

Geodesics

M a manifold w/ conn. ∇ ,

defn: $\gamma: (a,b) \rightarrow M$ is a geodesic if
 $\nabla_t \dot{\gamma} \equiv 0$ (i.e. $\dot{\gamma}$ is a parallel vec. fld. along γ).

for local coords., $\gamma = (\gamma^1, \dots, \gamma^n)$,

$$\boxed{\ddot{\gamma}^i + \Gamma_{jk}^i(\gamma) \dot{\gamma}^j \dot{\gamma}^k = 0}$$

Theory of ODEs:

$\forall p \in M$ & $X \in T_p M$, \exists a maximal interval
 $(a,b) \subseteq \mathbb{R}$ & ! sol. $\gamma_X: (a,b) \rightarrow M$ to
the geod. eqn. s.t. $\gamma_X(0) = p$, $\dot{\gamma}_X(0) = X$;
 $\gamma_X(t)$ depts. smoothly on $t \in \mathbb{R}$ & $X \in TM$.

observation: If γ a geod. & $\hat{\gamma}(t) = \gamma(ct)$

for some $c \in \mathbb{R}$, then $\nabla_t \partial_t \hat{\gamma}(t) = \nabla_t (c \dot{\gamma}(ct))$
 $= c \nabla_t \dot{\gamma}(ct) \equiv 0 \Rightarrow \hat{\gamma}$ also a geod.

\Rightarrow con: $\gamma_X(t) =: \exp(tX)$ depts. only on $tX \in TM$.

\Rightarrow prop: \exists a maximal open set $\mathcal{O} \subseteq TM$ & smooth map

$\exp: \mathcal{O} \rightarrow M$ s.t. $\forall X \in \mathcal{O}$, $I := \{t \in \mathbb{R} \mid$
 $tX \in \mathcal{O}\}$ is an open interval around 0 &

$\gamma: I \rightarrow M: t \mapsto \exp(tX)$ is the maximal geod. w/
 $\dot{\gamma}(0) = X$. "exponential map" \square

notation: $p \in M$, $\exp_p := \exp|_{\mathcal{O} \cap T_p M}$. $\exp_p(0) = p$

The deriv. of \exp_p at $0 \in T_p M$ as $\text{Id}: T_p M \rightarrow T_p M$

$\xrightarrow{\text{IFT}}$ \exp_p maps a nbhd of $0 \in T_p M$ to a nbhd of
 $p \in M$ diffeomorphically!

Assume (M, g) a pseudo-Riemannian mfd.,
 $g =: \langle \cdot, \cdot \rangle \Rightarrow TM$ has a $O(k, l)$ -structure for
 some $k + l = n = \dim N$.

EX: On a real V.B. $E \rightarrow M$ w/ bil. metric $\langle \cdot, \cdot \rangle =: g$
 (i.e. $O(k, l)$ -str.), a conn. is $O(k, l)$ -compat.

$$\Leftrightarrow 2 \nabla_x \langle \eta, \xi \rangle = \langle \nabla_x \eta, \xi \rangle + \langle \eta, \nabla_x \xi \rangle$$

$$\Leftrightarrow g \in \Gamma(E_2^0) \text{ satisfies } \nabla g \equiv 0.$$

We say ∇ is a "metric conn.", \Leftrightarrow it is compatible w/ $\langle \cdot, \cdot \rangle$.

Fundamental thm of Riem. geometry: \forall ps.-Riem. mfd,
 (M, g) , $\exists !$ symmetric conn. on TM compat. w/ g .

