{R}$ . **Two new features:**

- 1 For  $x \in df^{-1}(0)$ ,  $\mathbf{D}_x := D(df)(x)$  is always **symmetric**, so the previous codimension formula changes to

$$\text{codim } \mathcal{M}^G(df; k, c) = \dim \text{End}_G^{\text{sym}}(\ker \mathbf{D}_x)$$

which is generally **smaller**, but still **positive**.

- 2 Every  $\mathbf{D}_x^i$  is self-adjoint, thus  $\text{ind } \mathbf{D}_x^i = 0$ .

Then all strata  $\mathcal{M}^G(df)$  are **0-dimensional**. Non-Morse critical points live in walls  $\mathcal{M}^G(df; k, c)$ , which have **negative dimension**  $\Rightarrow$  empty.  $\square$

# Problem 1 (finite dimensions): Proofs

## Corollary (of stratification)

For generic  $\sigma$ , if  $\mathcal{M}_i \subset \mathcal{M}^G(\sigma)$  is a component whose points  $x \in \mathcal{M}_i$  satisfy  $\text{ind } \mathbf{D}_x^i \geq 0$  for all  $i$ , then  $\sigma \pitchfork 0$  on an **open dense** subset of  $\mathcal{M}_i$ . Similarly for **clean intersections** if  $\text{ind } \mathbf{D}^i \leq 0$  for  $i \geq 2$ .  $\square$

## Proof of Theorem 1.B (Morse functions):

We consider  $E := T^*M$  and  $df \in \Gamma(E)$  and need to show  $df \pitchfork 0$  for generic  $f : M \rightarrow \mathbb{R}$ . **Two new features:**

- 1 For  $x \in df^{-1}(0)$ ,  $\mathbf{D}_x := D(df)(x)$  is always **symmetric**, so the previous codimension formula changes to

$$\text{codim } \mathcal{M}^G(df; k, c) = \dim \text{End}_G^{\text{sym}}(\ker \mathbf{D}_x)$$

which is generally **smaller**, but still **positive**.

- 2 Every  $\mathbf{D}_x^i$  is self-adjoint, thus  $\text{ind } \mathbf{D}_x^i = 0$ .

Then all strata  $\mathcal{M}^G(df)$  are **0-dimensional**. Non-Morse critical points live in walls  $\mathcal{M}^G(df; k, c)$ , which have **negative dimension**  $\Rightarrow$  empty.  $\square$



# Problem 1 (finite dimensions): Proofs

## Corollary (of stratification)

For generic  $\sigma$ , if  $\mathcal{M}_i \subset \mathcal{M}^G(\sigma)$  is a component whose points  $x \in \mathcal{M}_i$  satisfy  $\text{ind } \mathbf{D}_x^i \geq 0$  for all  $i$ , then  $\sigma \pitchfork 0$  on an **open dense** subset of  $\mathcal{M}_i$ . Similarly for **clean intersections** if  $\text{ind } \mathbf{D}^i \leq 0$  for  $i \geq 2$ .  $\square$

## Proof of Theorem 1.B (Morse functions):

We consider  $E := T^*M$  and  $df \in \Gamma(E)$  and need to show  $df \pitchfork 0$  for generic  $f : M \rightarrow \mathbb{R}$ . **Two new features:**

- 1 For  $x \in df^{-1}(0)$ ,  $\mathbf{D}_x := D(df)(x)$  is always **symmetric**, so the previous codimension formula changes to

$$\text{codim } \mathcal{M}^G(df; k, c) = \dim \text{End}_G^{\text{sym}}(\ker \mathbf{D}_x)$$

which is generally **smaller**, but still **positive**.

- 2 Every  $\mathbf{D}_x^i$  is self-adjoint, thus  $\text{ind } \mathbf{D}_x^i = 0$ .

Then all strata  $\mathcal{M}^G(df)$  are **0-dimensional**. Non-Morse critical points live in walls  $\mathcal{M}^G(df; k, c)$ , which have **negative dimension**  $\Rightarrow$  empty.  $\square$

# Problem 1 (finite dimensions): Proofs

## Corollary (of stratification)

For generic  $\sigma$ , if  $\mathcal{M}_i \subset \mathcal{M}^G(\sigma)$  is a component whose points  $x \in \mathcal{M}_i$  satisfy  $\text{ind } \mathbf{D}_x^i \geq 0$  for all  $i$ , then  $\sigma \pitchfork 0$  on an **open dense** subset of  $\mathcal{M}_i$ . Similarly for **clean intersections** if  $\text{ind } \mathbf{D}^i \leq 0$  for  $i \geq 2$ .  $\square$

## Proof of Theorem 1.B (Morse functions):

We consider  $E := T^*M$  and  $df \in \Gamma(E)$  and need to show  $df \pitchfork 0$  for generic  $f : M \rightarrow \mathbb{R}$ . **Two new features:**

- 1 For  $x \in df^{-1}(0)$ ,  $\mathbf{D}_x := D(df)(x)$  is always **symmetric**, so the previous codimension formula changes to

$$\text{codim } \mathcal{M}^G(df; k, c) = \dim \text{End}_G^{\text{sym}}(\ker \mathbf{D}_x)$$

which is generally **smaller**, but still **positive**.

- 2 Every  $\mathbf{D}_x^i$  is self-adjoint, thus  $\text{ind } \mathbf{D}_x^i = 0$ .

Then all strata  $\mathcal{M}^G(df)$  are **0-dimensional**. Non-Morse critical points live in walls  $\mathcal{M}^G(df; k, c)$ , which have **negative dimension**  $\Rightarrow$  empty.  $\square$

# Problem 1 (finite dimensions): Proofs

## Corollary (of stratification)

For generic  $\sigma$ , if  $\mathcal{M}_i \subset \mathcal{M}^G(\sigma)$  is a component whose points  $x \in \mathcal{M}_i$  satisfy  $\text{ind } \mathbf{D}_x^i \geq 0$  for all  $i$ , then  $\sigma \pitchfork 0$  on an **open dense** subset of  $\mathcal{M}_i$ . Similarly for **clean intersections** if  $\text{ind } \mathbf{D}^i \leq 0$  for  $i \geq 2$ .  $\square$

## Proof of Theorem 1.B (Morse functions):

We consider  $E := T^*M$  and  $df \in \Gamma(E)$  and need to show  $df \pitchfork 0$  for generic  $f : M \rightarrow \mathbb{R}$ . **Two new features:**

- 1 For  $x \in df^{-1}(0)$ ,  $\mathbf{D}_x := D(df)(x)$  is always **symmetric**, so the previous codimension formula changes to

$$\text{codim } \mathcal{M}^G(df; k, c) = \dim \text{End}_G^{\text{sym}}(\ker \mathbf{D}_x)$$

which is generally **smaller**, but still **positive**.

- 2 Every  $\mathbf{D}_x^i$  is self-adjoint, thus  $\text{ind } \mathbf{D}_x^i = 0$ .

Then all strata  $\mathcal{M}^G(df)$  are **0-dimensional**. Non-Morse critical points live in walls  $\mathcal{M}^G(df; k, c)$ , which have **negative dimension**  $\Rightarrow$  empty.  $\square$

# Problem 1 (finite dimensions): Proofs

## Corollary (of stratification)

For generic  $\sigma$ , if  $\mathcal{M}_i \subset \mathcal{M}^G(\sigma)$  is a component whose points  $x \in \mathcal{M}_i$  satisfy  $\text{ind } \mathbf{D}_x^i \geq 0$  for all  $i$ , then  $\sigma \pitchfork 0$  on an **open dense** subset of  $\mathcal{M}_i$ . Similarly for **clean intersections** if  $\text{ind } \mathbf{D}^i \leq 0$  for  $i \geq 2$ .  $\square$

## Proof of Theorem 1.B (Morse functions):

We consider  $E := T^*M$  and  $df \in \Gamma(E)$  and need to show  $df \pitchfork 0$  for generic  $f : M \rightarrow \mathbb{R}$ . **Two new features:**

- 1 For  $x \in df^{-1}(0)$ ,  $\mathbf{D}_x := D(df)(x)$  is always **symmetric**, so the previous codimension formula changes to

$$\text{codim } \mathcal{M}^G(df; k, c) = \dim \text{End}_G^{\text{sym}}(\ker \mathbf{D}_x)$$

which is generally **smaller**, but still **positive**.

- 2 Every  $\mathbf{D}_x^i$  is self-adjoint, thus  $\text{ind } \mathbf{D}_x^i = 0$ .

Then all strata  $\mathcal{M}^G(df)$  are **0-dimensional**. Non-Morse critical points live in walls  $\mathcal{M}^G(df; k, c)$ , which have **negative dimension**  $\Rightarrow$  empty.  $\square$

## Problem 1 (finite dimensions): Proofs

To do more, one must compute the **codimensions of the walls**  $\mathcal{M}^G(\sigma; k, c) \subset \mathcal{M}^G(\sigma)$ . These come via **Schur's lemma**:

$$\dim \operatorname{Hom}_G(\ker \mathbf{D}_x, \operatorname{coker} \mathbf{D}_x) = \sum_{i=1}^N (\dim_{\mathbb{R}} \mathbb{K}_i) \cdot k_i c_i,$$

where  $\mathbb{K}_i := \operatorname{End}_G(W_i) \in \{\mathbb{R}, \mathbb{C}, \mathbb{H}\}$  has dimension  $\in \{1, 2, 4\}$ ,  $k_i := \dim_{\mathbb{K}_i} \ker \mathbf{D}_x^i$  and  $c_i := \dim_{\mathbb{K}_i} \operatorname{coker} \mathbf{D}_x^i$ .

**Proof of Theorem 1.A** (clean intersections), case  $|G_x| \leq 2$ :

For  $x \in \mathcal{M}^{\mathbb{Z}_2}(\sigma)$ , there are two irreps  $\theta_{\pm} : \mathbb{Z}_2 \rightarrow \operatorname{GL}(1, \mathbb{R})$ , both with  $\operatorname{End}_{\mathbb{Z}_2}(\mathbb{R}) = \mathbb{R}$ . Write  $\mathbf{D}_x = \mathbf{D}_x^+ \oplus \mathbf{D}_x^-$ , where  $\mathbf{D}_x^+$  is surjective and  $\ker \mathbf{D}_x^+ = T_x \mathcal{M}^{\mathbb{Z}_2}(\sigma)$ . We have  $\operatorname{ind} \mathbf{D}_x = \dim M - \operatorname{rank} E = 0$ , thus

$$\operatorname{ind} \mathbf{D}_x^- = -\operatorname{ind} \mathbf{D}_x^+ \leq 0,$$

and need to show that  $\mathbf{D}_x^-$  is injective. If not, then  $x \in \mathcal{M}^{\mathbb{Z}_2}(\sigma; k, c)$  for  $k := \dim \ker \mathbf{D}_x^- > 0$  and  $c := k - \operatorname{ind} \mathbf{D}_x^- = k + \operatorname{ind} \mathbf{D}_x^+$ . Then  $\dim \mathcal{M}^{\mathbb{Z}_2}(\sigma; k, c) = \dim \mathcal{M}^{\mathbb{Z}_2}(\sigma) - kc = \operatorname{ind} \mathbf{D}_x^+ - k(k + \operatorname{ind} \mathbf{D}_x^+) < 0$ .  $\square$

## Problem 1 (finite dimensions): Proofs

To do more, one must compute the **codimensions of the walls**  $\mathcal{M}^G(\sigma; k, c) \subset \mathcal{M}^G(\sigma)$ . These come via **Schur's lemma**:

$$\dim \operatorname{Hom}_G(\ker \mathbf{D}_x, \operatorname{coker} \mathbf{D}_x) = \sum_{i=1}^N (\dim_{\mathbb{R}} \mathbb{K}_i) \cdot k_i c_i,$$

where  $\mathbb{K}_i := \operatorname{End}_G(W_i) \in \{\mathbb{R}, \mathbb{C}, \mathbb{H}\}$  has dimension  $\in \{1, 2, 4\}$ ,  $k_i := \dim_{\mathbb{K}_i} \ker \mathbf{D}_x^i$  and  $c_i := \dim_{\mathbb{K}_i} \operatorname{coker} \mathbf{D}_x^i$ .

