

Vectorfields and Euler number

As further application of the concept of degree - which we heard last week - we will study vector fields on other manifolds.

Def A **vector field** on a manifold X in \mathbb{R}^N is a smooth assignment of a tangent vector to each point in X which is a smooth map $\vec{v}: X \rightarrow \mathbb{R}^N$ s.t. $\vec{v}(x) \in T_x X$

all interesting behavior occurs at "zeros", the points $x \in X$ where $v(x) = 0$

Since for $v(x) \neq 0$ v is nearly constant in magnitude and direction

near x . Like:



However when $v(x) = 0$ the direction of v

may change radically in any small neighborhood ~~around~~ of x

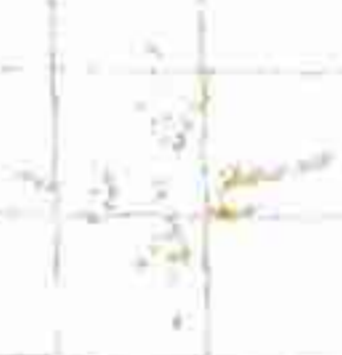
The field may circulate around x / have a source / sink / saddle

may spiral in toward x or away or even more complicated

Pics



circulation



sink



source



saddle



spiral

To investigate the relation between v and (topology of) X

we will look at the directional change around its zeros

~~Therefore we look at the fct. $\vec{v}(x) = \frac{v(x)}{\|v(x)\|}$ where v~~

Therefore we consider first an open set $U \subset \mathbb{R}^m$ and smooth vector field $v: U \rightarrow \mathbb{R}^m$ with isolated zero at point $z \in U$

The function $\vec{v}(x) = \frac{v(x)}{\|v(x)\|}$ maps a small sphere centered at z into the unit sphere.

Def The degree of $\vec{v}(x)$ is called **index i** of v at zero z .

In two-dim case i simply counts the ~~times~~ # of times v rotates completely while we walk counterclockwise

counterclockwise = +1

clockwise = -1

Examples

In the plane of complex numbers the polynomial z^k defines a smooth vector field with zero of index k at the origin and $z^k \Rightarrow i = -k$

We have to show that this concept of index is invariant under diffeomorphism of U .

To explain what this means we'll look at a more general situation of a map $f: M \rightarrow N$ with a vector field on each manifold.

Definition

The vector fields v (on M) and v' (on N) correspond under f if df_x carries $v(x)$ into $v'(f(x))$ $\forall x \in M$.

If f is a diffeomorphism, v' is uniquely defined by v .

$$\underline{v' = df \circ v \circ f^{-1}}$$

Lemma 1

Suppose the vector field v on U corresponds to v' on U' under a diffeomorphism $f: U \rightarrow U'$ ($v' = df \circ v \circ f^{-1}$)

THEN the index of v at an isolated zero z is equal to the index of v' at $f(z)$.

Following Lemma 1, the concept for index for a vector field w on an arbitrary manifold M is as:

if $g: U \rightarrow M$ is parametr. of a neighborhood of z in M

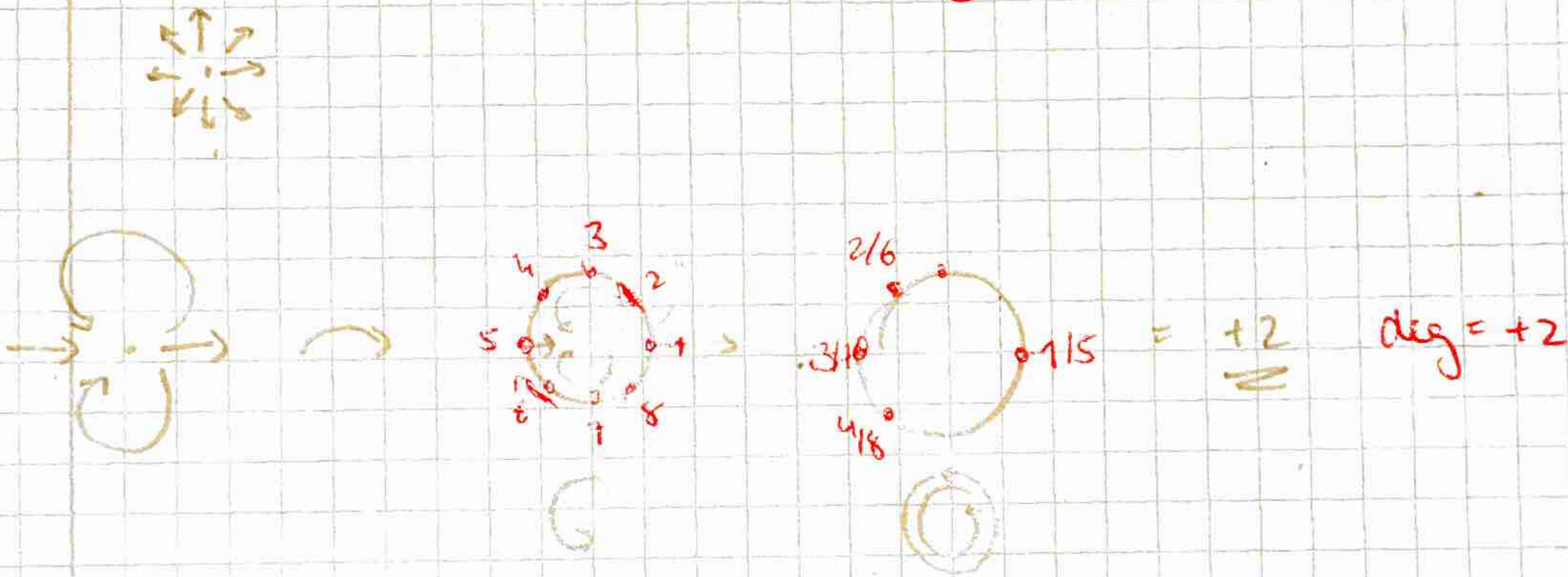
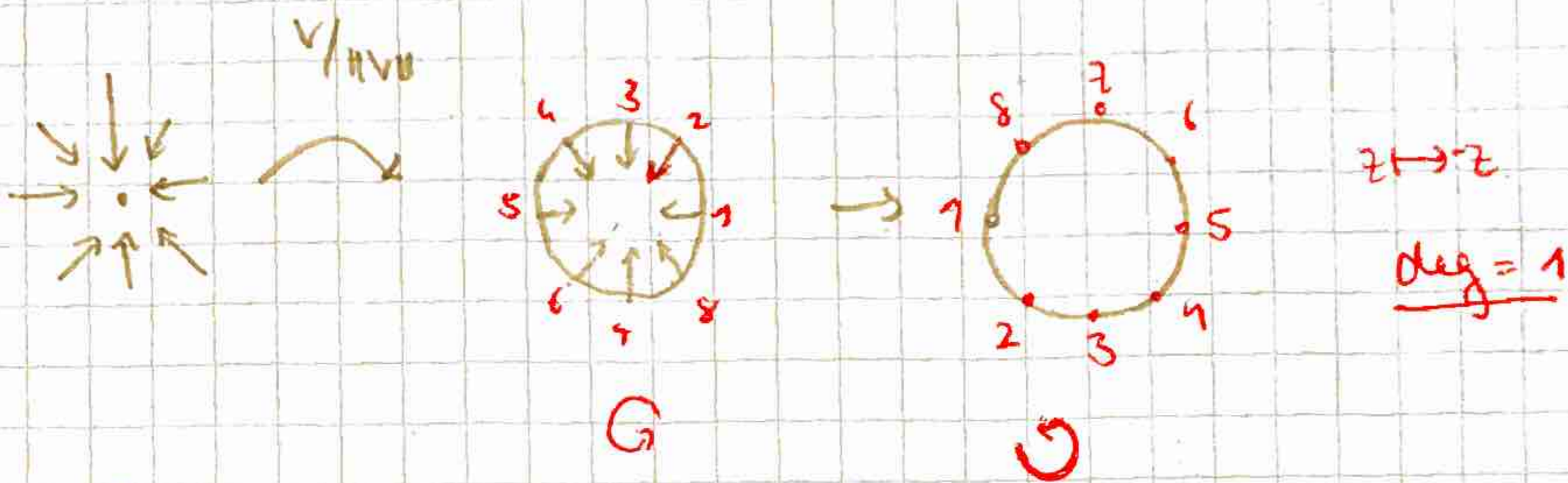
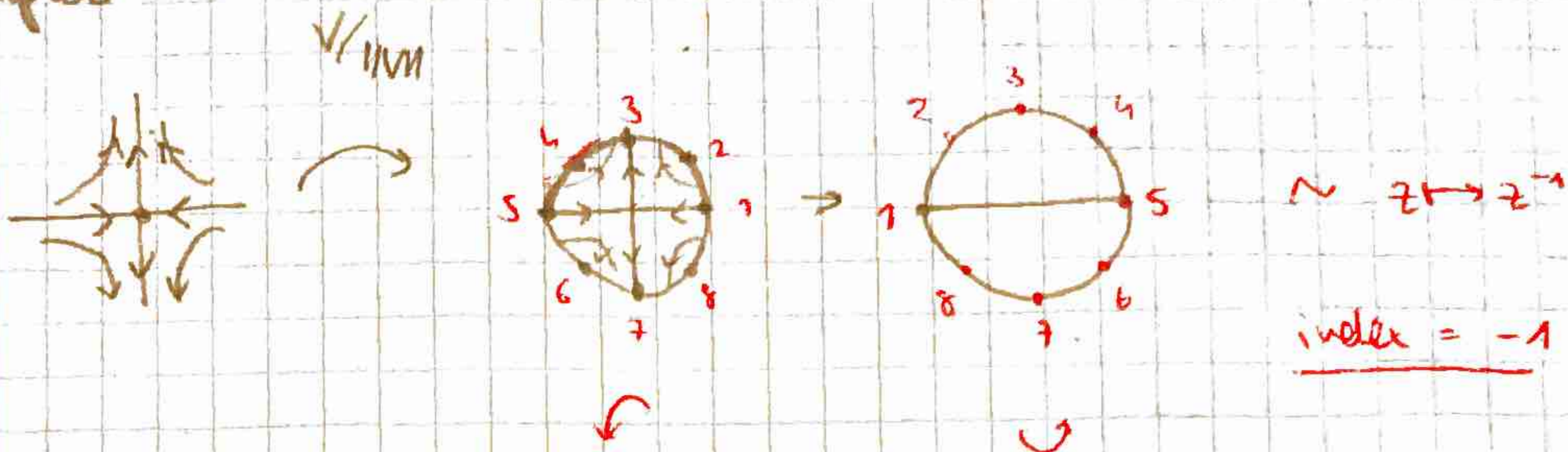
then i of w at z is equal to i of $dg^{-1} \circ w \circ g$ on U at $\text{zer } g^{-1}(z)$

