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## Problem Set 11

To be discussed: 2.02.2022

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### Problem 1

This is essentially a repeat of Problem Set 5 #1, but using concepts and terminology that we did not yet have at our disposal back then. Any nowhere-vanishing 1-form  $\alpha \in \Omega^1(M)$  on a 3-manifold  $M$  defines a 2-dimensional distribution  $\xi \subset TM$  by  $\xi_p := \ker \alpha_p \subset T_p M$ .

- (a) Deduce from the Frobenius theorem that  $\xi$  is an integrable distribution if and only if  $d\alpha|_\xi$  vanishes, and that the latter is also equivalent to the condition  $\alpha \wedge d\alpha \equiv 0$ .
- (b) Show that for  $\alpha = f(x) dy + g(x) dz \in \Omega^1(\mathbb{R}^3)$  with smooth functions  $f, g : \mathbb{R} \rightarrow \mathbb{R}$ ,  $\xi$  is integrable if and only if the vector  $(f'(x), g'(x)) \in \mathbb{R}^2$  is a scalar multiple of  $(f(x), g(x))$  for each  $x$ , and in this case, one can also write  $\xi = \ker(A dy + B dz)$  for some constants  $A, B \in \mathbb{R}$ . (The integral submanifolds are then easy to find: they form a family of parallel planes in  $\mathbb{R}^3$ .)

### Problem 2

An integrable  $k$ -dimensional distribution  $\xi \subset TM$  on an  $n$ -manifold  $M$  determines a *foliation* of  $M$ , which one thinks of as a decomposition of  $M$  into a smooth family of disjoint integral submanifolds: every point in  $M$  belongs to a unique *leaf* of the foliation, meaning a maximal connected subset  $L \subset M$  of the form  $L = f(\Sigma)$  where  $\Sigma$  is a  $k$ -manifold and  $i : \Sigma \rightarrow M$  is an injective immersion satisfying  $\text{im}(T_p f) = \xi_p$  for all  $p \in \Sigma$ .

Consider the integrable 1-dimensional distribution  $\xi$  on  $\mathbb{T}^2 = \mathbb{R}^2/\mathbb{Z}^2$  defined by  $\xi = \ker(a dx + b dy)$  for some constant  $(a, b) \in \mathbb{R}^2 \setminus \{0\}$ , where  $x, y$  are the usual coordinates on  $\mathbb{R}^2$ , whose coordinate differentials descend to closed (but not exact) 1-forms on the quotient  $\mathbb{T}^2$ . Show that the leaves of the resulting foliation on  $\mathbb{T}^2$  can be described as follows:

- (a) If  $a/b \in \mathbb{Q}$  or  $b = 0$ , they are compact submanifolds diffeomorphic to  $S^1$ .
- (b) Otherwise, they are images of injective immersions  $\mathbb{R} \rightarrow \mathbb{T}^2$  and are dense in  $\mathbb{T}^2$ . (The latter implies that they cannot be submanifolds.)

### Problem 3

Suppose  $\ell \rightarrow S^1$  is a non-orientable real line bundle over  $S^1$  (as for instance in Problem Set 8 #6). Find a path  $\gamma : [0, 1] \rightarrow S^1$  with  $\gamma(0) = \gamma(1) =: p$  such that the parallel transport  $P_\gamma^t : \ell_p \rightarrow \ell_p$  cannot be the identity map for any choice of connection  $\nabla$ .

### Problem 4

Suppose  $\nabla$  is a flat connection on a vector bundle  $E \rightarrow M$ .

- (a) Show that for any smooth map  $f : N \rightarrow M$ , the pullback of  $\nabla$  to a connection on  $f^*E \rightarrow N$  is also flat.
- (b) Show that if  $\{\gamma_s : [0, 1] \rightarrow M\}_{s \in [0, 1]}$  is a smooth family of paths with fixed end points  $\gamma_s(0) = p$  and  $\gamma_s(1) = q$  for all  $s \in [0, 1]$ , then the two parallel transport maps  $P_{\gamma_0}^1, P_{\gamma_1}^1 : E_p \rightarrow E_q$  are the same.  
*Hint: Write  $h(s, t) := \gamma_s(t)$  and use the fact that the pullback connection on  $h^*E \rightarrow$*

$[0, 1] \times [0, 1]$  is also flat. Can you construct global flat sections of  $h^*E$ ? What will they look like on the subsets  $[0, 1] \times \{0\}$  and  $[0, 1] \times \{1\}$ ?<sup>1</sup>

**Problem 5**

For a connection  $\nabla$  on a vector bundle  $E \rightarrow M$ , verify the following properties of the Riemann tensor that were stated in lecture:

- (a) The map  $R(X, Y)v = \nabla_X \nabla_Y v - \nabla_Y \nabla_X v - \nabla_{[X, Y]}v$  is  $C^\infty$ -linear with respect to each of  $X, Y \in \mathfrak{X}(M)$  and  $v \in \Gamma(E)$ .
- (b) The components  $R^a_{jkb}$  of  $R$  with respect to a chart for  $M$  and frame for  $E$  over some subset  $\mathcal{U} \subset M$  are related to the Christoffel symbols  $\Gamma^a_{jk}$  by

$$R^a_{jkb} = \partial_j \Gamma^a_{kb} - \partial_k \Gamma^a_{jb} + \Gamma^a_{jc} \Gamma^c_{kb} - \Gamma^a_{kc} \Gamma^c_{jb}.$$

**Problem 6**

Show that if  $\nabla$  is compatible with a bundle metric  $\langle \cdot, \cdot \rangle$  on  $E \rightarrow M$ , then the Riemann tensor satisfies the antisymmetry relation

$$\langle R(X, Y)v, w \rangle + \langle v, R(X, Y)w \rangle = 0.$$

*Hint:* Given  $X, Y \in \mathfrak{X}(M)$  and  $v, w \in \Gamma(E)$ , compute  $(\mathcal{L}_X \mathcal{L}_Y - \mathcal{L}_Y \mathcal{L}_X - \mathcal{L}_{[X, Y]})(\langle v, w \rangle)$ .

**Problem 7**

For a connection  $\nabla$  on the bundle  $\pi : E \rightarrow M$ , prove:

- (a) For any  $v \in \Gamma(E) = \Omega^0(M, E)$  and  $X, Y \in T_p M$  at a point  $p \in M$ ,  $d^2_{\nabla} v := d_{\nabla}(d_{\nabla} v) \in \Omega^2(M, E)$  satisfies  $(d^2_{\nabla} v)(X, Y) = R(X, Y)v$ .
- (b) The connection  $\nabla$  is flat if and only if the covariant exterior derivative operators  $d_{\nabla} : \Omega^k(M, E) \rightarrow \Omega^{k+1}(M, E)$  for all  $k \geq 0$  satisfy  $d_{\nabla} \circ d_{\nabla} = 0$ .

**Problem 8**

Suppose  $\pi : E \rightarrow M$  has structure group  $G \subset \text{GL}(m, \mathbb{F})$  with Lie algebra  $\mathfrak{g} \subset \mathbb{F}^{m \times m}$ ,  $\nabla$  is a  $G$ -compatible connection,  $\Phi_\alpha : E|_{\mathcal{U}_\alpha} \rightarrow \mathcal{U}_\alpha \times \mathbb{F}^m$  is a  $G$ -compatible local trivialization and  $A_\alpha \in \Omega^1(\mathcal{U}_\alpha, \mathfrak{g})$  is the corresponding connection 1-form, satisfying the formula  $(\nabla_X v)_\alpha = \mathcal{L}_X v_\alpha + A_\alpha(X)v_\alpha$  for  $X \in \mathfrak{X}(\mathcal{U}_\alpha)$  and  $v \in \Gamma(E|_{\mathcal{U}_\alpha})$ . We define the *local curvature 2-form*  $F_\alpha \in \Omega^2(\mathcal{U}_\alpha, \mathbb{F}^{m \times m})$  in terms of the curvature 2-form  $\Omega_K \in \Omega^2(M, \text{End}(E))$  by  $(\Omega_K(X, Y)v)_\alpha = F_\alpha(X, Y)v_\alpha$ .

- (a) Prove the formula  $F_\alpha(X, Y) = dA_\alpha(X, Y) + [A_\alpha(X), A_\alpha(Y)]$ , where the bracket on the right hand side denotes the matrix commutator  $[\mathbf{A}, \mathbf{B}] := \mathbf{AB} - \mathbf{BA}$ .  
*Hint:* Use the Riemann tensor as a stand-in for  $\Omega_K$ .
- (b) If  $\Phi_\beta : E|_{\mathcal{U}_\beta} \rightarrow \mathcal{U}_\beta \times \mathbb{F}^m$  is a second trivialization related to  $\Phi_\alpha$  by the transition map  $g = g_{\beta\alpha} : \mathcal{U}_\alpha \cap \mathcal{U}_\beta \rightarrow G$ , show that  $F_\beta(X, Y) = gF_\alpha(X, Y)g^{-1}$ .
- (c) Show that if  $G$  is abelian, then  $F_\alpha = dA_\alpha$  and it is independent of the choice of trivialization, thus defining a global 2-form  $F \in \Omega^2(M, \mathfrak{g})$ . (It is sometimes also called the *curvature 2-form* of  $\nabla$ .)

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<sup>1</sup>For the purposes of Problem 4, you are safe in pretending that  $[0, 1] \times [0, 1]$  is a smooth manifold, rather than something exotic like a “manifold with boundary and corners”. If this worries you, assume that the family of paths  $\gamma_s : [0, 1] \rightarrow M$  is defined for  $s \in \mathbb{R}$  instead of just  $s \in [0, 1]$ ; this does not change the situation in any significant way.