**Proof of Theorem 1.A** (clean intersections), case  $|G_x| \leq 2$ :

For  $x \in \mathcal{M}^{\mathbb{Z}_2}(\sigma)$ , there are two irreps  $\theta_{\pm} : \mathbb{Z}_2 \rightarrow \operatorname{GL}(1, \mathbb{R})$ , both with  $\operatorname{End}_{\mathbb{Z}_2}(\mathbb{R}) = \mathbb{R}$ . Write  $\mathbf{D}_x = \mathbf{D}_x^+ \oplus \mathbf{D}_x^-$ , where  $\mathbf{D}_x^+$  is surjective and  $\ker \mathbf{D}_x^+ = T_x \mathcal{M}^{\mathbb{Z}_2}(\sigma)$ . We have  $\operatorname{ind} \mathbf{D}_x = \dim M - \operatorname{rank} E = 0$ , thus

$$\operatorname{ind} \mathbf{D}_x^- = -\operatorname{ind} \mathbf{D}_x^+ \leq 0,$$

and need to show that  $\mathbf{D}_x^-$  is injective. If not, then  $x \in \mathcal{M}^{\mathbb{Z}_2}(\sigma; k, c)$  for  $k := \dim \ker \mathbf{D}_x^- > 0$  and  $c := k - \operatorname{ind} \mathbf{D}_x^- = k + \operatorname{ind} \mathbf{D}_x^+$ . Then  $\dim \mathcal{M}^{\mathbb{Z}_2}(\sigma; k, c) = \dim \mathcal{M}^{\mathbb{Z}_2}(\sigma) - kc = \operatorname{ind} \mathbf{D}_x^+ - k(k + \operatorname{ind} \mathbf{D}_x^+) < 0$ .  $\square$

## Problem 1 (finite dimensions): Proofs

To do more, one must compute the **codimensions of the walls**  $\mathcal{M}^G(\sigma; k, c) \subset \mathcal{M}^G(\sigma)$ . These come via **Schur's lemma**:

$$\dim \operatorname{Hom}_G(\ker \mathbf{D}_x, \operatorname{coker} \mathbf{D}_x) = \sum_{i=1}^N (\dim_{\mathbb{R}} \mathbb{K}_i) \cdot k_i c_i,$$

where  $\mathbb{K}_i := \operatorname{End}_G(W_i) \in \{\mathbb{R}, \mathbb{C}, \mathbb{H}\}$  has dimension  $\in \{1, 2, 4\}$ ,  $k_i := \dim_{\mathbb{K}_i} \ker \mathbf{D}_x^i$  and  $c_i := \dim_{\mathbb{K}_i} \operatorname{coker} \mathbf{D}_x^i$ .

**Proof of Theorem 1.A** (clean intersections), case  $|G_x| \leq 2$ :

For  $x \in \mathcal{M}^{\mathbb{Z}_2}(\sigma)$ , there are two irreps  $\theta_{\pm} : \mathbb{Z}_2 \rightarrow \operatorname{GL}(1, \mathbb{R})$ , both with  $\operatorname{End}_{\mathbb{Z}_2}(\mathbb{R}) = \mathbb{R}$ . Write  $\mathbf{D}_x = \mathbf{D}_x^+ \oplus \mathbf{D}_x^-$ , where  $\mathbf{D}_x^+$  is surjective and  $\ker \mathbf{D}_x^+ = T_x \mathcal{M}^{\mathbb{Z}_2}(\sigma)$ . We have  $\operatorname{ind} \mathbf{D}_x = \dim M - \operatorname{rank} E = 0$ , thus

$$\operatorname{ind} \mathbf{D}_x^- = -\operatorname{ind} \mathbf{D}_x^+ \leq 0,$$

and need to show that  $\mathbf{D}_x^-$  is injective. If not, then  $x \in \mathcal{M}^{\mathbb{Z}_2}(\sigma; k, c)$  for  $k := \dim \ker \mathbf{D}_x^- > 0$  and  $c := k - \operatorname{ind} \mathbf{D}_x^- = k + \operatorname{ind} \mathbf{D}_x^+$ . Then  $\dim \mathcal{M}^{\mathbb{Z}_2}(\sigma; k, c) = \dim \mathcal{M}^{\mathbb{Z}_2}(\sigma) - kc = \operatorname{ind} \mathbf{D}_x^+ - k(k + \operatorname{ind} \mathbf{D}_x^+) < 0$ .  $\square$

## Problem 1 (finite dimensions): Proofs

To do more, one must compute the **codimensions of the walls**  $\mathcal{M}^G(\sigma; k, c) \subset \mathcal{M}^G(\sigma)$ . These come via **Schur's lemma**:

$$\dim \operatorname{Hom}_G(\ker \mathbf{D}_x, \operatorname{coker} \mathbf{D}_x) = \sum_{i=1}^N (\dim_{\mathbb{R}} \mathbb{K}_i) \cdot k_i c_i,$$

where  $\mathbb{K}_i := \operatorname{End}_G(W_i) \in \{\mathbb{R}, \mathbb{C}, \mathbb{H}\}$  has dimension  $\in \{1, 2, 4\}$ ,  $k_i := \dim_{\mathbb{K}_i} \ker \mathbf{D}_x^i$  and  $c_i := \dim_{\mathbb{K}_i} \operatorname{coker} \mathbf{D}_x^i$ .

**Proof of Theorem 1.A** (clean intersections), case  $|G_x| \leq 2$ :

For  $x \in \mathcal{M}^{\mathbb{Z}_2}(\sigma)$ , there are two irreps  $\theta_{\pm} : \mathbb{Z}_2 \rightarrow \operatorname{GL}(1, \mathbb{R})$ , both with  $\operatorname{End}_{\mathbb{Z}_2}(\mathbb{R}) = \mathbb{R}$ . Write  $\mathbf{D}_x = \mathbf{D}_x^+ \oplus \mathbf{D}_x^-$ , where  $\mathbf{D}_x^+$  is surjective and  $\ker \mathbf{D}_x^+ = T_x \mathcal{M}^{\mathbb{Z}_2}(\sigma)$ . We have  $\operatorname{ind} \mathbf{D}_x = \dim M - \operatorname{rank} E = 0$ , thus

$$\operatorname{ind} \mathbf{D}_x^- = -\operatorname{ind} \mathbf{D}_x^+ \leq 0,$$

and need to show that  $\mathbf{D}_x^-$  is injective. If not, then  $x \in \mathcal{M}^{\mathbb{Z}_2}(\sigma; k, c)$  for  $k := \dim \ker \mathbf{D}_x^- > 0$  and  $c := k - \operatorname{ind} \mathbf{D}_x^- = k + \operatorname{ind} \mathbf{D}_x^+$ . Then  $\dim \mathcal{M}^{\mathbb{Z}_2}(\sigma; k, c) = \dim \mathcal{M}^{\mathbb{Z}_2}(\sigma) - kc = \operatorname{ind} \mathbf{D}_x^+ - k(k + \operatorname{ind} \mathbf{D}_x^+) < 0$ .  $\square$



## Problem 1 (finite dimensions): Proofs

To do more, one must compute the **codimensions of the walls**  $\mathcal{M}^G(\sigma; k, c) \subset \mathcal{M}^G(\sigma)$ . These come via **Schur's lemma**:

$$\dim \operatorname{Hom}_G(\ker \mathbf{D}_x, \operatorname{coker} \mathbf{D}_x) = \sum_{i=1}^N (\dim_{\mathbb{R}} \mathbb{K}_i) \cdot k_i c_i,$$

where  $\mathbb{K}_i := \operatorname{End}_G(W_i) \in \{\mathbb{R}, \mathbb{C}, \mathbb{H}\}$  has dimension  $\in \{1, 2, 4\}$ ,  $k_i := \dim_{\mathbb{K}_i} \ker \mathbf{D}_x^i$  and  $c_i := \dim_{\mathbb{K}_i} \operatorname{coker} \mathbf{D}_x^i$ .

**Proof of Theorem 1.A** (clean intersections), case  $|G_x| \leq 2$ :

For  $x \in \mathcal{M}^{\mathbb{Z}_2}(\sigma)$ , there are two irreps  $\theta_{\pm} : \mathbb{Z}_2 \rightarrow \operatorname{GL}(1, \mathbb{R})$ , both with  $\operatorname{End}_{\mathbb{Z}_2}(\mathbb{R}) = \mathbb{R}$ . Write  $\mathbf{D}_x = \mathbf{D}_x^+ \oplus \mathbf{D}_x^-$ , where  $\mathbf{D}_x^+$  is surjective and  $\ker \mathbf{D}_x^+ = T_x \mathcal{M}^{\mathbb{Z}_2}(\sigma)$ . We have  $\operatorname{ind} \mathbf{D}_x = \dim M - \operatorname{rank} E = 0$ , thus

$$\operatorname{ind} \mathbf{D}_x^- = -\operatorname{ind} \mathbf{D}_x^+ \leq 0,$$

and need to show that  $\mathbf{D}_x^-$  is injective. If not, then  $x \in \mathcal{M}^{\mathbb{Z}_2}(\sigma; k, c)$  for  $k := \dim \ker \mathbf{D}_x^- > 0$  and  $c := k - \operatorname{ind} \mathbf{D}_x^- = k + \operatorname{ind} \mathbf{D}_x^+$ . Then  $\dim \mathcal{M}^{\mathbb{Z}_2}(\sigma; k, c) = \dim \mathcal{M}^{\mathbb{Z}_2}(\sigma) - kc = \operatorname{ind} \mathbf{D}_x^+ - k(k + \operatorname{ind} \mathbf{D}_x^+) < 0$ .  $\square$

## Problem 1 (finite dimensions): Proofs

To do more, one must compute the **codimensions of the walls**  $\mathcal{M}^G(\sigma; k, c) \subset \mathcal{M}^G(\sigma)$ . These come via **Schur's lemma**:

$$\dim \operatorname{Hom}_G(\ker \mathbf{D}_x, \operatorname{coker} \mathbf{D}_x) = \sum_{i=1}^N (\dim_{\mathbb{R}} \mathbb{K}_i) \cdot k_i c_i,$$

where  $\mathbb{K}_i := \operatorname{End}_G(W_i) \in \{\mathbb{R}, \mathbb{C}, \mathbb{H}\}$  has dimension  $\in \{1, 2, 4\}$ ,  $k_i := \dim_{\mathbb{K}_i} \ker \mathbf{D}_x^i$  and  $c_i := \dim_{\mathbb{K}_i} \operatorname{coker} \mathbf{D}_x^i$ .

**Proof of Theorem 1.A** (clean intersections), case  $|G_x| \leq 2$ :

For  $x \in \mathcal{M}^{\mathbb{Z}_2}(\sigma)$ , there are two irreps  $\theta_{\pm} : \mathbb{Z}_2 \rightarrow \operatorname{GL}(1, \mathbb{R})$ , both with  $\operatorname{End}_{\mathbb{Z}_2}(\mathbb{R}) = \mathbb{R}$ . Write  $\mathbf{D}_x = \mathbf{D}_x^+ \oplus \mathbf{D}_x^-$ , where  $\mathbf{D}_x^+$  is surjective and  $\ker \mathbf{D}_x^+ = T_x \mathcal{M}^{\mathbb{Z}_2}(\sigma)$ . We have  $\operatorname{ind} \mathbf{D}_x = \dim M - \operatorname{rank} E = 0$ , thus

$$\operatorname{ind} \mathbf{D}_x^- = -\operatorname{ind} \mathbf{D}_x^+ \leq 0,$$

and need to show that  $\mathbf{D}_x^-$  is injective. If not, then  $x \in \mathcal{M}^{\mathbb{Z}_2}(\sigma; k, c)$  for  $k := \dim \ker \mathbf{D}_x^- > 0$  and  $c := k - \operatorname{ind} \mathbf{D}_x^- = k + \operatorname{ind} \mathbf{D}_x^+$ . Then  $\dim \mathcal{M}^{\mathbb{Z}_2}(\sigma; k, c) = \dim \mathcal{M}^{\mathbb{Z}_2}(\sigma) - kc = \operatorname{ind} \mathbf{D}_x^+ - k(k + \operatorname{ind} \mathbf{D}_x^+) < 0$ .  $\square$

## Problem 1 (finite dimensions): Proofs

To do more, one must compute the **codimensions of the walls**  $\mathcal{M}^G(\sigma; k, c) \subset \mathcal{M}^G(\sigma)$ . These come via **Schur's lemma**:

$$\dim \operatorname{Hom}_G(\ker \mathbf{D}_x, \operatorname{coker} \mathbf{D}_x) = \sum_{i=1}^N (\dim_{\mathbb{R}} \mathbb{K}_i) \cdot k_i c_i,$$

where  $\mathbb{K}_i := \operatorname{End}_G(W_i) \in \{\mathbb{R}, \mathbb{C}, \mathbb{H}\}$  has dimension  $\in \{1, 2, 4\}$ ,  $k_i := \dim_{\mathbb{K}_i} \ker \mathbf{D}_x^i$  and  $c_i := \dim_{\mathbb{K}_i} \operatorname{coker} \mathbf{D}_x^i$ .