$\Rightarrow i$ well defined

Lemma 2

Any orientation preserving diffeo f of \mathbb{R}^m is smoothly isotopic to the identity.

Examples



Main Theorem of the talk

Poincaré-Hopf Theorem

M be compact manifold with

then: $\forall v \in \mathcal{V}(M) \exists \chi(M) \in \mathbb{Z} \forall v$ with isolated zeros:

$$\sum i = \chi(M)$$

$i =$ index of zero of v

$\chi(M) =$ Euler number

Particularly the index sum is a topological invariant of M

it does not depend on the particular choice of vector field.

For the people who have seen it before or are interested

$$\chi(M) = \sum_{k=0}^n (-1)^k \cdot \text{rank } H_k(M) \quad (\text{ith homology group})$$

$$\Rightarrow \chi(\Delta) = \# \text{ corners (vertices)} - \# \text{ edges} + \# \text{ faces}$$

$$\chi(\Delta^2) = \begin{array}{c} \text{[Diagram of a tetrahedron with red arrows pointing outwards from each face]} \\ 3 - 3 + 1 = 1 \checkmark \\ 6 - 6 + 1 = 1 \checkmark \end{array}$$

$\chi(M)$ same under subdivision

$$\chi(S^1) = \Delta = 3 - 3 + 0 \Rightarrow \chi(S^2) = \begin{array}{c} \text{[Diagram of a tetrahedron with red arrows pointing outwards from each face]} \\ 4 - 6 + 4 = 2 \end{array}$$

χ is the alternating sum $\sum (-1)^k \cdot h_k$ where h_k denotes the number of k -simplices in the complex.