pf: If such ∇ exists, then $\forall X, Y, Z \in \mathcal{K}(M)$,

$$2_X \langle Y, Z \rangle = \langle \nabla_X Y, Z \rangle + \langle Y, \nabla_X Z \rangle \quad (1)$$

$$2_Y \langle Z, X \rangle = \langle \nabla_Y Z, X \rangle + \langle Z, \nabla_Y X \rangle \quad (2)$$

$$2_Z \langle X, Y \rangle = \langle \nabla_Z X, Y \rangle + \langle X, \nabla_Z Y \rangle \quad (3)$$

$$(1) + (2) - (3) = \underbrace{\langle \nabla_X Y + \nabla_Y X, Z \rangle}_{2 \nabla_X Y - [X, Y] \text{ (symmetry!)}} + \underbrace{\langle \nabla_X Z - \nabla_Z X, Y \rangle}_{[Y, Z] \text{ (symmetry!)}}$$

$$\Rightarrow 2 \langle \nabla_X Y, Z \rangle = \langle [X, Y], Z \rangle - \langle [X, Z], Y \rangle - \langle [Y, Z], X \rangle \\ + 2_X \langle Y, Z \rangle + 2_Y \langle Z, X \rangle - 2_Z \langle X, Y \rangle.$$

claim (EX): RHS is C^∞ -linear w.r.t. X & Z

\Rightarrow can rewrite it as $S_Y(X, Z)$ for a tensor field $S_Y \in \Gamma(T_2^0 M)$ that depts. linearly on $Y \in \mathcal{K}(M)$

\Rightarrow We can define $\nabla_X Y$ by $\langle \nabla_X Y, \cdot \rangle := \frac{1}{2} S_Y(X, \cdot)$
(determines $\nabla_X Y$ uniquely since $\langle \cdot, \cdot \rangle$ is nondeg.!!)

Now check: $\nabla_X Y$ satisfies Leibniz rule \Rightarrow depts. a conn.,

α is symmetric & comput. w.r.t. $\langle \cdot, \cdot \rangle$. \square

Local coords

Spce E a real V.B. w/ bdd metric $\langle \cdot, \cdot \rangle$.

\exists an isom. $b: E \rightarrow E^*: v \mapsto v_b := \langle v, \cdot \rangle$
 $\# := b^{-1}: E^* \rightarrow E: \lambda \mapsto \lambda^\#$ (musical isomorphism)

Choose frame e_1, \dots, e_m for E over $U \stackrel{\text{open}}{\subseteq} M$,

\leadsto dual frame e^1, \dots, e^m for E^* , $v = v^i e_i \in E|_U$
 $\lambda = \lambda_i e^i \in E^*|_U$.

Write $g_{ij} := \langle e_i, e_j \rangle$, $\Rightarrow \langle v, w \rangle = g_{ij} v^i w^j$

Defn natural bdd metric on E^* by $\langle \lambda, \mu \rangle := \langle \lambda^\#, \mu^\# \rangle$.

$g^{ij} := \langle e^i, e^j \rangle \Rightarrow \langle \lambda, \mu \rangle = g^{ij} \lambda_i \mu_j$.

notational convention:

$v = v^i e_i \Leftrightarrow v_b = v_i e^i$, $\lambda = \lambda_i e^i \Leftrightarrow \lambda^\# = \lambda^i e_i$.

Now $\langle v, w \rangle = v_b(w) = w_b(v) = g_{ij} v^i w^j = v_i w^i = v^i w_i$

$\Rightarrow \boxed{v_i = g_{ij} v^j}$, sim. $\boxed{\lambda^i = g^{ij} \lambda_j}$

\Rightarrow the metrics (g_{ij}) & (g^{ij}) are inverses!

$\boxed{g^{ik} g_{kj} = \delta^i_j}$.

On (M, g) , the ! symm. conn. ∇ compat. w. g is called the Levi-Civita connection.

Choose local coords (x^1, \dots, x^n) , write

$$g_{ij} = \langle \partial_i, \partial_j \rangle, \quad g^{ij} = \langle dx^i, dx^j \rangle.$$