**Proof of Theorem 1.A** (clean intersections), case  $|G_x| \leq 2$ :

For  $x \in \mathcal{M}^{\mathbb{Z}_2}(\sigma)$ , there are two irreps  $\theta_{\pm} : \mathbb{Z}_2 \rightarrow \operatorname{GL}(1, \mathbb{R})$ , both with  $\operatorname{End}_{\mathbb{Z}_2}(\mathbb{R}) = \mathbb{R}$ . Write  $\mathbf{D}_x = \mathbf{D}_x^+ \oplus \mathbf{D}_x^-$ , where  $\mathbf{D}_x^+$  is surjective and  $\ker \mathbf{D}_x^+ = T_x \mathcal{M}^{\mathbb{Z}_2}(\sigma)$ . We have  $\operatorname{ind} \mathbf{D}_x = \dim M - \operatorname{rank} E = 0$ , thus

$$\operatorname{ind} \mathbf{D}_x^- = -\operatorname{ind} \mathbf{D}_x^+ \leq 0,$$

and need to show that  $\mathbf{D}_x^-$  is injective. If not, then  $x \in \mathcal{M}^{\mathbb{Z}_2}(\sigma; k, c)$  for  $k := \dim \ker \mathbf{D}_x^- > 0$  and  $c := k - \operatorname{ind} \mathbf{D}_x^- = k + \operatorname{ind} \mathbf{D}_x^+$ . Then  $\dim \mathcal{M}^{\mathbb{Z}_2}(\sigma; k, c) = \dim \mathcal{M}^{\mathbb{Z}_2}(\sigma) - kc = \operatorname{ind} \mathbf{D}_x^+ - k(k + \operatorname{ind} \mathbf{D}_x^+) < 0$ .  $\square$

## Problem 3 (holomorphic curves): Preparation

### Linearizations

Each  $u : (\Sigma, j) \rightarrow (M, J)$  has a **linearized Cauchy-Riemann operator**

$$\mathbf{D}_u := D\bar{\partial}_J(u) : \Gamma(u^*TM) \rightarrow \Omega^{0,1}(\Sigma, u^*TM)$$

and a **normal Cauchy-Riemann operator**

$$\mathbf{D}_u^N := \pi_N \circ \mathbf{D}_u|_{N_u} : \Gamma(N_u) \rightarrow \Omega^{0,1}(\Sigma, N_u),$$

for the projection  $u^*TM = T_u \oplus N_u \xrightarrow{\pi_N} N_u$  along the subbundle  $T_u \subset u^*TM$  with  $(T_u)_z = \text{im } du(z)$  at all noncritical points  $z$ .

**Lemma:** (i)  $u$  is cut out **transversely** iff  $\mathbf{D}_u^N$  is **surjective**.

(ii) For an immersed simple curve with index 0,  $u$  is **super-rigid** iff  $\mathbf{D}_{u \circ \varphi}^N$  is **injective** for all branched covers  $\varphi : (\Sigma', j') \rightarrow (\Sigma, j)$ .  $\square$

This makes  $\mathbf{D}_u^N$  the more convenient operator to work with. But we need it to vary continuously on isosymmetric strata...

## Problem 3 (holomorphic curves): Preparation

### Linearizations

Each  $u : (\Sigma, j) \rightarrow (M, J)$  has a **linearized Cauchy-Riemann operator**

$$\mathbf{D}_u := D\bar{\partial}_J(u) : \Gamma(u^*TM) \rightarrow \Omega^{0,1}(\Sigma, u^*TM)$$

and a **normal Cauchy-Riemann operator**

$$\mathbf{D}_u^N := \pi_N \circ \mathbf{D}_u|_{N_u} : \Gamma(N_u) \rightarrow \Omega^{0,1}(\Sigma, N_u),$$

for the projection  $u^*TM = T_u \oplus N_u \xrightarrow{\pi_N} N_u$  along the subbundle  $T_u \subset u^*TM$  with  $(T_u)_z = \text{im } du(z)$  at all noncritical points  $z$ .

**Lemma:** (i)  $u$  is cut out **transversely** iff  $\mathbf{D}_u^N$  is **surjective**.

(ii) For an immersed simple curve with index 0,  $u$  is **super-rigid** iff  $\mathbf{D}_{u \circ \varphi}^N$  is **injective** for all branched covers  $\varphi : (\Sigma', j') \rightarrow (\Sigma, j)$ .  $\square$

This makes  $\mathbf{D}_u^N$  the more convenient operator to work with. But we need it to vary continuously on isosymmetric strata...

## Problem 3 (holomorphic curves): Preparation

### Linearizations

Each  $u : (\Sigma, j) \rightarrow (M, J)$  has a **linearized Cauchy-Riemann operator**

$$\mathbf{D}_u := D\bar{\partial}_J(u) : \Gamma(u^*TM) \rightarrow \Omega^{0,1}(\Sigma, u^*TM)$$

and a **normal Cauchy-Riemann operator**

$$\mathbf{D}_u^N := \pi_N \circ \mathbf{D}_u|_{N_u} : \Gamma(N_u) \rightarrow \Omega^{0,1}(\Sigma, N_u),$$

for the projection  $u^*TM = T_u \oplus N_u \xrightarrow{\pi_N} N_u$  along the subbundle  $T_u \subset u^*TM$  with  $(T_u)_z = \text{im } du(z)$  at all noncritical points  $z$ .

**Lemma:** (i)  $u$  is cut out **transversely** iff  $\mathbf{D}_u^N$  is **surjective**.

(ii) For an immersed simple curve with index 0,  $u$  is **super-rigid** iff  $\mathbf{D}_{u \circ \varphi}^N$  is **injective** for all branched covers  $\varphi : (\Sigma', j') \rightarrow (\Sigma, j)$ .  $\square$

This makes  $\mathbf{D}_u^N$  the more convenient operator to work with. But we need it to vary continuously on isosymmetric strata...

## Problem 3 (holomorphic curves): Preparation

### Linearizations

Each  $u : (\Sigma, j) \rightarrow (M, J)$  has a **linearized Cauchy-Riemann operator**

$$\mathbf{D}_u := D\bar{\partial}_J(u) : \Gamma(u^*TM) \rightarrow \Omega^{0,1}(\Sigma, u^*TM)$$

and a **normal Cauchy-Riemann operator**

$$\mathbf{D}_u^N := \pi_N \circ \mathbf{D}_u|_{N_u} : \Gamma(N_u) \rightarrow \Omega^{0,1}(\Sigma, N_u),$$

for the projection  $u^*TM = T_u \oplus N_u \xrightarrow{\pi_N} N_u$  along the subbundle  $T_u \subset u^*TM$  with  $(T_u)_z = \text{im } du(z)$  at all noncritical points  $z$ .

**Lemma:** (i)  $u$  is cut out **transversely** iff  $\mathbf{D}_u^N$  is **surjective**.

(ii) For an immersed simple curve with index 0,  $u$  is **super-rigid** iff  $\mathbf{D}_{u \circ \varphi}^N$  is **injective** for all branched covers  $\varphi : (\Sigma', j') \rightarrow (\Sigma, j)$ .  $\square$

This makes  $\mathbf{D}_u^N$  the more convenient operator to work with. But we need it to vary continuously on isosymmetric strata...

## Problem 3 (holomorphic curves): Preparation

### Linearizations

Each  $u : (\Sigma, j) \rightarrow (M, J)$  has a **linearized Cauchy-Riemann operator**

$$\mathbf{D}_u := D\bar{\partial}_J(u) : \Gamma(u^*TM) \rightarrow \Omega^{0,1}(\Sigma, u^*TM)$$

and a **normal Cauchy-Riemann operator**

$$\mathbf{D}_u^N := \pi_N \circ \mathbf{D}_u|_{N_u} : \Gamma(N_u) \rightarrow \Omega^{0,1}(\Sigma, N_u),$$

for the projection  $u^*TM = T_u \oplus N_u \xrightarrow{\pi_N} N_u$  along the subbundle  $T_u \subset u^*TM$  with  $(T_u)_z = \text{im } du(z)$  at all noncritical points  $z$ .

**Lemma:** (i)  $u$  is cut out **transversely** iff  $\mathbf{D}_u^N$  is **surjective**.

(ii) For an immersed simple curve with index 0,  $u$  is **super-rigid** iff  $\mathbf{D}_{u \circ \varphi}^N$  is **injective** for all branched covers  $\varphi : (\Sigma', j') \rightarrow (\Sigma, j)$ .  $\square$

This makes  $\mathbf{D}_u^N$  the more convenient operator to work with. But we need it to vary continuously on isosymmetric strata...



## Problem 3 (holomorphic curves): Isosymmetric strata

Define strata of the form

$$\mathcal{M}^d(J) = \{u = v \circ \varphi\} \subset \mathcal{M}_g(A, J)$$

such that:

- $v$  varies among **simple** curves  $v : (\Sigma, j) \rightarrow (M, J)$  with a prescribed number of **critical** points, each of **prescribed order**;
- $\varphi$  varies among  $d$ -**fold branched covers**  $\varphi : (\Sigma', j') \rightarrow (\Sigma, j)$  with a prescribed number of **critical values**, each with a prescribed number of preimages that each has **prescribed branching order**.

**Lemma** (via standard transversality for simple curves):

For generic  $J$ ,  $\mathcal{M}^d(J)$  is a smooth manifold, and the operators  $\mathbf{D}_u^N$  vary smoothly as  $u$  varies in  $\mathcal{M}^d(J)$ . □

## Problem 3 (holomorphic curves): Isosymmetric strata

Define strata of the form

$$\mathcal{M}^d(J) = \{u = v \circ \varphi\} \subset \mathcal{M}_g(A, J)$$

such that:

- $v$  varies among **simple** curves  $v : (\Sigma, j) \rightarrow (M, J)$  with a prescribed number of **critical** points, each of **prescribed order**;
- $\varphi$  varies among  **$d$ -fold branched covers**  $\varphi : (\Sigma', j') \rightarrow (\Sigma, j)$  with a prescribed number of **critical values**, each with a prescribed number of preimages that each has **prescribed branching order**.

**Lemma** (via standard transversality for simple curves):

For generic  $J$ ,  $\mathcal{M}^d(J)$  is a smooth manifold, and the operators  $\mathbf{D}_u^N$  vary smoothly as  $u$  varies in  $\mathcal{M}^d(J)$ . □

## Problem 3 (holomorphic curves): Isosymmetric strata

Define strata of the form

$$\mathcal{M}^d(J) = \{u = v \circ \varphi\} \subset \mathcal{M}_g(A, J)$$

such that:

- $v$  varies among **simple** curves  $v : (\Sigma, j) \rightarrow (M, J)$  with a prescribed number of **critical** points, each of **prescribed order**;
- $\varphi$  varies among  **$d$ -fold branched covers**  $\varphi : (\Sigma', j') \rightarrow (\Sigma, j)$  with a prescribed number of **critical values**, each with a prescribed number of preimages that each has **prescribed branching order**.