As we've seen $\chi(S^2) = 2$ so there has to be at least one zero with index 2 (Satz von Poincaré / hairy ball theorem)
(there can also be more zeros but the \sum of indices has to be 2)
for example



In the case of the torus the $\chi(T^2) = 0$ " it is possible to comb a hairy donut flat / the torus doesn't have to have a zero



or $\chi(S^1) = 0$



Remark: Let M be a compact manifold and w a smooth vector field on M with isolated zeros.

If M has a boundary then w is required to point outward at all boundary points.

Def. Let $X \subset \mathbb{R}^m$ be a compact m -manifold with boundary. The Gauss mapping $g: \partial X \rightarrow S^{m-1}$ assigns to each $x \in \partial X$ the outward unit normal vector at x .

Lemma 3 (Hopf)

If $v: X \rightarrow \mathbb{R}^m$ is a smooth vector field with isolated zeros, v points out of X along the boundary

THEN: $\sum_i = \deg(g)$

\sum_i doesn't depend on v

Example If a vector field on the disk D^2 points outward along the boundary

then $\sum_i = +1$



Proof

removing an ϵ -ball around each zero \Rightarrow we get new manifold with boundary

$\bar{v}(x) = \frac{v(x)}{\|v(x)\|}$ maps the manifold into S^{m-1}

\sum degrees of \bar{v} restricted to the various boundary components = 0

But $\bar{v}|_{\partial X}$ is homotopic to g and the degrees of the other boundary comp = $-\sum_i$ (each small sphere gets wrong orientation)

Therefore

$$\deg(g) - \sum_i = 0 \Leftrightarrow \deg(g) = \sum_i \quad \square$$



Remark

$\deg(g)$ known as "curvature integral" of ∂X

$\int \frac{v(x)}{\|v(x)\|^m}$

(+)

Definition

The vector field is nonsingular at zero \neq if the linear transformation $d_x v$ is nonsingular

Lemma 4

Index of v at a nonsingular zero is either $+1$ or -1 according to the determinant of $d_x v$ pos or neg.

Lemma 5 ~~the derivative $d_x v$~~

(+)

consider vector field v on open set $U \subset \mathbb{R}^m$ and think of v as mapping $U \rightarrow \mathbb{R}^m$
so that $d_x v: \mathbb{R}^m \rightarrow \mathbb{R}^m$ is defined

↑ more generally consider a zero z of vect. f. w on a manifold $M \subset \mathbb{R}^n$. Think of w as a map from $M \rightarrow \mathbb{R}^m$ s.o. that $d_z w: T_z M \rightarrow \mathbb{R}^m$ is defined.

Lemma 5 $d_z w$ carries $T_z M$ into subspace $T_z M \subset \mathbb{R}^m$ and therefore can be considered as lin. transformation from $T_z M$ to itself.

If this lin. transf. has determinant $D \neq 0$ then z is an isolated zero of w with index $+1$ or -1 according as D is positive or negative.

~~Theorem 1~~

↑ Now consider a compact, boundaryless manifold $M \subset \mathbb{R}^n$.

Let N_ϵ denote the closed ϵ -neigh. of M (ϵ suff. small $\rightarrow N_\epsilon$ smooth manifold with boundary).

Theorem 1

For any vector field v on M with only nondegen. zeros the $\sum i$ is equal to the deg. (Gauss mapping) $g: \partial N_\epsilon \rightarrow S^{n-1}$

Proof.

For $x \in N_\epsilon$ let $r(x) \in M$ the closest point on M .



Note $x - r(x)$ perpendicular to the tang. space of M at $r(x)$.

(ϵ suff. small $\rightarrow r(x)$ smooth and well defined)

We consider the squared dist. fct. $\varphi(x) = \|x - r(x)\|^2$

with $\text{grad } \varphi = 2\|x - r(x)\|$

Then for each $x \in \partial N_\epsilon = \varphi^{-1}(\epsilon^2)$ the outward unit vector is given

$$\text{by } g(x) = \frac{\text{grad } \varphi}{\|\text{grad } \varphi\|} = \frac{2(x - r(x))}{2\epsilon} = \frac{x - r(x)}{\epsilon}$$

were extending the vector field v to a vef w

$$\text{by } w(x) = (x - r(x)) + v(r(x))$$

Then w points outward along the boundary (since $w(x) \cdot g(x) > \epsilon$)

Computing derivative of w at a zero $z \in M$

we get: $d_z w(u) = d_z v(u)$ for $u \in T_z M$

$d_z w(u) = u$ for $u \in T_z M^\perp$

\Rightarrow Det. of $w =$ Det of v \cdot i of w at zero $z = i$ of v at z

$\xrightarrow{\text{Lemma 3}}$
 $\rightarrow \sum i = \deg(g) \quad \square$

3 steps Poincaré Hopf system

Step 1 Identification of the invariant Σ_i with $\chi(M)$

Step 2 Proving theorem for vector field w deg-zeros

Step 3 Manifolds with boundary.