Let $X = \partial_i, Y = \partial_j, Z = \partial_k$, so

$$\langle \nabla_X Y, Z \rangle = g_{ab} (\nabla_i \partial_j)^a \delta_k^b = g_{ab} \Gamma_{ij}^a \delta_k^b = g_{ak} \Gamma_{ij}^a.$$

$$= \frac{1}{2} \left(2_X \langle Y, Z \rangle + 2_Y \langle Z, X \rangle - 2_Z \langle X, Y \rangle + \text{2ic bracket terms} \right)$$

$$= \frac{1}{2} \left(\partial_i g_{jk} + \partial_j g_{ki} - \partial_k g_{ij} \right)$$

$$\Rightarrow \Gamma_{ij}^k = \frac{1}{2} g^{kl} \left(\partial_i g_{jl} + \partial_j g_{li} - \partial_l g_{ij} \right)$$

ex: (\mathbb{R}^n, g_E) , $g_E =$ Euclidean inner product

$$\Rightarrow (g_E)_{ij} = \delta_{ij} \text{ const.} \Rightarrow \Gamma_{jk}^i = 0$$

\Rightarrow geod. eqn. $\ddot{x}^i = 0 \Rightarrow$ sols. are straight lines.

Assume (M, g) a Riem. mfd.

Fix $a < b$ & $p, q \in M$,

$$C^{\infty}(p, q) := \left\{ \gamma: [a, b] \xrightarrow{C^{\infty}} M \mid \gamma(a) = p, \gamma(b) = q \right\}.$$

For $X \in TM$, $|X| := \sqrt{\langle X, X \rangle}$, a path

$\gamma \in C^{\infty}(p, q)$ has speed $|\dot{\gamma}(t)|$ at time t .

The length of γ is $l(\gamma) := \int_a^b |\dot{\gamma}(t)| dt$.

Its energy is $E(\gamma) := \int_a^b \langle \dot{\gamma}(t), \dot{\gamma}(t) \rangle dt$

def: For a functional $F: C^{\infty}(p, q) \rightarrow \mathbb{R}$, a path $\gamma \in C^{\infty}(p, q)$ is stationary if \forall smooth 1-param. family $\{\gamma_s \in C^{\infty}(p, q)\}_{s \in (-\epsilon, \epsilon)}$ (i.e. $(s, t) \mapsto \gamma_s(t)$ is C^{∞}), (s.t. $\gamma_0 = \gamma$)

$$\frac{d}{ds} F(\gamma_s) \Big|_{s=0} = 0.$$

prop: γ is a geodesic \Leftrightarrow it is stationary for E .
 \Leftrightarrow it has constant speed & is stationary for l .

pf: Assume $\gamma_0 = \gamma$, $\partial_s \gamma_s|_{s=0} =: \eta \in \Gamma(\gamma^* TM)$.

$$\begin{aligned} \frac{d}{ds} E(\gamma_s) \Big|_{s=0} &= \frac{d}{ds} \int_a^b \langle \dot{\gamma}_s(t), \dot{\gamma}_s(t) \rangle dt \Big|_{s=0} \\ &= \int_a^b \partial_s \langle \dot{\gamma}_s(t), \dot{\gamma}_s(t) \rangle \Big|_{s=0} dt = 2 \int_a^b \underbrace{\langle \nabla_s \dot{\gamma}_s(t) \Big|_{s=0}, \dot{\gamma}(t) \rangle}_{\nabla_s \partial_t = \nabla_t \partial_s} dt \\ &= 2 \int_a^b \langle \nabla_t \partial_s \gamma_s \Big|_{s=0}, \dot{\gamma}(t) \rangle dt = 2 \int_a^b \langle \nabla_t \eta(t), \dot{\gamma}(t) \rangle dt. \end{aligned}$$

Since $\eta(a) = \eta(b) = 0$, $\int_a^b \partial_t \langle \eta(t), \dot{\gamma}(t) \rangle dt = 0$

$$= \int_a^b \langle \nabla_t \eta, \dot{\gamma} \rangle dt + \int_a^b \langle \eta, \nabla_t \dot{\gamma} \rangle dt$$

$$\Rightarrow \frac{d}{ds} E(\gamma_s) \Big|_{s=0} = -2 \int_a^b \langle \eta(t), \nabla_t \dot{\gamma}(t) \rangle dt = 0$$

$\forall \eta$ satisfying $\eta(a) = \eta(b) = 0 \Leftrightarrow \nabla_t \dot{\gamma} \equiv 0$.