**Lemma** (via standard transversality for simple curves):

For generic  $J$ ,  $\mathcal{M}^d(J)$  is a smooth manifold, and the operators  $\mathbf{D}_u^N$  vary smoothly as  $u$  varies in  $\mathcal{M}^d(J)$ . □

## Problem 3 (holomorphic curves): Splitting

Consider  $\mathbf{D} := \mathbf{D}_v^N : \Gamma(E) \rightarrow \Omega^{0,1}(\Sigma, E)$  on  $E := N_v$ , and

$$\varphi^* \mathbf{D} := \mathbf{D}_u^N : \Gamma(\varphi^* E) \rightarrow \Omega^{0,1}(\Sigma', \varphi^* E)$$

for a  $d$ -fold branched cover  $\varphi : (\Sigma', j') \rightarrow (\Sigma, j)$ .

**Simplest interesting case:** Assume  $d = 2$ .

Then  $G := \text{Aut}(\varphi) = \mathbb{Z}_2$  and there is a unique nontrivial **deck transformation**  $\psi : \Sigma' \rightarrow \Sigma'$ . We define

$$\Gamma_{\pm}(\varphi^* E) := \{ \eta \in \Gamma(\varphi^* E) \mid \eta \circ \psi = \pm \eta \},$$

and  $\Omega_{\pm}^{0,1}(\Sigma', \varphi^* E)$  similarly, so  $\varphi^* \mathbf{D} = \mathbf{D}^+ \oplus \mathbf{D}^-$  for operators  $\mathbf{D}^{\pm} : \Gamma_{\pm}(\varphi^* E) \rightarrow \Omega_{\pm}^{0,1}(\Sigma', \varphi^* E)$ .

**Difficult to generalize...** for  $d > 2$ ,  $\text{Aut}(\varphi)$  may be empty!

## Problem 3 (holomorphic curves): Splitting

Consider  $\mathbf{D} := \mathbf{D}_v^N : \Gamma(E) \rightarrow \Omega^{0,1}(\Sigma, E)$  on  $E := N_v$ , and

$$\varphi^* \mathbf{D} := \mathbf{D}_u^N : \Gamma(\varphi^* E) \rightarrow \Omega^{0,1}(\Sigma', \varphi^* E)$$

for a  $d$ -fold branched cover  $\varphi : (\Sigma', j') \rightarrow (\Sigma, j)$ .

**Simplest interesting case:** Assume  $d = 2$ .

Then  $G := \text{Aut}(\varphi) = \mathbb{Z}_2$  and there is a unique nontrivial **deck transformation**  $\psi : \Sigma' \rightarrow \Sigma'$ . We define

$$\Gamma_{\pm}(\varphi^* E) := \{ \eta \in \Gamma(\varphi^* E) \mid \eta \circ \psi = \pm \eta \},$$

and  $\Omega_{\pm}^{0,1}(\Sigma', \varphi^* E)$  similarly, so  $\varphi^* \mathbf{D} = \mathbf{D}^+ \oplus \mathbf{D}^-$  for operators  $\mathbf{D}^{\pm} : \Gamma_{\pm}(\varphi^* E) \rightarrow \Omega_{\pm}^{0,1}(\Sigma', \varphi^* E)$ .

**Difficult to generalize...** for  $d > 2$ ,  $\text{Aut}(\varphi)$  may be empty!

## Problem 3 (holomorphic curves): Splitting

Consider  $\mathbf{D} := \mathbf{D}_v^N : \Gamma(E) \rightarrow \Omega^{0,1}(\Sigma, E)$  on  $E := N_v$ , and

$$\varphi^* \mathbf{D} := \mathbf{D}_u^N : \Gamma(\varphi^* E) \rightarrow \Omega^{0,1}(\Sigma', \varphi^* E)$$

for a  $d$ -fold branched cover  $\varphi : (\Sigma', j') \rightarrow (\Sigma, j)$ .

**Simplest interesting case:** Assume  $d = 2$ .

Then  $G := \text{Aut}(\varphi) = \mathbb{Z}_2$  and there is a unique nontrivial **deck transformation**  $\psi : \Sigma' \rightarrow \Sigma'$ . We define

$$\Gamma_{\pm}(\varphi^* E) := \{ \eta \in \Gamma(\varphi^* E) \mid \eta \circ \psi = \pm \eta \},$$

and  $\Omega_{\pm}^{0,1}(\Sigma', \varphi^* E)$  similarly, so  $\varphi^* \mathbf{D} = \mathbf{D}^+ \oplus \mathbf{D}^-$  for operators  $\mathbf{D}^{\pm} : \Gamma_{\pm}(\varphi^* E) \rightarrow \Omega_{\pm}^{0,1}(\Sigma', \varphi^* E)$ .

**Difficult to generalize...** for  $d > 2$ ,  $\text{Aut}(\varphi)$  may be empty!

## Problem 3 (holomorphic curves): Splitting

### Idea

Replace  $\Gamma(\varphi^*E)$  with  $\Gamma(E \otimes_{\mathbb{R}} W)$  for some flat bundle  $W$ .

**Lemma** (via asymptotic regularity):

For a finite set  $\Theta \subset \Sigma$ , restricting  $\mathbf{D}$  to the **punctured** domain  $\dot{\Sigma} := \Sigma \setminus \Theta$  produces an operator on weighted Sobolev spaces (with small exponential growth at punctures) that has the **same index and kernel** as  $\mathbf{D}$ .  $\square$

Now **remove branch points** and consider  $\varphi : \dot{\Sigma}' \rightarrow \dot{\Sigma}$  as a covering map of punctured Riemann surfaces.

**Lemma** (covering space theory):

There exists a **regular** cover  $\pi : \dot{\Sigma}'' \rightarrow \dot{\Sigma}$  with **finite automorphism group**  $G$  and an injective homomorphism  $\rho : G \rightarrow S_d$  to the symmetric group such that  $\varphi$  is equivalent to the cover

$$\left( \dot{\Sigma}'' \times \{1, \dots, d\} \right) / G \xrightarrow{\varphi} \dot{\Sigma}, \quad \varphi([(z, i)]) = \pi(z).$$

## Problem 3 (holomorphic curves): Splitting

### Idea

Replace  $\Gamma(\varphi^*E)$  with  $\Gamma(E \otimes_{\mathbb{R}} W)$  for some flat bundle  $W$ .

**Lemma** (via asymptotic regularity):

For a finite set  $\Theta \subset \Sigma$ , restricting  $\mathbf{D}$  to the **punctured** domain  $\dot{\Sigma} := \Sigma \setminus \Theta$  produces an operator on weighted Sobolev spaces (with small exponential growth at punctures) that has the **same index and kernel** as  $\mathbf{D}$ .  $\square$

Now **remove branch points** and consider  $\varphi : \dot{\Sigma}' \rightarrow \dot{\Sigma}$  as a covering map of punctured Riemann surfaces.

**Lemma** (covering space theory):

There exists a **regular** cover  $\pi : \dot{\Sigma}'' \rightarrow \dot{\Sigma}$  with **finite automorphism group**  $G$  and an injective homomorphism  $\rho : G \rightarrow S_d$  to the symmetric group such that  $\varphi$  is equivalent to the cover

$$\left( \dot{\Sigma}'' \times \{1, \dots, d\} \right) / G \xrightarrow{\varphi} \dot{\Sigma}, \quad \varphi([(z, i)]) = \pi(z).$$



## Problem 3 (holomorphic curves): Splitting

### Idea

Replace  $\Gamma(\varphi^*E)$  with  $\Gamma(E \otimes_{\mathbb{R}} W)$  for some flat bundle  $W$ .

**Lemma** (via asymptotic regularity):

For a finite set  $\Theta \subset \Sigma$ , restricting  $\mathbf{D}$  to the **punctured** domain  $\dot{\Sigma} := \Sigma \setminus \Theta$  produces an operator on weighted Sobolev spaces (with small exponential growth at punctures) that has the **same index and kernel** as  $\mathbf{D}$ .  $\square$

Now **remove branch points** and consider  $\varphi : \dot{\Sigma}' \rightarrow \dot{\Sigma}$  as a covering map of punctured Riemann surfaces.

**Lemma** (covering space theory):

There exists a **regular** cover  $\pi : \dot{\Sigma}'' \rightarrow \dot{\Sigma}$  with **finite automorphism group**  $G$  and an injective homomorphism  $\rho : G \rightarrow S_d$  to the symmetric group such that  $\varphi$  is equivalent to the cover

$$\left( \dot{\Sigma}'' \times \{1, \dots, d\} \right) / G \xrightarrow{\varphi} \dot{\Sigma}, \quad \varphi([(z, i)]) = \pi(z).$$

## Problem 3 (holomorphic curves): Splitting

### Idea

Replace  $\Gamma(\varphi^*E)$  with  $\Gamma(E \otimes_{\mathbb{R}} W)$  for some flat bundle  $W$ .

**Lemma** (via asymptotic regularity):

For a finite set  $\Theta \subset \Sigma$ , restricting  $\mathbf{D}$  to the **punctured** domain  $\dot{\Sigma} := \Sigma \setminus \Theta$  produces an operator on weighted Sobolev spaces (with small exponential growth at punctures) that has the **same index and kernel** as  $\mathbf{D}$ .  $\square$

Now **remove branch points** and consider  $\varphi : \dot{\Sigma}' \rightarrow \dot{\Sigma}$  as a covering map of punctured Riemann surfaces.

**Lemma** (covering space theory):

There exists a **regular** cover  $\pi : \dot{\Sigma}'' \rightarrow \dot{\Sigma}$  with **finite automorphism group**  $G$  and an injective homomorphism  $\rho : G \rightarrow S_d$  to the symmetric group such that  $\varphi$  is equivalent to the cover

$$\left( \dot{\Sigma}'' \times \{1, \dots, d\} \right) / G \xrightarrow{\varphi} \dot{\Sigma}, \quad \varphi([(z, i)]) = \pi(z).$$

## Problem 3 (holomorphic curves): Splitting

Given a representation  $\theta : G \rightarrow \text{Aut}_{\mathbb{R}}(W)$ , define the **flat vector bundle**

$$W^\theta := (\dot{\Sigma}'' \times W)/G \rightarrow \dot{\Sigma}.$$

This gives a **twisted** bundle  $E^\theta := E \otimes_{\mathbb{R}} W^\theta \rightarrow \dot{\Sigma}$  with Cauchy-Riemann operator  $\mathbf{D}^\theta$  defined by  $\mathbf{D}^\theta(\eta \otimes v) := (\mathbf{D}\eta) \otimes v$  for flat sections  $v$ .

**Lemma:** For the permutation representation  $\rho : G \rightarrow \text{GL}(d, \mathbb{R})$  arising from  $\rho : G \rightarrow S_d$ , there is a natural isomorphism  $\Gamma(\varphi^* E) \cong \Gamma(E^\rho)$  such that the operator  $\varphi^* \mathbf{D}$  is identified with  $\mathbf{D}^\rho$ . □

Corollary (the general splitting of  $\mathbf{D}_u^N$ )

If  $\rho \cong \bigoplus_{i=1}^N \theta_i^{\oplus m_i}$ , then  $\varphi^* \mathbf{D} \cong \mathbf{D}^\rho \cong \bigoplus_{i=1}^N (\mathbf{D}^{\theta_i})^{\oplus m_i}$ . □

**Remark:** If  $\text{ind } \mathbf{D} = 0$ , a computation via the punctured Riemann-Roch formula shows  $\text{ind } \mathbf{D}^\theta \leq 0$  always. This is 45% of the reason why Theorem 3.A (super-rigidity) is true.