Step 1

Sufficient to construct an example of a nondeg. vector field on M with $\Sigma_i = \chi(M)$

pleasant way:

acc. to Moscar Morse: always possible to find a real-valued f on M whose "gradient" is a nondeg. vector field

\Rightarrow Morse furthermore

showed that the sum of indices associated with such a gradient field = $\chi(M)$

Step 2

Consider first vec. f. v on open set U with isolated zero z .

If $\lambda: U \rightarrow [0, 1]$

$\lambda(N_1) = 1$

$\lambda(\text{outside a slightly larger neighborhood}) = 0$

N_1 neighborhood of z

If y is suff. small regular value of v

then $v'(x) = v(x) - \lambda(x)y$ is nondegenerate within N

(if y suff. small $\Rightarrow v'$ will have no zeros at all within $N - N_1$)

The sum of the indices at the zeros within N can be evaluated as the degree of the map $\bar{v}: \partial N \rightarrow S^{m-1}$ and hence does not change during this attraction.

More generally consider vect. fields on a compact manifold M

Applying this argument locally we see that any vector field with isolated zeros can be replaced by a nondeg. vect. field without altering the integer \sum_i

Step 3

If $M \subset \mathbb{D}^n$ has boundary: then any v.f. v which points outward along ∂M can be extended over the neighborhood N_ϵ so as to point outward along ∂N_ϵ

Problem N_ϵ is not smooth manifold / only C^1 manifold

The extension w from earlier will only be contin. v.f. near ∂M

The argument can be carried out

- by showing that our strong differentiability assumption isn't necessary
- by other methods.

Proof Lemma 2

Assume $f(0) = 0$ $df(x) = \lim_{t \rightarrow 0} \frac{f(tx)}{t}$

We will construct a smooth isotopy $F: \mathbb{R}^m \times [0, 1] \rightarrow \mathbb{R}^m$

$$F(x, t) = f(tx)/t$$

$$F(x, 0) = df(x) \quad F(x, 1) = f(x)$$

to show F smooth even for $t \rightarrow 0$

we write f as

$$f(x) = x_1 g_1(x) + \dots + x_m g_m(x)$$

where g_1, \dots, g_m suitable
smooth functions

$$F(x, t) = \frac{f(tx)}{t} = \frac{x_1 g_1(tx)}{t} + \dots + \frac{x_m g_m(tx)}{t}$$

Since g_k smooth $\Rightarrow \lim_{t \rightarrow 0} \frac{g_k(tx)}{t} = g'_k(x)$ smooth for $\forall k$

$$\Rightarrow F(x, 0) = df(x) = x_1 g'_1(x) + \dots + x_m g'_m(x)$$

Since g_k smooth

$\rightarrow g'_k$ smooth

$\Rightarrow F(x, 0)$ smooth

$\Rightarrow f$ isotopic to df which is clearly isotopic to identity

Proof Lemma 1

We assume $z = f(z) = 0$ and U convex.

1) case:

f preserves orientation

like lemma 2

$$f_t: U \rightarrow \mathbb{R}^n$$

f_0 : identity

f_1 : f

and $f_t(0) = 0 \quad \forall t$

$$\text{let } v_t = df_t \circ v \circ f_t^{-1}$$

$\uparrow \quad \uparrow \quad \uparrow$

all defin. and non zero on a diff small sphere around 0

He yields $v = v_0$ must be the same to the vector $v' = v_1$

$$(v_1 = df_1 \circ v \circ f_1^{-1} = df \circ v \circ f^{-1} = v_0) \text{ at zero}$$

2) f doesn't preserve orientation

Suff. to show for special case of a reflection P

Then $v' = P \cdot v \cdot e^{-1}$