## Problem 3 (holomorphic curves): Splitting

Given a representation  $\theta : G \rightarrow \text{Aut}_{\mathbb{R}}(W)$ , define the **flat vector bundle**

$$W^\theta := (\dot{\Sigma}'' \times W)/G \rightarrow \dot{\Sigma}.$$

This gives a **twisted** bundle  $E^\theta := E \otimes_{\mathbb{R}} W^\theta \rightarrow \dot{\Sigma}$  with Cauchy-Riemann operator  $\mathbf{D}^\theta$  defined by  $\mathbf{D}^\theta(\eta \otimes v) := (\mathbf{D}\eta) \otimes v$  for flat sections  $v$ .

**Lemma:** For the permutation representation  $\rho : G \rightarrow \text{GL}(d, \mathbb{R})$  arising from  $\rho : G \rightarrow S_d$ , there is a natural isomorphism  $\Gamma(\varphi^* E) \cong \Gamma(E^\rho)$  such that the operator  $\varphi^* \mathbf{D}$  is identified with  $\mathbf{D}^\rho$ . □

**Corollary** (the general splitting of  $\mathbf{D}_u^N$ )

If  $\rho \cong \bigoplus_{i=1}^N \theta_i^{\oplus m_i}$ , then  $\varphi^* \mathbf{D} \cong \mathbf{D}^\rho \cong \bigoplus_{i=1}^N (\mathbf{D}^{\theta_i})^{\oplus m_i}$ . □

**Remark:** If  $\text{ind } \mathbf{D} = 0$ , a computation via the punctured Riemann-Roch formula shows  $\text{ind } \mathbf{D}^\theta \leq 0$  always. This is 45% of the reason why Theorem 3.A (super-rigidity) is true.

## Problem 3 (holomorphic curves): Splitting

Given a representation  $\theta : G \rightarrow \text{Aut}_{\mathbb{R}}(W)$ , define the **flat vector bundle**

$$W^\theta := (\dot{\Sigma}'' \times W)/G \rightarrow \dot{\Sigma}.$$

This gives a **twisted** bundle  $E^\theta := E \otimes_{\mathbb{R}} W^\theta \rightarrow \dot{\Sigma}$  with Cauchy-Riemann operator  $\mathbf{D}^\theta$  defined by  $\mathbf{D}^\theta(\eta \otimes v) := (\mathbf{D}\eta) \otimes v$  for flat sections  $v$ .

**Lemma:** For the permutation representation  $\rho : G \rightarrow \text{GL}(d, \mathbb{R})$  arising from  $\rho : G \rightarrow S_d$ , there is a natural isomorphism  $\Gamma(\varphi^* E) \cong \Gamma(E^\rho)$  such that the operator  $\varphi^* \mathbf{D}$  is identified with  $\mathbf{D}^\rho$ . □

Corollary (the general splitting of  $\mathbf{D}_u^N$ )

If  $\rho \cong \bigoplus_{i=1}^N \theta_i^{\oplus m_i}$ , then  $\varphi^* \mathbf{D} \cong \mathbf{D}^\rho \cong \bigoplus_{i=1}^N (\mathbf{D}^{\theta_i})^{\oplus m_i}$ . □

**Remark:** If  $\text{ind } \mathbf{D} = 0$ , a computation via the punctured Riemann-Roch formula shows  $\text{ind } \mathbf{D}^\theta \leq 0$  always. This is 45% of the reason why Theorem 3.A (super-rigidity) is true.

## Problem 3 (holomorphic curves): Splitting

Given a representation  $\theta : G \rightarrow \text{Aut}_{\mathbb{R}}(W)$ , define the **flat vector bundle**

$$W^\theta := (\dot{\Sigma}'' \times W)/G \rightarrow \dot{\Sigma}.$$

This gives a **twisted** bundle  $E^\theta := E \otimes_{\mathbb{R}} W^\theta \rightarrow \dot{\Sigma}$  with Cauchy-Riemann operator  $\mathbf{D}^\theta$  defined by  $\mathbf{D}^\theta(\eta \otimes v) := (\mathbf{D}\eta) \otimes v$  for flat sections  $v$ .

**Lemma:** For the permutation representation  $\rho : G \rightarrow \text{GL}(d, \mathbb{R})$  arising from  $\rho : G \rightarrow S_d$ , there is a natural isomorphism  $\Gamma(\varphi^* E) \cong \Gamma(E^\rho)$  such that the operator  $\varphi^* \mathbf{D}$  is identified with  $\mathbf{D}^\rho$ . □

**Corollary (the general splitting of  $\mathbf{D}_u^N$ )**

If  $\rho \cong \bigoplus_{i=1}^N \theta_i^{\oplus m_i}$ , then  $\varphi^* \mathbf{D} \cong \mathbf{D}^\rho \cong \bigoplus_{i=1}^N (\mathbf{D}^{\theta_i})^{\oplus m_i}$ . □

**Remark:** If  $\text{ind } \mathbf{D} = 0$ , a computation via the punctured Riemann-Roch formula shows  $\text{ind } \mathbf{D}^\theta \leq 0$  always. This is 45% of the reason why Theorem 3.A (super-rigidity) is true.

## Problem 3 (holomorphic curves): Splitting

Given a representation  $\theta : G \rightarrow \text{Aut}_{\mathbb{R}}(W)$ , define the **flat vector bundle**

$$W^\theta := (\dot{\Sigma}'' \times W)/G \rightarrow \dot{\Sigma}.$$

This gives a **twisted** bundle  $E^\theta := E \otimes_{\mathbb{R}} W^\theta \rightarrow \dot{\Sigma}$  with Cauchy-Riemann operator  $\mathbf{D}^\theta$  defined by  $\mathbf{D}^\theta(\eta \otimes v) := (\mathbf{D}\eta) \otimes v$  for flat sections  $v$ .

**Lemma:** For the permutation representation  $\rho : G \rightarrow \text{GL}(d, \mathbb{R})$  arising from  $\rho : G \rightarrow S_d$ , there is a natural isomorphism  $\Gamma(\varphi^* E) \cong \Gamma(E^\rho)$  such that the operator  $\varphi^* \mathbf{D}$  is identified with  $\mathbf{D}^\rho$ . □

**Corollary (the general splitting of  $\mathbf{D}_u^N$ )**

If  $\rho \cong \bigoplus_{i=1}^N \theta_i^{\oplus m_i}$ , then  $\varphi^* \mathbf{D} \cong \mathbf{D}^\rho \cong \bigoplus_{i=1}^N (\mathbf{D}^{\theta_i})^{\oplus m_i}$ . □

**Remark:** If  $\text{ind } \mathbf{D} = 0$ , a computation via the punctured Riemann-Roch formula shows  $\text{ind } \mathbf{D}^\theta \leq 0$  always. This is 45% of the reason why Theorem 3.A (super-rigidity) is true.

## Problem 3 (holomorphic curves): Walls

**Walls** in  $\mathcal{M}^d(J)$  are defined by fixing the dimensions of the kernel and cokernel of  $\mathbf{D}_u^N$  and its summands. Locally near  $u$ , this is the **zero-set** of a map to  $\text{Hom}_G(\ker \mathbf{D}_u^N, \text{coker } \mathbf{D}_u^N)$  whose derivative with respect to a variation  $\mathbf{T}$  in  $\mathbf{D}_u^N$  is

$$\ker \mathbf{D}_u^N \xrightarrow{\mathbf{T}} \Omega^{0,1}(\Sigma, N_u) \xrightarrow{\text{proj}} \text{coker } \mathbf{D}_u^N.$$

### Why is this derivative surjective?

Perturbing  $J$  causes **zeroth-order** perturbations in  $\mathbf{D}_u^N$ , so  $\mathbf{T}$  should be realized by a **bundle map**  $A : N_u \rightarrow \Lambda^{0,1} T^* \Sigma \otimes N_u$ . If not every map  $\ker \mathbf{D}_u^N \rightarrow \text{coker } \mathbf{D}_u^N$  arises this way, then given bases  $(\eta_i) \in \ker \mathbf{D}_u^N$  and  $(\xi_j) \in \ker(\mathbf{D}_u^N)^* \cong \text{coker } \mathbf{D}_u^N$ , there exist nontrivial coefficients  $c_{ij} \in \mathbb{R}$  such that for **all** zeroth-order perturbations  $A$ ,

$$\sum_{i,j} c_{ij} \langle A\eta_i, \xi_j \rangle_{L^2} = 0 = \int_{\Sigma} \langle \cdot, \cdot \rangle \circ (A \otimes \mathbb{1}) \left( \sum_{i,j} c_{ij} \eta_i \otimes \xi_j \right) d \text{vol}.$$



## Problem 3 (holomorphic curves): Walls

**Walls** in  $\mathcal{M}^d(J)$  are defined by fixing the dimensions of the kernel and cokernel of  $\mathbf{D}_u^N$  and its summands. Locally near  $u$ , this is the **zero-set** of a map to  $\text{Hom}_G(\ker \mathbf{D}_u^N, \text{coker } \mathbf{D}_u^N)$  whose derivative with respect to a variation  $\mathbf{T}$  in  $\mathbf{D}_u^N$  is

$$\ker \mathbf{D}_u^N \xrightarrow{\mathbf{T}} \Omega^{0,1}(\Sigma, N_u) \xrightarrow{\text{proj}} \text{coker } \mathbf{D}_u^N.$$

### Why is this derivative surjective?

Perturbing  $J$  causes **zeroth-order** perturbations in  $\mathbf{D}_u^N$ , so  $\mathbf{T}$  should be realized by a **bundle map**  $A : N_u \rightarrow \Lambda^{0,1}T^*\Sigma \otimes N_u$ . If not every map  $\ker \mathbf{D}_u^N \rightarrow \text{coker } \mathbf{D}_u^N$  arises this way, then given bases  $(\eta_i) \in \ker \mathbf{D}_u^N$  and  $(\xi_j) \in \ker(\mathbf{D}_u^N)^* \cong \text{coker } \mathbf{D}_u^N$ , there exist nontrivial coefficients  $c_{ij} \in \mathbb{R}$  such that for **all** zeroth-order perturbations  $A$ ,

$$\sum_{i,j} c_{ij} \langle A\eta_i, \xi_j \rangle_{L^2} = 0 = \int_{\Sigma} \langle \cdot, \cdot \rangle \circ (A \otimes \mathbb{1}) \left( \sum_{i,j} c_{ij} \eta_i \otimes \xi_j \right) d \text{vol}.$$

## Problem 3 (holomorphic curves): Walls

**Walls** in  $\mathcal{M}^d(J)$  are defined by fixing the dimensions of the kernel and cokernel of  $\mathbf{D}_u^N$  and its summands. Locally near  $u$ , this is the **zero-set** of a map to  $\text{Hom}_G(\ker \mathbf{D}_u^N, \text{coker } \mathbf{D}_u^N)$  whose derivative with respect to a variation  $\mathbf{T}$  in  $\mathbf{D}_u^N$  is

$$\ker \mathbf{D}_u^N \xrightarrow{\mathbf{T}} \Omega^{0,1}(\Sigma, N_u) \xrightarrow{\text{proj}} \text{coker } \mathbf{D}_u^N.$$

### Why is this derivative surjective?

Perturbing  $J$  causes **zeroth-order** perturbations in  $\mathbf{D}_u^N$ , so  $\mathbf{T}$  should be realized by a **bundle map**  $A : N_u \rightarrow \Lambda^{0,1}T^*\Sigma \otimes N_u$ . If not every map  $\ker \mathbf{D}_u^N \rightarrow \text{coker } \mathbf{D}_u^N$  arises this way, then given bases  $(\eta_i) \in \ker \mathbf{D}_u^N$  and  $(\xi_j) \in \ker(\mathbf{D}_u^N)^* \cong \text{coker } \mathbf{D}_u^N$ , there exist nontrivial coefficients  $c_{ij} \in \mathbb{R}$  such that for **all** zeroth-order perturbations  $A$ ,

$$\sum_{i,j} c_{ij} \langle A\eta_i, \xi_j \rangle_{L^2} = 0 = \int_{\Sigma} \langle \cdot, \cdot \rangle \circ (A \otimes \mathbb{1}) \left( \sum_{i,j} c_{ij} \eta_i \otimes \xi_j \right) d \text{vol}.$$

## Problem 3 (holomorphic curves): Walls

**Walls** in  $\mathcal{M}^d(J)$  are defined by fixing the dimensions of the kernel and cokernel of  $\mathbf{D}_u^N$  and its summands. Locally near  $u$ , this is the **zero-set** of a map to  $\text{Hom}_G(\ker \mathbf{D}_u^N, \text{coker } \mathbf{D}_u^N)$  whose derivative with respect to a variation  $\mathbf{T}$  in  $\mathbf{D}_u^N$  is

$$\ker \mathbf{D}_u^N \xrightarrow{\mathbf{T}} \Omega^{0,1}(\Sigma, N_u) \xrightarrow{\text{proj}} \text{coker } \mathbf{D}_u^N.$$

### Why is this derivative surjective?

Perturbing  $J$  causes **zeroth-order** perturbations in  $\mathbf{D}_u^N$ , so  $\mathbf{T}$  should be realized by a **bundle map**  $A : N_u \rightarrow \Lambda^{0,1}T^*\Sigma \otimes N_u$ . If not every map  $\ker \mathbf{D}_u^N \rightarrow \text{coker } \mathbf{D}_u^N$  arises this way, then given bases  $(\eta_i) \in \ker \mathbf{D}_u^N$  and  $(\xi_j) \in \ker(\mathbf{D}_u^N)^* \cong \text{coker } \mathbf{D}_u^N$ , there exist nontrivial coefficients  $c_{ij} \in \mathbb{R}$  such that for **all** zeroth-order perturbations  $A$ ,

$$\sum_{i,j} c_{ij} \langle A\eta_i, \xi_j \rangle_{L^2} = 0 = \int_{\Sigma} \langle \cdot, \cdot \rangle \circ (A \otimes \mathbb{1}) \left( \sum_{i,j} c_{ij} \eta_i \otimes \xi_j \right) d \text{vol}.$$

In other words,  $\sum_{i,j} c_{ij} \eta_i \otimes \xi_j = 0 \in \Gamma(N_u \otimes \Lambda^{0,1}T^*\Sigma \otimes N_u)$ .

## Problem 3 (holomorphic curves): Walls

**Walls** in  $\mathcal{M}^d(J)$  are defined by fixing the dimensions of the kernel and cokernel of  $\mathbf{D}_u^N$  and its summands. Locally near  $u$ , this is the **zero-set** of a map to  $\text{Hom}_G(\ker \mathbf{D}_u^N, \text{coker } \mathbf{D}_u^N)$  whose derivative with respect to a variation  $\mathbf{T}$  in  $\mathbf{D}_u^N$  is

$$\ker \mathbf{D}_u^N \xrightarrow{\mathbf{T}} \Omega^{0,1}(\Sigma, N_u) \xrightarrow{\text{proj}} \text{coker } \mathbf{D}_u^N.$$

### Why is this derivative surjective?

Perturbing  $J$  causes **zeroth-order** perturbations in  $\mathbf{D}_u^N$ , so  $\mathbf{T}$  should be realized by a **bundle map**  $A : N_u \rightarrow \Lambda^{0,1}T^*\Sigma \otimes N_u$ . If not every map  $\ker \mathbf{D}_u^N \rightarrow \text{coker } \mathbf{D}_u^N$  arises this way, then given bases  $(\eta_i) \in \ker \mathbf{D}_u^N$  and  $(\xi_j) \in \ker(\mathbf{D}_u^N)^* \cong \text{coker } \mathbf{D}_u^N$ , there exist nontrivial coefficients  $c_{ij} \in \mathbb{R}$  such that for **all** zeroth-order perturbations  $A$ ,

$$\sum_{i,j} c_{ij} \langle A\eta_i, \xi_j \rangle_{L^2} = \int_{\Sigma} \langle \cdot, \cdot \rangle \circ (A \otimes \mathbf{1}) \left( \sum_{i,j} c_{ij} \eta_i \otimes \xi_j \right) d \text{vol} = 0.$$

In other words,  $\sum_{i,j} c_{ij} \eta_i \otimes \xi_j \equiv 0 \in \Gamma(N_u \otimes \Lambda^{0,1}T^*\Sigma \otimes N_u)$ .

## Problem 3 (holomorphic curves): Walls

**Walls** in  $\mathcal{M}^d(J)$  are defined by fixing the dimensions of the kernel and cokernel of  $\mathbf{D}_u^N$  and its summands. Locally near  $u$ , this is the **zero-set** of a map to  $\text{Hom}_G(\ker \mathbf{D}_u^N, \text{coker } \mathbf{D}_u^N)$  whose derivative with respect to a variation  $\mathbf{T}$  in  $\mathbf{D}_u^N$  is

$$\ker \mathbf{D}_u^N \xrightarrow{\mathbf{T}} \Omega^{0,1}(\Sigma, N_u) \xrightarrow{\text{proj}} \text{coker } \mathbf{D}_u^N.$$

### Why is this derivative surjective?

Perturbing  $J$  causes **zeroth-order** perturbations in  $\mathbf{D}_u^N$ , so  $\mathbf{T}$  should be realized by a **bundle map**  $A : N_u \rightarrow \Lambda^{0,1}T^*\Sigma \otimes N_u$ . If not every map  $\ker \mathbf{D}_u^N \rightarrow \text{coker } \mathbf{D}_u^N$  arises this way, then given bases  $(\eta_i) \in \ker \mathbf{D}_u^N$  and  $(\xi_j) \in \ker(\mathbf{D}_u^N)^* \cong \text{coker } \mathbf{D}_u^N$ , there exist nontrivial coefficients  $c_{ij} \in \mathbb{R}$  such that for **all** zeroth-order perturbations  $A$ ,

$$\sum_{i,j} c_{ij} \langle A\eta_i, \xi_j \rangle_{L^2} = \int_{\Sigma} \langle \cdot, \cdot \rangle \circ (A \otimes \mathbf{1}) \left( \sum_{i,j} c_{ij} \eta_i \otimes \xi_j \right) d \text{vol} = 0.$$

In other words,  $\sum_{i,j} c_{ij} \eta_i \otimes \xi_j \equiv 0 \in \Gamma(N_u \otimes \Lambda^{0,1}T^*\Sigma \otimes N_u)$ .

## Problem 3 (holomorphic curves): Walls

Definition (a “quadratic unique continuation” property)

A real-linear partial differential operator  $\mathbf{D} : \Gamma(E) \rightarrow \Gamma(F)$  on Euclidean vector bundles  $E, F \rightarrow \Sigma$  satisfies **Petri's condition** if the canonical map

$$\ker \mathbf{D} \otimes \ker \mathbf{D}^* \xrightarrow{\Pi} \Gamma(E \otimes F|_{\mathcal{U}})$$

is **injective** for every open subset  $\mathcal{U} \subset \Sigma$ .

**Meta-theorem** (cf. work of A. Doan and T. Walpuski):

Equivariant transversality problems are **tractable** for a large class of elliptic operators that satisfy **Petri's condition**.

**Example 1**, via uniqueness for ODEs: Elliptic operators on **1-dimensional** domains. (This makes Problem 2 tractable.)

**Non-example 2**:  $\mathbf{D} = \bar{\partial}$  and  $\mathbf{D}^* = -\partial$ , **FAIL**:

$\Pi(1 \otimes_{\mathbb{R}} i\bar{z} - i \otimes_{\mathbb{R}} \bar{z} - z \otimes_{\mathbb{R}} i + iz \otimes_{\mathbb{R}} 1) \equiv 0$ . (This makes us panic slightly.)

## Problem 3 (holomorphic curves): Walls

Definition (a “quadratic unique continuation” property)

A real-linear partial differential operator  $\mathbf{D} : \Gamma(E) \rightarrow \Gamma(F)$  on Euclidean vector bundles  $E, F \rightarrow \Sigma$  satisfies **Petri's condition** if the canonical map

$$\ker \mathbf{D} \otimes \ker \mathbf{D}^* \xrightarrow{\Pi} \Gamma(E \otimes F|_{\mathcal{U}})$$

is **injective** for every open subset  $\mathcal{U} \subset \Sigma$ .

**Meta-theorem** (cf. work of A. Doan and T. Walpuski):

Equivariant transversality problems are **tractable** for a large class of elliptic operators that satisfy **Petri's condition**.

**Example 1**, via uniqueness for ODEs: Elliptic operators on **1-dimensional** domains. (This makes Problem 2 tractable.)

**Non-example 2**:  $\mathbf{D} = \bar{\partial}$  and  $\mathbf{D}^* = -\partial$ , **FAIL**:

$\Pi(1 \otimes_{\mathbb{R}} i\bar{z} - i \otimes_{\mathbb{R}} \bar{z} - z \otimes_{\mathbb{R}} i + iz \otimes_{\mathbb{R}} 1) \equiv 0$ . (This makes us panic slightly.)

## Problem 3 (holomorphic curves): Walls

Definition (a “quadratic unique continuation” property)

A real-linear partial differential operator  $\mathbf{D} : \Gamma(E) \rightarrow \Gamma(F)$  on Euclidean vector bundles  $E, F \rightarrow \Sigma$  satisfies **Petri's condition** if the canonical map

$$\ker \mathbf{D} \otimes \ker \mathbf{D}^* \xrightarrow{\Pi} \Gamma(E \otimes F|_{\mathcal{U}})$$

is **injective** for every open subset  $\mathcal{U} \subset \Sigma$ .

**Meta-theorem** (cf. work of A. Doan and T. Walpuski):

Equivariant transversality problems are **tractable** for a large class of elliptic operators that satisfy **Petri's condition**.

**Example 1**, via uniqueness for ODEs: Elliptic operators on **1-dimensional** domains. (This makes Problem 2 tractable.)

**Non-example 2:**  $\mathbf{D} = \bar{\partial}$  and  $\mathbf{D}^* = -\partial$ , **FAIL**:

$\Pi(1 \otimes_{\mathbb{R}} i\bar{z} - i \otimes_{\mathbb{R}} \bar{z} - z \otimes_{\mathbb{R}} i + iz \otimes_{\mathbb{R}} 1) \equiv 0$ . (This makes us panic slightly.)



## Problem 3 (holomorphic curves): Walls

Definition (a “quadratic unique continuation” property)

A real-linear partial differential operator  $\mathbf{D} : \Gamma(E) \rightarrow \Gamma(F)$  on Euclidean vector bundles  $E, F \rightarrow \Sigma$  satisfies **Petri's condition** if the canonical map

$$\ker \mathbf{D} \otimes \ker \mathbf{D}^* \xrightarrow{\Pi} \Gamma(E \otimes F|_{\mathcal{U}})$$

is **injective** for every open subset  $\mathcal{U} \subset \Sigma$ .

**Meta-theorem** (cf. work of A. Doan and T. Walpuski):

Equivariant transversality problems are **tractable** for a large class of elliptic operators that satisfy **Petri's condition**.

**Example 1**, via uniqueness for ODEs: Elliptic operators on **1-dimensional** domains. (This makes Problem 2 tractable.)

**Non-example 2:**  $\mathbf{D} = \bar{\partial}$  and  $\mathbf{D}^* = -\partial$ , **FAIL**:

$\Pi(1 \otimes_{\mathbb{R}} i\bar{z} - i \otimes_{\mathbb{R}} \bar{z} - z \otimes_{\mathbb{R}} i + iz \otimes_{\mathbb{R}} 1) \equiv 0$ . (This makes us panic slightly.)

## Problem 3 (holomorphic curves): Walls

Definition (a “quadratic unique continuation” property)

A real-linear partial differential operator  $\mathbf{D} : \Gamma(E) \rightarrow \Gamma(F)$  on Euclidean vector bundles  $E, F \rightarrow \Sigma$  satisfies **Petri's condition** if the canonical map

$$\ker \mathbf{D} \otimes \ker \mathbf{D}^* \xrightarrow{\Pi} \Gamma(E \otimes F|_{\mathcal{U}})$$

is **injective** for every open subset  $\mathcal{U} \subset \Sigma$ .

**Meta-theorem** (cf. work of A. Doan and T. Walpuski):

Equivariant transversality problems are **tractable** for a large class of elliptic operators that satisfy **Petri's condition**.

**Example 1**, via uniqueness for ODEs: Elliptic operators on **1-dimensional** domains. (This makes Problem 2 tractable.)

**Non-example 2:**  $\mathbf{D} = \bar{\partial}$  and  $\mathbf{D}^* = -\partial$ , **FAIL**:

$\Pi(1 \otimes_{\mathbb{R}} i\bar{z} - i \otimes_{\mathbb{R}} \bar{z} - z \otimes_{\mathbb{R}} i + iz \otimes_{\mathbb{R}} 1) \equiv 0$ . (This makes us panic slightly.)

## Problem 3 (holomorphic curves): Walls

Definition (a “quadratic unique continuation” property)

A real-linear partial differential operator  $\mathbf{D} : \Gamma(E) \rightarrow \Gamma(F)$  on Euclidean vector bundles  $E, F \rightarrow \Sigma$  satisfies **Petri's condition** if the canonical map

$$\ker \mathbf{D} \otimes \ker \mathbf{D}^* \xrightarrow{\Pi} \Gamma(E \otimes F|_{\mathcal{U}})$$

is **injective** for every open subset  $\mathcal{U} \subset \Sigma$ .

**Meta-theorem** (cf. work of A. Doan and T. Walpuski):

Equivariant transversality problems are **tractable** for a large class of elliptic operators that satisfy **Petri's condition**.

**Example 1**, via uniqueness for ODEs: Elliptic operators on **1-dimensional** domains. (This makes Problem 2 tractable.)

**Non-example 2:**  $\mathbf{D} = \bar{\partial}$  and  $\mathbf{D}^* = -\partial$ , **FAIL**:

$\Pi(1 \otimes_{\mathbb{R}} i\bar{z} - i \otimes_{\mathbb{R}} \bar{z} - z \otimes_{\mathbb{R}} i + iz \otimes_{\mathbb{R}} 1) \equiv 0$ . (This makes us panic slightly.)

## Problem 3 (holomorphic curves): Walls

### Crucial technical lemma

For each  $\ell \in \mathbb{N}$ , there exists an integer  $k \geq \ell$  and a **Baire set** of compatible almost complex structures  $J$  such that for every **simple curve**  $u : (\Sigma, j) \rightarrow (M, J)$  and point  $z \in \Sigma$ , if  $\eta_i, \xi_j$  are **local solutions** to  $\mathbf{D}_u^N \eta_i = 0$  and  $(\mathbf{D}_u^N)^* \xi_j = 0$  near  $z$  such that the tensor product

$$t := \sum_{i,j} c_{ij} \eta_i \otimes_{\mathbb{R}} \xi_j$$

**vanishes to order  $\ell$**  at  $z$ , then  $\Pi(t)$  **does not vanish to order  $k$**  at  $z$ .

**Corollary** (via unique continuation): Generically all  $\mathbf{D}_u^N$  satisfy Petri.

“Proof”: Sard-Smale theorem + dimension counting in jet spaces at  $z$ ...

**Remark:** The proof requires  $u$  to be simple for the usual (Sard-Smale) reasons, but the result is **local**, so it **carries over to all multiple covers**.

## Problem 3 (holomorphic curves): Walls

### Crucial technical lemma

For each  $\ell \in \mathbb{N}$ , there exists an integer  $k \geq \ell$  and a **Baire set** of compatible almost complex structures  $J$  such that for every **simple curve**  $u : (\Sigma, j) \rightarrow (M, J)$  and point  $z \in \Sigma$ , if  $\eta_i, \xi_j$  are **local solutions** to  $\mathbf{D}_u^N \eta_i = 0$  and  $(\mathbf{D}_u^N)^* \xi_j = 0$  near  $z$  such that the tensor product

$$t := \sum_{i,j} c_{ij} \eta_i \otimes_{\mathbb{R}} \xi_j$$

**vanishes to order  $\ell$**  at  $z$ , then  $\Pi(t)$  **does not vanish to order  $k$**  at  $z$ .

**Corollary** (via unique continuation): Generically all  $\mathbf{D}_u^N$  satisfy Petri.

“**Proof**”: Sard-Smale theorem + dimension counting in jet spaces at  $z \dots$

**Remark**: The proof requires  $u$  to be simple for the usual (Sard-Smale) reasons, but the result is **local**, so it **carries over to all multiple covers**.

## Problem 3 (holomorphic curves): Walls

### Crucial technical lemma

For each  $\ell \in \mathbb{N}$ , there exists an integer  $k \geq \ell$  and a **Baire set** of compatible almost complex structures  $J$  such that for every **simple curve**  $u : (\Sigma, j) \rightarrow (M, J)$  and point  $z \in \Sigma$ , if  $\eta_i, \xi_j$  are **local solutions** to  $\mathbf{D}_u^N \eta_i = 0$  and  $(\mathbf{D}_u^N)^* \xi_j = 0$  near  $z$  such that the tensor product

$$t := \sum_{i,j} c_{ij} \eta_i \otimes_{\mathbb{R}} \xi_j$$

**vanishes to order  $\ell$**  at  $z$ , then  $\Pi(t)$  **does not vanish to order  $k$**  at  $z$ .

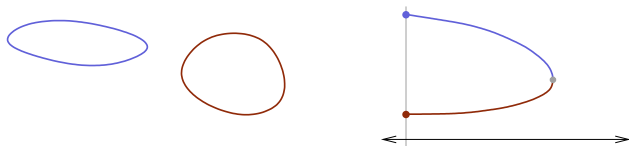
**Corollary** (via unique continuation): Generically all  $\mathbf{D}_u^N$  satisfy Petri.

“**Proof**”: Sard-Smale theorem + dimension counting in jet spaces at  $z \dots$

**Remark**: The proof requires  $u$  to be simple for the usual (Sard-Smale) reasons, but the result is **local**, so it **carries over to all multiple covers**.

## Back to Problem 2 (closed orbits)

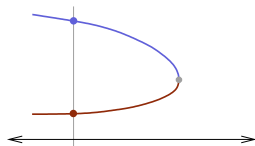
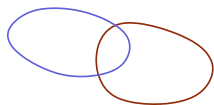
(1) **Birth-death:**



$$\mathcal{M}(\{l_s\}) = \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(l_s)\}$$

## Back to Problem 2 (closed orbits)

(1) **Birth-death:**

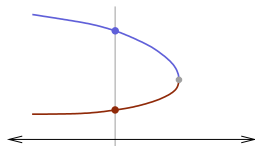
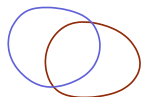


$$\mathcal{M}(\{\ell_s\}) = \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$



## Back to Problem 2 (closed orbits)

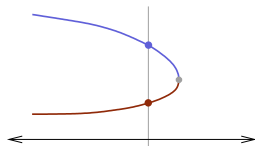
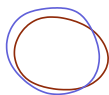
(1) **Birth-death:**



$$\mathcal{M}(\{\ell_s\}) = \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

## Back to Problem 2 (closed orbits)

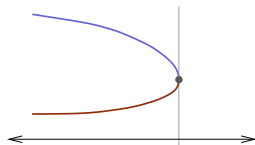
(1) **Birth-death:**



$$\mathcal{M}(\{l_s\}) = \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(l_s)\}$$

## Back to Problem 2 (closed orbits)

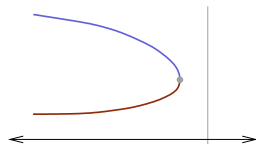
(1) **Birth-death:**



$$\mathcal{M}(\{\ell_s\}) = \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

## Back to Problem 2 (closed orbits)

(1) **Birth-death:**



$$\mathcal{M}(\{\ell_s\}) = \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

## Back to Problem 2 (closed orbits)

(1) **Birth-death:**

$$\mathcal{M}(\{\ell_s\}) = \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

(2) **Period-doubling:**



## Back to Problem 2 (closed orbits)

(1) **Birth-death:**

$$\mathcal{M}(\{\ell_s\}) = \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

(2) **Period-doubling:**

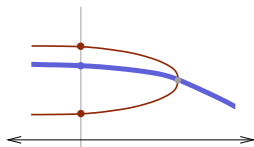
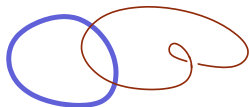


## Back to Problem 2 (closed orbits)

(1) **Birth-death:**

$$\mathcal{M}(\{l_s\}) = \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(l_s)\}$$

(2) **Period-doubling:**

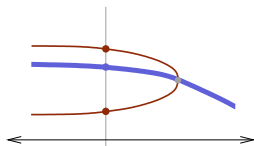
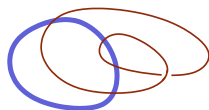


## Back to Problem 2 (closed orbits)

(1) **Birth-death:**

$$\mathcal{M}(\{\ell_s\}) = \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

(2) **Period-doubling:**



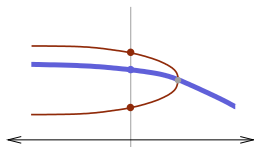
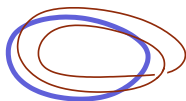


## Back to Problem 2 (closed orbits)

(1) **Birth-death:**

$$\mathcal{M}(\{\ell_s\}) = \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

(2) **Period-doubling:**

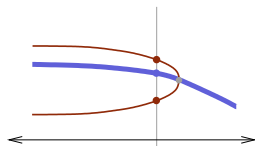


## Back to Problem 2 (closed orbits)

(1) **Birth-death:**

$$\mathcal{M}(\{\ell_s\}) = \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

(2) **Period-doubling:**

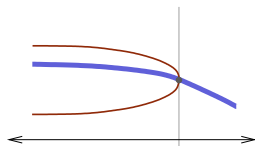


## Back to Problem 2 (closed orbits)

(1) **Birth-death:**

$$\mathcal{M}(\{\ell_s\}) = \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

(2) **Period-doubling:**

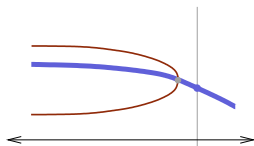


## Back to Problem 2 (closed orbits)

(1) **Birth-death:**

$$\mathcal{M}(\{\ell_s\}) = \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

(2) **Period-doubling:**

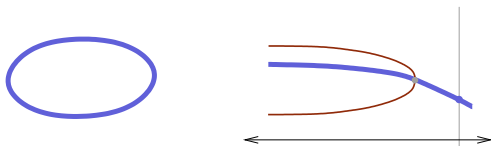


## Back to Problem 2 (closed orbits)

(1) **Birth-death:**

$$\mathcal{M}(\{\ell_s\}) = \{(s, \gamma) \mid s \in [0, 1] \text{ and } \gamma \in \mathcal{M}(\ell_s)\}$$

(2) **Period-doubling:**



### Sample theorem 2.B

For generic deformations  $\{\ell_s\}_{s \in [0,1]}$  of an oriented line field, if lengths of orbits are bounded, nothing else goes wrong.

## Back to Problem 2 (closed orbits)

**Why not?**

**Isosymmetric strata:** For  $d = 1, 2, 3, \dots$ ,

$$\mathcal{M}^d(\{\ell_s\}) := \{(s, \gamma) \in \mathcal{M}(\{\ell_s\}) \mid \text{cov}(\gamma) = d\}$$

is a smooth 1-manifold for generic  $\{\ell_s\}$ .

**Splitting:** For  $(s, \gamma) \in \mathcal{M}^d(\{\ell_s\})$ ,

$$\mathbf{D}_\gamma = \bigoplus_{i=1}^N \mathbf{D}_\gamma^{\theta_i}$$

with  $\theta_1, \dots, \theta_N$  the **irreps of  $\mathbb{Z}_d$** . All summands have **index 0**.

**Bifurcations = crossing walls of codimension 1:**

$$\text{codim } \mathcal{M}^d(\{\ell_s\}; k, c) = \sum_{i=1}^N t_i k_i c_i$$

with  $t_i =$  dimension of the equivariant endomorphism algebra of  $\theta_i$ .

## Back to Problem 2 (closed orbits)

Why not?

**Isosymmetric strata:** For  $d = 1, 2, 3, \dots$ ,

$$\mathcal{M}^d(\{\ell_s\}) := \{(s, \gamma) \in \mathcal{M}(\{\ell_s\}) \mid \text{cov}(\gamma) = d\}$$

is a smooth 1-manifold for generic  $\{\ell_s\}$ .

**Splitting:** For  $(s, \gamma) \in \mathcal{M}^d(\{\ell_s\})$ ,

$$\mathbf{D}_\gamma = \bigoplus_{i=1}^N \mathbf{D}_\gamma^{\theta_i}$$

with  $\theta_1, \dots, \theta_N$  the **irreps of  $\mathbb{Z}_d$** . All summands have **index 0**.

**Bifurcations = crossing walls of codimension 1:**

$$\text{codim } \mathcal{M}^d(\{\ell_s\}; k, c) = \sum_{i=1}^N t_i k_i c_i$$

with  $t_i =$  dimension of the equivariant endomorphism algebra of  $\theta_i$ .

## Back to Problem 2 (closed orbits)

Why not?

**Isosymmetric strata:** For  $d = 1, 2, 3, \dots$ ,

$$\mathcal{M}^d(\{\ell_s\}) := \{(s, \gamma) \in \mathcal{M}(\{\ell_s\}) \mid \text{cov}(\gamma) = d\}$$

is a smooth 1-manifold for generic  $\{\ell_s\}$ .

**Splitting:** For  $(s, \gamma) \in \mathcal{M}^d(\{\ell_s\})$ ,

$$\mathbf{D}_\gamma = \bigoplus_{i=1}^N \mathbf{D}_\gamma^{\theta_i}$$

with  $\theta_1, \dots, \theta_N$  the **irreps of  $\mathbb{Z}_d$** . All summands have **index 0**.

**Bifurcations = crossing walls of codimension 1:**

$$\text{codim } \mathcal{M}^d(\{\ell_s\}; k, c) = \sum_{i=1}^N t_i k_i c_i$$

with  $t_i =$  dimension of the equivariant endomorphism algebra of  $\theta_i$ .



## Back to Problem 2 (closed orbits)

Why not?

**Isosymmetric strata:** For  $d = 1, 2, 3, \dots$ ,

$$\mathcal{M}^d(\{\ell_s\}) := \{(s, \gamma) \in \mathcal{M}(\{\ell_s\}) \mid \text{cov}(\gamma) = d\}$$

is a smooth 1-manifold for generic  $\{\ell_s\}$ .

**Splitting:** For  $(s, \gamma) \in \mathcal{M}^d(\{\ell_s\})$ ,

$$\mathbf{D}_\gamma = \bigoplus_{i=1}^N \mathbf{D}_\gamma^{\theta_i}$$

with  $\theta_1, \dots, \theta_N$  the **irreps of  $\mathbb{Z}_d$** . All summands have **index 0**.

**Bifurcations = crossing walls of codimension 1:**

$$\text{codim } \mathcal{M}^d(\{\ell_s\}; k, c) = \sum_{i=1}^N t_i k_i c_i$$

with  $t_i =$  dimension of the equivariant endomorphism algebra of  $\theta_i$ .

## Back to Problem 2 (closed orbits)

**Real irreps of  $\mathbb{Z}_d$  come in two types:**

- *Real type:*  $\theta_{\pm} : \mathbb{Z}_d \rightarrow \text{Aut}_{\mathbb{R}}(\mathbb{R})$  with

$$\theta_+(m) = 1, \quad \theta_-(m) = (-1)^m \text{ (if } d \text{ even).}$$

- *Complex type:*  $\theta_j : \mathbb{Z}_d \rightarrow \text{Aut}_{\mathbb{R}}(\mathbb{C})$  with

$$\theta_j(m) = (e^{2\pi i j/d})^m \text{ (for } j \neq m/2).$$

$$\dim \ker \mathbf{D}_{\gamma}^{\theta_+} = \dim \text{coker } \mathbf{D}_{\gamma}^{\theta_+} = 1 \quad \Rightarrow \quad \text{birth-death.}$$

$$\dim \ker \mathbf{D}_{\gamma}^{\theta_-} = \dim \text{coker } \mathbf{D}_{\gamma}^{\theta_-} = 1 \quad \Rightarrow \quad \text{period-doubling.}$$

All other walls have codimension  $\geq 2$ . □

**Final remark:**

In the Hamiltonian case, orbits are critical points of an **action functional**  
 $\Rightarrow$  linearizations are **self-adjoint**. This changes  $\text{codim } \mathcal{M}^d(\{\ell_s\}; k, c)$  so  
that **complex-type representations** also play a role.

## Back to Problem 2 (closed orbits)

**Real irreps of  $\mathbb{Z}_d$  come in two types:**

- *Real type:*  $\theta_{\pm} : \mathbb{Z}_d \rightarrow \text{Aut}_{\mathbb{R}}(\mathbb{R})$  with

$$\theta_+(m) = 1, \quad \theta_-(m) = (-1)^m \text{ (if } d \text{ even).}$$

- *Complex type:*  $\theta_j : \mathbb{Z}_d \rightarrow \text{Aut}_{\mathbb{R}}(\mathbb{C})$  with

$$\theta_j(m) = (e^{2\pi i j/d})^m \text{ (for } j \neq m/2).$$

$$\dim \ker \mathbf{D}_{\gamma}^{\theta_+} = \dim \text{coker } \mathbf{D}_{\gamma}^{\theta_+} = 1 \quad \Rightarrow \quad \text{birth-death.}$$

$$\dim \ker \mathbf{D}_{\gamma}^{\theta_-} = \dim \text{coker } \mathbf{D}_{\gamma}^{\theta_-} = 1 \quad \Rightarrow \quad \text{period-doubling.}$$

All other walls have codimension  $\geq 2$ . □

Final remark:

In the Hamiltonian case, orbits are critical points of an **action functional**  
 $\Rightarrow$  linearizations are **self-adjoint**. This changes  $\text{codim } \mathcal{M}^d(\{\ell_s\}; k, c)$  so that **complex-type representations** also play a role.

## Back to Problem 2 (closed orbits)

**Real irreps of  $\mathbb{Z}_d$  come in two types:**

- *Real type:*  $\theta_{\pm} : \mathbb{Z}_d \rightarrow \text{Aut}_{\mathbb{R}}(\mathbb{R})$  with

$$\theta_+(m) = 1, \quad \theta_-(m) = (-1)^m \text{ (if } d \text{ even).}$$

- *Complex type:*  $\theta_j : \mathbb{Z}_d \rightarrow \text{Aut}_{\mathbb{R}}(\mathbb{C})$  with

$$\theta_j(m) = (e^{2\pi i j/d})^m \text{ (for } j \neq m/2).$$

$$\dim \ker \mathbf{D}_{\gamma}^{\theta^+} = \dim \text{coker } \mathbf{D}_{\gamma}^{\theta^+} = 1 \quad \Rightarrow \quad \text{birth-death.}$$

$$\dim \ker \mathbf{D}_{\gamma}^{\theta^-} = \dim \text{coker } \mathbf{D}_{\gamma}^{\theta^-} = 1 \quad \Rightarrow \quad \text{period-doubling.}$$

All other walls have codimension  $\geq 2$ . □

**Final remark:**

In the Hamiltonian case, orbits are critical points of an **action functional**  
 $\Rightarrow$  linearizations are **self-adjoint**. This changes  $\text{codim } \mathcal{M}^d(\{\ell_s\}; k, c)$  so  
that **complex-type representations** also play a role.

## Back to Problem 2 (closed orbits)

**Real irreps of  $\mathbb{Z}_d$  come in two types:**

- *Real type:*  $\theta_{\pm} : \mathbb{Z}_d \rightarrow \text{Aut}_{\mathbb{R}}(\mathbb{R})$  with

$$\theta_+(m) = 1, \quad \theta_-(m) = (-1)^m \text{ (if } d \text{ even).}$$

- *Complex type:*  $\theta_j : \mathbb{Z}_d \rightarrow \text{Aut}_{\mathbb{R}}(\mathbb{C})$  with

$$\theta_j(m) = (e^{2\pi i j/d})^m \text{ (for } j \neq m/2).$$

$$\dim \ker \mathbf{D}_{\gamma}^{\theta^+} = \dim \text{coker } \mathbf{D}_{\gamma}^{\theta^+} = 1 \quad \Rightarrow \quad \text{birth-death.}$$

$$\dim \ker \mathbf{D}_{\gamma}^{\theta^-} = \dim \text{coker } \mathbf{D}_{\gamma}^{\theta^-} = 1 \quad \Rightarrow \quad \text{period-doubling.}$$

**All other walls have codimension  $\geq 2$ .** □

**Final remark:**

In the Hamiltonian case, orbits are critical points of an **action functional**  
 $\Rightarrow$  linearizations are **self-adjoint**. This changes  $\text{codim } \mathcal{M}^d(\{\ell_s\}; k, c)$  so  
that **complex-type representations** also play a role.

## Back to Problem 2 (closed orbits)

**Real irreps of  $\mathbb{Z}_d$  come in two types:**

- *Real type:*  $\theta_{\pm} : \mathbb{Z}_d \rightarrow \text{Aut}_{\mathbb{R}}(\mathbb{R})$  with

$$\theta_+(m) = 1, \quad \theta_-(m) = (-1)^m \text{ (if } d \text{ even).}$$

- *Complex type:*  $\theta_j : \mathbb{Z}_d \rightarrow \text{Aut}_{\mathbb{R}}(\mathbb{C})$  with

$$\theta_j(m) = (e^{2\pi i j/d})^m \text{ (for } j \neq m/2).$$

$$\dim \ker \mathbf{D}_{\gamma}^{\theta^+} = \dim \text{coker } \mathbf{D}_{\gamma}^{\theta^+} = 1 \quad \Rightarrow \quad \text{birth-death.}$$

$$\dim \ker \mathbf{D}_{\gamma}^{\theta^-} = \dim \text{coker } \mathbf{D}_{\gamma}^{\theta^-} = 1 \quad \Rightarrow \quad \text{period-doubling.}$$

**All other walls have codimension  $\geq 2$ .** □

**Final remark:**

In the Hamiltonian case, orbits are critical points of an **action functional**  
 $\Rightarrow$  linearizations are **self-adjoint**. This changes  $\text{codim } \mathcal{M}^d(\{\ell_s\}; k, c)$  so  
that **complex-type representations** also play a role.

## Back to Problem 2 (closed orbits)

Real irreps of  $\mathbb{Z}_d$  come in two types:

- *Real type:*  $\theta_{\pm} : \mathbb{Z}_d \rightarrow \text{Aut}_{\mathbb{R}}(\mathbb{R})$  with

$$\theta_+(m) = 1, \quad \theta_-(m) = (-1)^m \text{ (if } d \text{ even).}$$

- *Complex type:*  $\theta_j : \mathbb{Z}_d \rightarrow \text{Aut}_{\mathbb{R}}(\mathbb{C})$  with

$$\theta_j(m) = (e^{2\pi i j/d})^m \text{ (for } j \neq m/2).$$

$$\dim \ker \mathbf{D}_{\gamma}^{\theta^+} = \dim \text{coker } \mathbf{D}_{\gamma}^{\theta^+} = 1 \quad \Rightarrow \quad \text{birth-death.}$$

$$\dim \ker \mathbf{D}_{\gamma}^{\theta^-} = \dim \text{coker } \mathbf{D}_{\gamma}^{\theta^-} = 1 \quad \Rightarrow \quad \text{period-doubling.}$$

All other walls have codimension  $\geq 2$ . □

**Final remark:**

In the Hamiltonian case, orbits are critical points of an **action functional**  $\Rightarrow$  linearizations are **self-adjoint**. This changes  $\text{codim } \mathcal{M}^d(\{\ell_s\}; k, c)$  so that **complex-type representations** also play a role.